

# Finer analysis of characteristic curves and its application to shock profile, exact and optimal controllability of a scalar conservation law with strict convex flux

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## Abstract

Here we consider scalar conservation law in one space dimension with strictly convex flux. Goal of this paper is to study two problems. First problem is to know the profile of the entropy solution. In spite of the fact that, this was studied extensively in last several decades, the complete profile of the entropy solution is not well understood. Second problem is the exact controllability. This was studied for Burgers equation and some partial results are obtained for large time. It was a challenging problem to know the controllability for all time and also for general convex flux. In a seminal paper [8], Dafermos introduces the characteristic curves and obtain some qualitative properties of a solution of a convex conservation law. In this paper, we further study the finer properties of these characteristic curves. As a bi-product we solve these two problems in complete generality. In view of the explicit formulas of Lax - Oleinik [10], Joseph - Gowda [16], target functions must satisfy some necessary conditions. In this paper we prove that it is also sufficient. Method of the proof depends highly on the characteristic methods and explicit formula given

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by Lax - Oleinik and the proof is constructive. This method allows to solve the optimal controllability problem in a trackable way.

Key words: Hamilton-Jacobi Equation, Scalar Conservation Laws, Control and Optimal Control, Explicit Formula.

## 1 Introduction:

In this paper we consider the following scalar conservation law in one space dimension. Let  $f : \mathbb{R} \rightarrow \mathbb{R}$  be a strictly convex  $C^2$  (Regularity condition on  $f$  can be relaxed, see remark 3.21) function satisfying the super linear growth,

$$\lim_{|u| \rightarrow \infty} \frac{f(u)}{|u|} = \infty. \quad (1.1)$$

Let  $T > 0$ ,  $I = (A, B)$ ,  $\Omega = I \times (0, T)$ ,  $u_0 \in L^\infty(I)$ ,  $b_0, b_1 \in L^\infty((0, T))$  and consider the problem

$$u_t + f(u)_x = 0 \quad (x, t) \in \Omega, \quad (1.2)$$

$$u(x, 0) = u_0(x) \quad x \in I, \quad (1.3)$$

$$u(A, t) = b_0(t) \quad t \in (0, T), \quad (1.4)$$

$$u(B, t) = b_1(t) \quad t \in (0, T). \quad (1.5)$$

This problem was well studied from last several decades starting from the pioneering works of Lax-Oleinik [10], Kruzkov [14], Bardaux-Leraux-Nedeleck [5]. They have studied the existence and uniqueness of weak solutions to (1.2)-(1.5) satisfying the entropy condition. In spite of being well studied, still there are problems which are open. Notably among them are

1. Profile of a solution, for example how many shocks can a solution exhibit and the nature of the shocks.
2. Exact controllability of initial and initial-boundary value problem.
3. Optimal controllability for initial and initial-boundary value problem.

In this paper we study these problems for the entropy solution of (1.2) and we say a solution means a weak solution satisfying the entropy condition. The basic ingredient in studying all these problems comes from the analysis of characteristic curves  $R_\pm$ . Originally this was introduced by Hopf [12] and later by Dafermos [8], who studied them quite extensively to obtain information on the nature of solutions.

Independently this was used in [2] to obtain the explicit formula for solution of discontinuous flux.

The plan of the paper is as follows:

In section (2) we study the finer properties of the characteristics for the initial value problem, namely

- (i). Comparison properties with respect to the initial data.
- (ii). Failure of the continuity with respect to the initial data.
- (iii). Behavior of the characteristics when one side of the initial data is large.

Main tool to study all these properties is the Lax-Oleinik formula [10] and we recall them without proof. Then proceed to obtain all the required properties. Next we use this information to study (1),(2) and (3).

**1. Profile of a solution:** In section (3) we study the profile of a solution. In order to understand the shock profile of a solution, we consider the following two basic examples which form the general pattern. Consider the Burgers equation,

$$u_t + \left(\frac{u^2}{2}\right)_x = 0, \quad (x, t) \in \mathbb{R} \times \mathbb{R}_+.$$

Let  $A_1 < A_2$ ,  $u_-, u_+ \in \mathbb{R}$ ,  $\bar{u}_0 \in L^\infty((A_1, A_2))$  and define the initial data  $u_0$  by

$$u_0(x) = \begin{cases} u_- & \text{if } x < A_1, \\ \bar{u}_0(x) & \text{if } A_1 < x < A_2, \\ u_+ & \text{if } x > A_2. \end{cases} \quad (1.6)$$

**Example 1.1 (Single shock case):** (See Figure 1) Let  $u_- > \alpha > u_+$  and  $\bar{u}_0(x) = \alpha$ . Define

$$\begin{aligned} \sigma_0 &= \frac{f(u_-) - f(u_+)}{u_- - u_+}, \quad \sigma_1 = \frac{f(u_-) - f(\alpha)}{u_- - \alpha}, \quad \sigma_2 = \frac{f(u_+) - f(\alpha)}{u_+ - \alpha}, \quad T_0 = \frac{A_2 - A_1}{\sigma_1 - \sigma_2}, \\ x_0 &= A_1 + \sigma_1 T_0, \quad s_1(t) = A_1 + \sigma_1 t, \quad s_2(t) = A_2 + \sigma_2 t, \quad s_0(t) = x_0 + (t - T_0)\sigma_0. \end{aligned}$$

Then the solution  $u$  is given by,

- (i). Let  $0 < t < T_0$ , then

$$u(x, t) = \begin{cases} u_- & \text{if } x < s_1(t), \\ \alpha & \text{if } s_1(t) < x < s_2(t), \\ u_+ & \text{if } x > s_2(t). \end{cases} \quad (1.7)$$

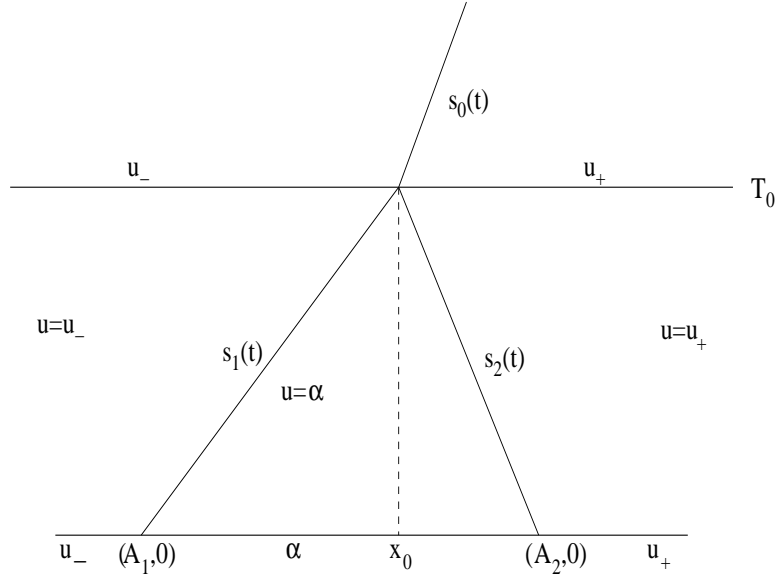


Figure 1:

(ii). Let  $t > T_0$ , then

$$u(x, t) = \begin{cases} u_- & \text{if } x < s_0(t), \\ u_+ & \text{if } x > s_0(t). \end{cases} \quad (1.8)$$

**Example 1.2.(Infinitely many Shocks):** (See Figure 2 and Figure 3) Let  $I = (A_1, A_2)$  and define the ASSP (asymptotically single shock packet; see definition 3.9)  $D(I)$  and single shock solution  $u(x, t, I)$  as follows:

$$D(I) = I \times (0, \infty). \quad (1.9)$$

$$T(I) = \frac{A_2 - A_1}{2}. \quad (1.10)$$

$$\bar{u}_0(x, I) = \begin{cases} 1 & \text{if } A_1 < x < \frac{A_1 + A_2}{2}, \\ -1 & \text{if } \frac{A_1 + A_2}{2} < x < A_2. \end{cases} \quad (1.11)$$

Let  $u(x, t, I)$  be a solution of (1.2) in  $D(I)$  with initial condition  $\bar{u}_0(x, I)$  and satisfying the boundary condition

$$u(A_1+, t, I) = u(A_2-, t, I) = 0, \quad (1.12)$$

and it is given by (see Figure 2).

(i). Let  $0 < t < T(I)$ , then

$$u(x, t, I) = \begin{cases} \frac{x - A_1}{t} & \text{if } A_1 < x < A_1 + t, \\ 1 & \text{if } A_1 + t < x < \frac{A_1 + A_2}{2}, \\ -1 & \text{if } \frac{A_1 + A_2}{2} < x < A_2 - t, \\ \frac{x - A_2}{t} & \text{if } A_2 - t < x < A_2. \end{cases} \quad (1.13)$$

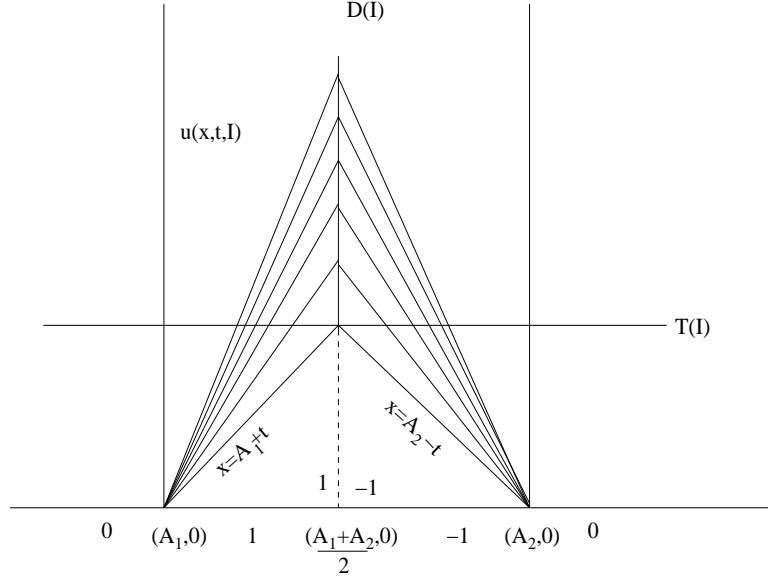


Figure 2:

(ii). Let  $t > T(I)$ , then

$$u(x, t, I) = \begin{cases} \frac{x-A_1}{t} & \text{if } A_1 < x < \frac{A_1+A_2}{2}, \\ \frac{x-A_2}{t} & \text{if } \frac{A_1+A_2}{2} < x < A_2. \end{cases} \quad (1.14)$$

Next we glue such solutions to produce a single solution having infinitely many shocks for each  $t > 0$ . Let  $n \geq 1$  and define

$$I_+ = (1, \infty), \quad I_- = (-\infty, 0), \quad I_n = \left(\frac{1}{2n}, \frac{1}{2n-1}\right), \quad J_n = \left(\frac{1}{2n+1}, \frac{1}{2n}\right), \quad n \geq 1.$$

$$D_n = I_n \times (0, \infty), \quad x_n = \frac{1}{2} \left(\frac{1}{2n} + \frac{1}{2n-1}\right).$$

$$u_0(x) = \begin{cases} 1 & \text{if } x \in (1, \infty) \cup_{n=1}^{\infty} \left(\frac{1}{2n}, x_n\right), \\ 0 & \text{if } x \in J_n \cup I_-, \\ -1 & \text{if } x \in \cup_{n=1}^{\infty} \left(x_n, \frac{1}{2n-1}\right), \end{cases} \quad (1.15)$$

and define the solution by (see Figure 3)

$$u(x, t) = \begin{cases} 1 & \text{if } 1+t < x, \\ \frac{x-1}{t} & \text{if } 1 < x < 1+t, \\ u(x, t, I_n) & \text{if } (x, t) \in D_n, \\ 0 & \text{otherwise.} \end{cases} \quad (1.16)$$

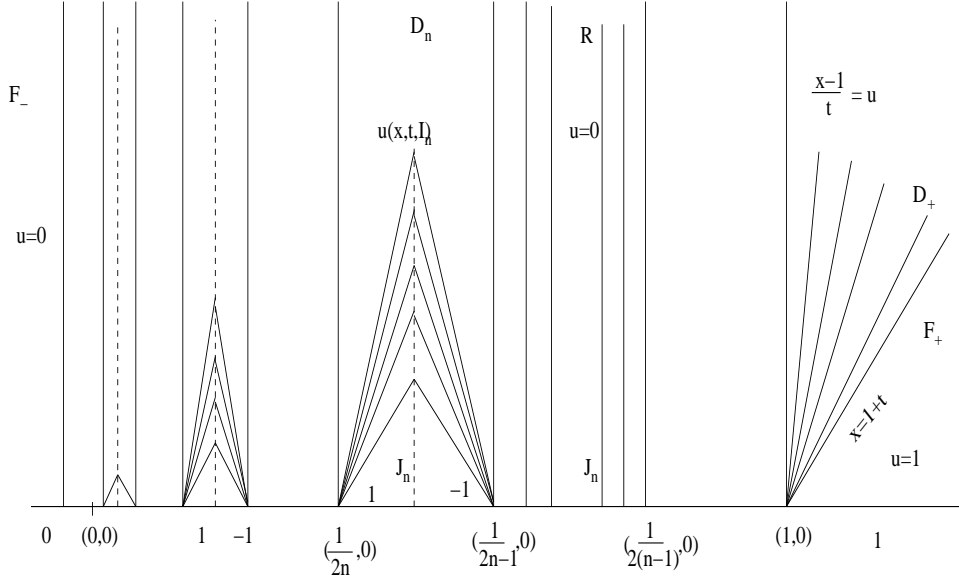


Figure 3:

In view of (1.12),  $u$  satisfies Rankine-Hugoniot condition across  $\partial D_n$  and hence  $u$  is a solution of (1.2) with  $u_0$  as its initial condition.

Now the basic question is, under what conditions,  $u$  admits a single shock (as in example (1.1)) for  $t$  sufficiently large and what happens if it does not admits a single shock (as in example 1.2) for  $t$  large.

**Analysis of shocks:** By looking at the example (1.1), the data satisfies

$$u_- > u_+. \quad (1.17)$$

It was proved by Liu [19] that for  $\bar{u}_0$  arbitrary and  $u$  is a piecewise continuous function, then  $u$  admits a single shock for  $t$  large provided (1.17) holds. Recently Shearer-Dafermos [9] have relaxed the condition of piecewise continuity of  $u$  but assuming (1.17) and for  $x \in (A_1, A_2)$ ,

$$u_- \geq \bar{u}_0(x) \geq u_+, \quad (1.18)$$

they proved that for  $t$  sufficiently large,  $u$  admits a single shock.

Then the question is **the condition (1.18) is necessary ?**

In section (3) of this paper (Theorem 3.12) we show that infact (1.17) is both necessary and sufficient conditions for  $u$  to admit a single shock for  $t$  sufficiently large.

Next we consider the case

$$u_- \leq u_+,$$

and want to know how the solution behaves. In this case we can show that (Theorem 3.12) any solutions behaves like as in example (1.2). That is there exists a countable

number of disjoint regions  $\{D_j\}, F_{\pm}, D_{\pm}$  (see Figure 3) such that

(i).  $\Omega = \mathbb{R} \times \mathbb{R}_+ = F_+ \cup F_- \cup D_- \cup D_+ \cup_{i \in I} D_i \cup R$ .

(ii).  $F_{\pm}$  are closed and  $u(x, t) = u_{\pm}$  in the interior of  $F_{\pm}$ . In example (1.2)

$$F_+ = \{(x, t) : x \leq 0\}, \quad F_- = \{(x, t) : x \geq 1 + t\}.$$

(iii).  $u$  behaves like rarefaction in  $D_- \cup D_+$ , and in example (1.2),  $D_- = \phi$ ,  $D_+ = \{(x, t) : 1 < x < 1 + t\}$ .

(iv).  $R$  is a closed set consists of characteristic lines and  $u$  is continuous in  $R$ . In example (1.2)  $R$  is given by

$$\begin{aligned} R &= \cup_{n=1}^{\infty} \{(x, t) : x \in \bar{J}_n\}, \\ u(x, t) &= 0 \quad \text{for } (x, t) \in R. \end{aligned}$$

(v).  $\partial D_i$  are parallel characteristic lines and any two characteristics curves within  $D_i$  intersects after finite time. Asyptotically it represents a single shock packet. In example (1.2),  $D_i = I_i \times (0, \infty)$ .

(vi). There exists a continuous non-decreasing  $N$  curve in  $\Omega \setminus F_- \cup F_+$  such that (see Figure 4)

$$\int_{-\infty}^{\infty} |u(x, t) - N(x, t)| = O\left(\frac{1}{t^{1/2}}\right)$$

provided  $f'' \geq \beta > 0$ . In example (1.2),  $N$  is given by

$$N(x, t) = \begin{cases} 0 & \text{if } x \leq 1, \\ \frac{x-1}{t} & \text{if } 1 \leq x \leq 1+t, \\ 1 & \text{if } x > 1+t. \end{cases}$$

Main result of this section is Theorem 3.12, where (i) to (iv) has been obtained for a

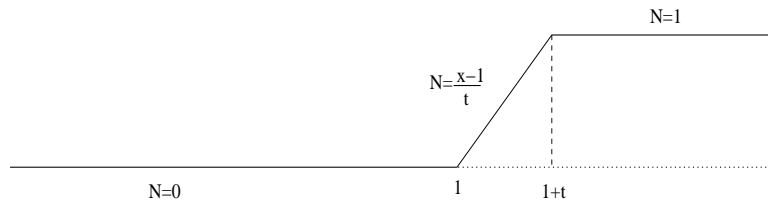


Figure 4:  $N$  Wave

general convex flux  $f$ . In case of (vi), we have relaxed the condition  $f'' \geq \beta > 0$ . We allow  $f''$  can have zeros finite order and then obtained the decay estimates. Earlier this problem was studied by Liu-Pierre [20] (for the power law). Kim [17] (for the

algebraic growth rate at zero) was relaxed the condition  $f'' \geq \beta > 0$  and obtained the decay estimates. Here we have generalized these results and obtain the rate of decay of solutions with respect to the  $N$ -wave (see Remark 3.21).

It has been shown by Schaeffer [21] that for large class of smooth initial data  $u_0$ , the solution can develop atmost finitely many shocks for  $t$  large. If we remove the smoothness in the initial data, example (1.2) shows the existence of infinitely many shock pockets  $D_i$  and asymptotically, each one represents a single shock. In fact within  $D_i$ , one can have infinitely many shocks and all of them merge at infinity (see example 3.17). On the other hand if the data is smooth, Schaeffer [21] showed that for a large class of smooth initial data for which the solution can exhibit a finite number of shocks. In example (see example 3.14), we construct a  $u_0 \in C_c^\infty(\mathbb{R})$  for which the solution admits infinitely many shocks and hence Schaeffer's result cannot be improved.

Main results of this section are Theorems 3.12, (where we prove the above decomposition and obtain optimal decay estimates for  $N$  curves) 3.13, 3.16 and example (3.17).

**2. Exact Controllability:** Normally for the non linear evolution equations, technique of linearization is adopted to study controllability problems. Unfortunately this method does not work (see Horsin [15]) and very few results are available on this subject. Here we consider the following three problems of controllability. Let  $u_0 \in L^\infty(\mathbb{R})$ ,

- (I) **Controllability for pure initial value problem:** Assume that  $I = \mathbb{R}, \Omega = \mathbb{R} \times (0, T)$ . Let  $J_1 = (C_1, C_2), J_2 = (B_1, B_2)$ ,  $g \in L^\infty(J_1)$ , a target be given. The question is, does there exists a  $\bar{u}_0 \in L^\infty(J_2)$  and  $u$  in  $L^\infty(\Omega)$  such that  $u$  is a solution of (1.2) satisfying

$$u(x, T) = g(x) \quad x \in J_1, \quad (1.19)$$

$$u(x, 0) = \begin{cases} u_0(x) & \text{if } x \notin J_2, \\ \bar{u}_0(x) & \text{if } x \in J_2. \end{cases} \quad (1.20)$$

- (II) **Controllability for one sided initial boundary value problem:** Assume that  $I = (0, \infty), \Omega = \mathbb{R} \times (0, T), J = (0, C)$  and a target function  $g \in L^\infty(J)$  be given. The question is, does there exists a  $u \in L^\infty(\Omega)$  and a  $b \in L^\infty((0, T))$  such that  $u$  is a solution of (1.2) satisfying

$$u(x, T) = g(x) \quad \text{if } x \in J, \quad (1.21)$$

$$u(x, 0) = u_0(x) \quad \text{if } x \in (0, \infty), \quad (1.22)$$

$$u(0, t) = b(t) \quad \text{if } t \in (0, T). \quad (1.23)$$

- (III) **Controllability from two sided initial boundary value problem:**



(a). Let  $\Omega = \mathbb{R} \times (0, T)$ ,  $I_1 = (B_1, B_2)$ ,  $B_1 \leq C \leq B_2$ . Given the target functions  $g_1 \in L^\infty(B_1, C)$ ,  $g_2 \in L^\infty(C, B_2)$ , does there exist a  $\bar{u}_0 \in L^\infty(\mathbb{R} \setminus I_1)$  and  $u \in L^\infty(\Omega)$  such that  $u$  is a solution of (1.2) satisfying

$$u(x, 0) = \begin{cases} g_1(x) & \text{if } B_1 < x < C, \\ g_2(x) & \text{if } C < x < B_2. \end{cases} \quad (1.24)$$

and

$$u(x, 0) = \begin{cases} u_0(x) & \text{if } B_1 < x < B_2, \\ \bar{u}_0(x) & \text{if } x < B_1 \text{ or } x > B_2. \end{cases} \quad (1.25)$$

(b). Here we consider controllability in a strip. Let  $I = (B_1, B_2)$ ,  $\Omega = I \times (0, T)$ ,  $B_1 < C < B_2$ . Let  $g_1 \in L^\infty((B_1, C))$ ,  $g_2 \in L^\infty((C, B_2))$  be given. The question is, does there exist  $b_0, b_1 \in L^\infty((0, T))$  and a  $u \in L^\infty(\Omega)$  such that  $u$  is a solution of (1.2) and satisfying

$$u(x, 0) = u_0(x), \quad (1.26)$$

$$u(x, T) = \begin{cases} g_1(x) & \text{if } B_1 < x < C, \\ g_2(x) & \text{if } C < x < B_2. \end{cases} \quad (1.27)$$

$$u(B_1, t) = b_0(t), \quad (1.28)$$

$$u(B_2, t) = b_1(t). \quad (1.29)$$

In view of the Lax-Oleinik (Chapter (3) of [10]) explicit formula for solutions of pure initial value problem and by Joseph-Gowda [16] for initial boundary value problem, the targets  $g$  or  $g_1, g_2$  cannot be arbitrary. They must satisfy the compatibility condition, for example in the case of problem (I), there exists a non-decreasing function  $\rho$  in  $(B_1, B_2)$  such that for a.e  $x \in (B_1, B_2)$

$$f'(g(x)) = \frac{x - \rho(x)}{T}. \quad (1.30)$$

In the case of problem (II), there exists a non-decreasing function  $\rho$  in  $(0, C)$  such that

$$f'(g(x)) = \frac{x}{T - \rho(x)}. \quad (1.31)$$

Assuming that the target functions satisfies the compatibility conditions, then the question is **whether the problems (I),(II) and (III) admit a solution?**. In fact, **it is true** and we have the following results. First we describe the class of functions satisfying compatibility conditions.

**Definition (Admissible functions):** Let  $J = (M, N)$  and  $T > 0$ ,

$$S(J) = \{\rho : J \rightarrow \mathbb{R} : \rho \text{ is monotone and left or right continuous function}\}.$$

Then define admissible class of target functions by

(i) Target space for initial value problem (IA):

$$IA(J) = \{g; f'(g(x)) = \frac{x - \rho(x)}{T}, \rho \in S(J), \rho \text{ is a non-decreasing function}\}. \quad (1.32)$$

(ii) Target space for left boundary problem (LA):

$$LA(J) = \{g; f'(g(x)) = \frac{x-M}{T-\rho(x)}, \rho \in S(J), \rho \text{ is a non-increasing right continuous function}\}. \quad (1.33)$$

(iii) Target space for right boundary problem (RA):

$$RA(J) = \{g; f'(g(x)) = \frac{x-N}{T-\rho(x)}, \rho \in S(J), \rho \text{ is a non-decreasing left continuous function}\}. \quad (1.34)$$

**THEOREM 1.1** *Let  $J_1 = (C_1, C_2), J_2 = (B_1, B_2)$ . Let  $g(x) = (f')^{-1}\left(\frac{x-\rho(x)}{T}\right)$  be in  $IA(J_1)$  and  $B_1 < A_1 < A_2 < B_2$ , satisfying*

$$A_1 \leq \rho(x) \leq A_2 \quad \text{if } x \in J_1, \quad (1.35)$$

*then there exists a  $\bar{u}_0 \in L^\infty(J_2), u \in L^\infty(\Omega)$  such that  $(u, \bar{u}_0)$  is a solution to problem (I) (see Figure 5).*

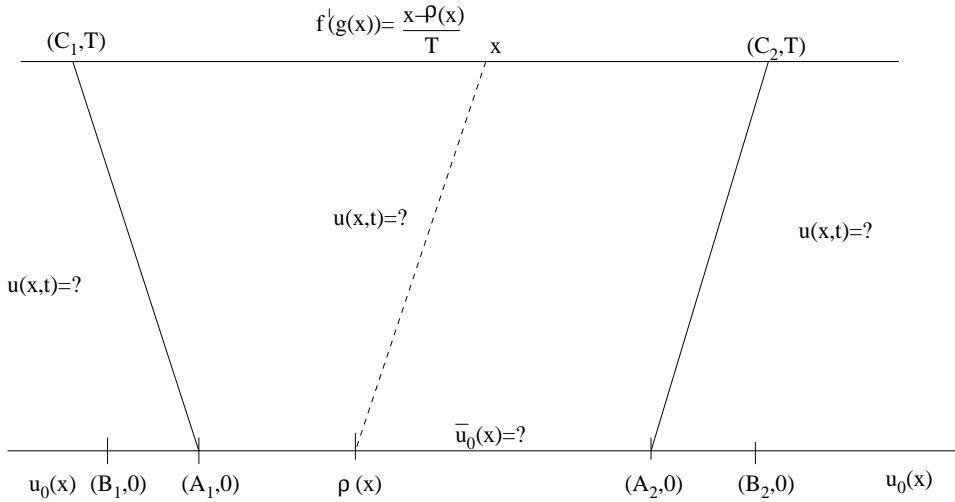


Figure 5:

**THEOREM 1.2** Let  $\wedge > 0, C > 0, \delta > 0, J = (0, C)$ . Let  $g \in LA(J)$  given by  $f'(g(x)) = \frac{x}{T-\rho(x)}$  for  $x \in J$  and satisfying

$$\delta \leq \rho(x) \leq T, \quad (1.36)$$

$$\left| \frac{x}{T-\rho(x)} \right| \leq \wedge. \quad (1.37)$$

Then there exist a  $b \in L^\infty(0, T), u \in L^\infty(\Omega)$  such that  $(u, b)$  is a solution to Problem II (see Figure 6).

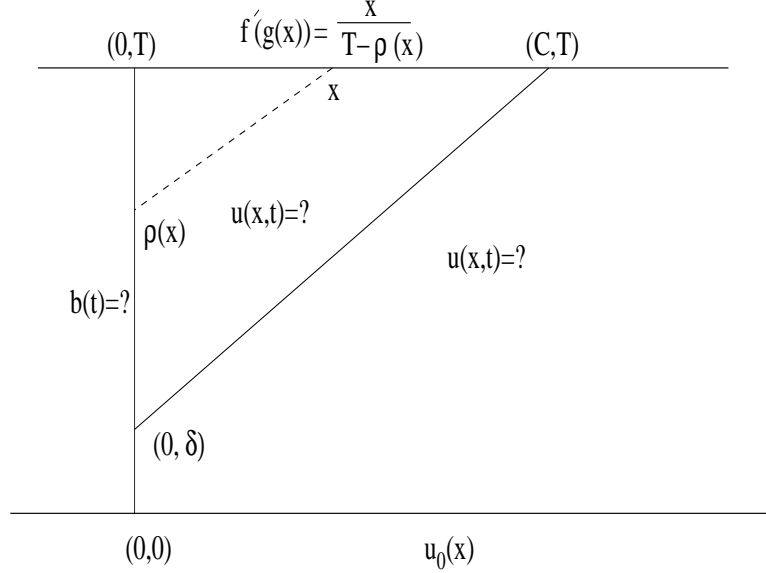


Figure 6:

**THEOREM 1.3** Let  $I_1 = (B_1, B_2), B_1 < C < B_2, J_1 = (B_1, C), J_2 = (C, B_2)$ , then

(a). Let  $A_1 < B_1 < B_2 < A_2$  and  $g_1 \in IA(J_1), g_2 \in IA(J_2)$  given by  $f'(g_1(x)) = \frac{x-\rho_1(x)}{T}, f'(g_2(x)) = \frac{x-\rho_2(x)}{T}$ , satisfying

$$\rho_1(x) \leq A_1 \quad \text{if } x \in J_1, \quad (1.38)$$

$$\rho_2(x) \geq A_2 \quad \text{if } x \in J_2. \quad (1.39)$$

Then there exists  $\bar{u}_0 \in L^\infty(\mathbb{R} \setminus I_1), u \in L^\infty(\Omega)$  such that  $(u, \bar{u}_0)$  is a solution to problem (a) of III (see Figure 7).

(b). Let  $\wedge > 0, 0 < \delta < T, g_1 \in LA(J_1), g_2 \in RA(J_2)$ , given by  $f'(g_1(x)) = \frac{x-B_1}{T-\rho_1(x)}, f'(g_2(x)) = \frac{x-B_2}{T-\rho_2(x)}$  satisfying for  $i = 1, 2, x \in J_i$

$$\delta \leq \rho_i(x) \leq T, \quad (1.40)$$

$$\left| \frac{x-B_i}{T-\rho_i(x)} \right| \leq \wedge. \quad (1.41)$$

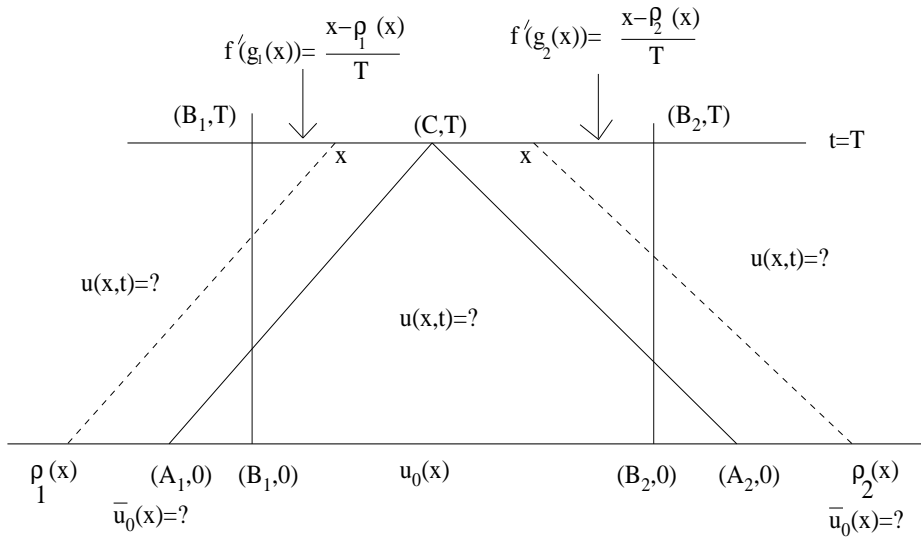


Figure 7:

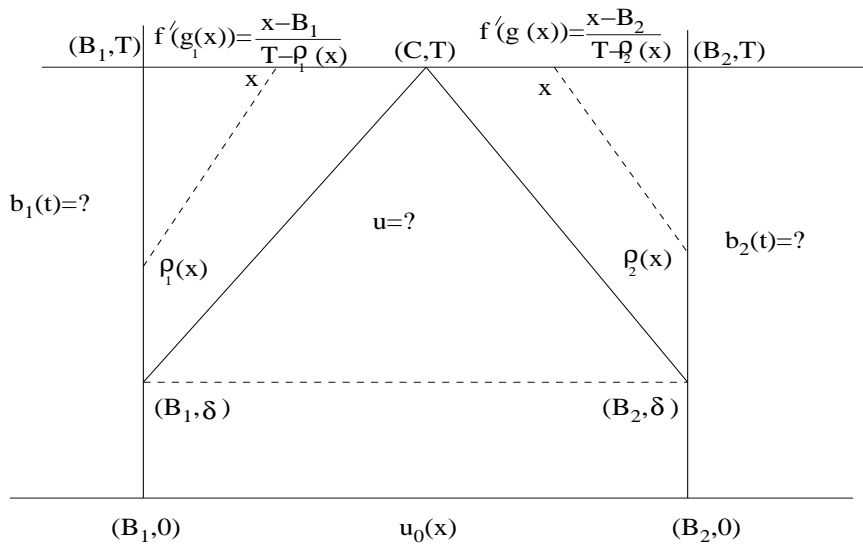


Figure 8:

Then there exists  $b_0, b_1 \in L^\infty((0, T))$  and  $u \in L^\infty(\Omega)$  such that  $(u, b_0, b_1)$  is a solution to problem (b) of III (see Figure 8).

Before going for further results, let us recall some of the earlier works in this direction.

Problem (a) in III was considered by Horsin [15] for the Burger's equation under similar assumptions on  $g_1$  and  $g_2$  as in (a) of Theorem (1.3). He proves that there exists  $T_c > 2$ , such that (a) of problem III has an approximate controllability solution. That is given  $\epsilon > 0$ , there exist  $(u, \bar{u}_0)$  such that

$$\int_{B_1}^{B_2} |u(x, T_c) - g(x)| dx = O(\epsilon),$$

and  $u(x, T_c) = g(x) = \chi_{(B_1, C)} g_1(x) + \chi_{(C, B_2)} g_2(x)$ , outside an interval of length  $\epsilon$ .

In the viscous case the same problem was considered by Glass-Guerrero [11] for the control  $u(x, T) = M$  is constant. Using the Cole-Hopf transformation, they show that there exist  $T_0 > 0$  such that for all time  $T > T_0$  and small viscosity, they prove the exact controllability. Also Guerrero-Imanuvilov [13] proves a negative result by showing that  $M = 0$  cannot be controllable.

Theorem (1.3) is stronger and much more precise result in the non viscous case because

- (i). It removes the condition on time  $T_c$  and obtains exact controllability.
- (ii). It deals with general convex flux instead of Burger's equation.
- (iii). In section (5) we give a criterion when the constants are controllable.

In the case of problem (II), Fabio-Ancona and Andrea-Marson [3],[4] studied the problem from the point of view of Hamilton-Jacobi equations (Earlier similar method was developed by Joseph-Gowda [16]) and studies the compactness properties of  $\{u(\cdot, T)\}$  when  $u(x, 0) = 0$  and  $u(\cdot, 0) \in \mathcal{U}$ , here  $\mathcal{U}$  is a set of controls satisfying some properties. But they do not address the exact controllability question and Theorem (1.2) gives a precise solution for control problem (II).

In our results on controllability, superlinearity of  $f$  plays an important role in removing the condition on  $T_c$  and obtain a free region (see Lemmas (2.9) and (2.10)). Next using convexity, we explicitly construct solutions in these free regions for particular data which allow to obtain solutions for control problems (see Lemmas (4.1) and (4.2)).

**(3) Optimal controllability:** Let  $g \in L^\infty(\mathbb{R})$  with compact support be given. For  $u_0 \in L^\infty(\mathbb{R})$ , let  $u$  be the solution of (1.2) in  $\Omega = \mathbb{R} \times \mathbb{R}_+$  with initial data  $u_0(x)$ . Define the cost functional

$$J(u_0) = \int_{\mathbb{R}} |u(x, T) - g(x)|^2 dx, \quad (1.42)$$

and consider the minimization problem

$$C = \inf_{u_0 \in L^\infty(\mathbb{R})} J(u_0).$$

This problem was considered by Castro-Palacios-Zuazua [6] and proved that there exists a minimizer. Since the functional is neither convex nor differentiable, it is quite hard to give a numerical scheme to capture a minimizer.

In section (5), we tackle this optimal controllability in a different way. From Lax-Oleinik formula, we first reduce the problem to a standard optimization in a Hilbert space and then using the explicit construction of a solution (see Lemma (4.1)) to obtain a minimizer. This construction turns out to be far **simpler**.

In Section (6), we generalize some of the results on control and optimal controllability.

**Guidelines for the readers:** Lemmas 2.2 and 2.4 are required to understand the shock profile. We use Lemmas 2.9, 2.10, 2.15, 4.1, 4.2 to prove the controllability results.

All this results in this paper has been extended to discontinuous flux [1].

**Acknowledgement:** Authors would like to thank Enric Zuazua for suggesting this problem and providing some valuable references.

## 2 Finer Analysis of Characteristics:

In a beautiful paper, Dafermos [8] had extensively studied the properties of characteristic curves. Here we make a finer analysis of these characteristics curves and then use them to obtain our results. In order to do this, first we recollect the results of Lax-Oleinik explicit formula and a good reference for this, is third chapter in [10].

Let  $f^*(p) = \sup_q \{pq - f(q)\}$  denote the Legendre transform of  $f$ .

Then  $f^*$  is in  $C^1$ , strictly convex, super linear growth and satisfies

$$\begin{aligned} f &= f^{**}, \\ f^{*'}(p) &= (f')^{-1}(p), \\ f^*(f'(p)) &= pf'(p) - f(p), \\ f(f^{*'}(p)) &= pf^{*'}(p) - f^*(p). \end{aligned} \tag{2.1}$$

**Controlled Curves:** Let  $x \in \mathbb{R}$ ,  $0 \leq s < t$  and define the controlled curves  $\Gamma(x, s, t)$  by

$$\Gamma(x, s, t) = \{r : [s, t] \rightarrow \mathbb{R}; r \text{ is linear and } r(t) = x\}, \tag{2.2}$$

and denote  $\Gamma(x, t) = \Gamma(x, 0, t)$ .

**Value function:** Let  $u_0 \in L^\infty(\mathbb{R})$ ,  $x_0 \in \mathbb{R}$ , define

$$v_0(x) = \int_{x_0}^x u_0(\theta) d\theta, \tag{2.3}$$

be its primitive. Define the value function  $v(x, t)$  by

$$\begin{aligned} v(x, t) &= \min_{r \in \Gamma(x, t)} \left\{ v_0(r(0)) + tf^* \left( \frac{x-r(0)}{t} \right) \right\} \\ &= \min_{\beta \in \mathbb{R}} \left\{ v_0(\beta) + tf^* \left( \frac{x-\beta}{t} \right) \right\}. \end{aligned} \tag{2.4}$$

Then  $v$  satisfies the

**Dynamic Programming principle:** For  $0 \leq s < t$ ,

$$v(x, t) = \min_{r \in \Gamma(x, s, t)} \left\{ v(r(s), s) + (t-s)f^* \left( \frac{x-r(s)}{t-s} \right) \right\}. \tag{2.5}$$

Define the characteristic set  $ch(x, s, t, u_0)$  and extreme characteristics  $y_\pm(x, s, t, u_0)$  by

$$ch(x, s, t, u_0) = \{r \in \Gamma(x, s, t); r \text{ is a minimizer in (2.5)}\}, \tag{2.6}$$

$$y_-(x, s, t, u_0) = \min\{r(s) : r \in ch(x, s, t, u_0)\}, \tag{2.7}$$

$$y_+(x, s, t, u_0) = \max\{r(s); r \in ch(x, s, t, u_0)\}, \tag{2.8}$$

Denote  $ch(x, t, u_0) = ch(x, 0, t, u_0)$ ,  $y_\pm(x, t, u_0) = y_\pm(x, 0, t, u_0)$ . Then we have the following result due to Hopf, Lax -Oleinik:

**THEOREM 2.1** *Let  $0 \leq s < t$ ,  $u_0, v_0, v$  be as above, then*

1.  *$v$  is a uniformly Lipschitz continuous function and is a unique viscosity solution of the Hamilton-Jacobi equation*

$$\begin{aligned} v_t + f(v_x) &= 0 & (x, t) \in \mathbb{R} \times (0, \infty), \\ v(x, 0) &= v_0(x) & x \in \mathbb{R}. \end{aligned} \tag{2.9}$$

2. There exist  $M > 0$ , depending only on  $\|u_0\|_\infty$  and Lipschitz constant of  $f$  restricted to the interval  $[-\|u_0\|_\infty, \|u_0\|_\infty]$  such that for  $(x, t) \in \mathbb{R} \times \mathbb{R}_+$ ,  $ch(x, s, t, u_0) \neq \emptyset$  and for  $r \in ch(x, s, t, u_0)$

$$\left| \frac{x - r(s)}{t - s} \right| \leq M. \quad (2.10)$$

3. NIP (Non intersecting property of characteristics): Let  $x_1 \neq x_2$  and for  $i = 1, 2, r_i \in ch(x_i, s, t, u_0)$ . Then  $r_1(\theta) \neq r_2(\theta)$  for all  $\theta \in (s, t)$ .

From NIP, it follows that for  $0 \leq s < t$ ,

(a).  $x \mapsto y_\pm(x, s, t, u_0)$  are non decreasing functions,

(b). At the points of continuity of  $y_+$ ,

$$y_+(x, s, t, u_0) = y_-(x, s, t, u_0),$$

and hence  $ch(x, s, t, u_0) = \{r\}$ , where  $r$  is given by

$$r(\theta) = \frac{x - y_+(x, s, t, u_0)}{t - s}(\theta - t) + x.$$

(c). Let  $r \in ch(x, t, u_0)$ ,  $z = r(s)$ . Let  $r_1(\theta) = r(\theta)$  for  $0 \leq \theta \leq s$ ,  $r_2(\theta) = r(\theta)$  for  $s \leq \theta \leq t$ . Then  $r_1 \in ch(z, s, u_0)$ ,  $r_2 \in ch(x, s, t, u_0)$ .

4. Let  $u(x, t) = \frac{\partial v}{\partial x}(x, t)$ . Then  $u$  is the unique solution of (1.2) in  $\Omega = \mathbb{R} \times \mathbb{R}_+$  with initial data  $u_0$  and satisfying

$$|u(x, t)| \leq \|u_0\|_\infty. \quad (2.11)$$

For a.e  $x$ ,  $y_-(x, t) = y_+(x, t)$  and  $u$  is given by

$$f'(u(x, t)) = \frac{x - y_+(x, t, u_0)}{t} = \frac{x - y_-(x, t, u_0)}{t}. \quad (2.12)$$

Let  $x$  be a point of differentiability of  $y_\pm(x, t, u_0)$  and  $y_\pm(x, t, u_0)$  is a point of differentiability of  $v_0$ , then

$$u(x, t) = u_0(y_\pm(x, t, u_0)). \quad (2.13)$$

5. Let  $u_0, w_0 \in L^\infty(\mathbb{R})$  and  $u, w$  be the solutions given in (4) with initial data  $u_0, w_0$  respectively. Then

(a). Monotonicity: Let  $u_0(x) \leq w_0(x)$  for  $x \in \mathbb{R}$ , then for a.e  $x \in \mathbb{R}, t > 0$ ,

$$u(x, t) \leq w(x, t). \quad (2.14)$$



(b).  $L^1_{loc}$  contractivity: Let  $c = \max(\|u_0\|_\infty, \|w_0\|_\infty)$  and  $I = [-c, c]$ . Then there exist a  $M > 0$ , depending on Lipschitz constant  $f$  restricted to  $I$  such that for all  $t > 0$ ,  $a < b$ ,

$$\int_a^b |u(x, t) - w(x, t)| dx \leq \int_{a-Mt}^{b+Mt} |u_0(x) - w_0(x)| dx. \quad (2.15)$$

For the proofs of (1) to (4) see chapter (3) of [10] and for (5), see chapter (3) of [14].

In this sequel we follow the notations of characteristic curves as in [2]. From now onwards, we assume that  $\Omega = \mathbb{R} \times (0, \infty)$ ,  $u_0 \in L^\infty(\mathbb{R})$ .

**Left and right characteristic curves:** Let  $0 \leq s < t$ ,  $u$  be a solution of (1.2) with initial data  $u_0$  and  $\alpha \in \mathbb{R}$ . Define the left characteristic curve  $R_-(t, s, \alpha, u_0)$  and right characteristic curve  $R_+(t, s, \alpha, u_0)$  and denote  $R_\pm(t, \alpha, u_0) = R_\pm(t, 0, \alpha, u_0)$  by

$$R_-(t, s, \alpha, u_0) = \inf\{x; \alpha \leq y_-(x, s, t, u_0)\}, \quad (2.16)$$

$$R_+(t, s, \alpha, u_0) = \sup\{x : y_+(x, s, t, u_0) \leq \alpha\}. \quad (2.17)$$

In view of (2.10),  $y_-(x, s, t, u_0) \rightarrow -\infty$  as  $x \rightarrow -\infty$ ,  $y_+(x, s, t, u_0) \rightarrow +\infty$  as  $x \rightarrow +\infty$ . Hence (2.16) and (2.17) are well defined. Our aim is to study the continuous dependence of  $R_\pm$  on their arguments  $(t, \alpha, u_0)$ .

For  $x, y \in \mathbb{R}, t > 0$ , let  $r(\theta, t, x, y) \in \Gamma(x, t)$  be the line joining  $(x, t), (y, 0)$  given by

$$r(\theta, t, x, y) = \left(\frac{x-y}{t}\right)(\theta-t) + x. \quad (2.18)$$

Observe that  $r(0, t, x, y) = y$  and hence  $r \in ch(x, t, u_0)$  if and only if  $y$  is a minimizer in (2.4). Hence define the extreme characteristic lines by

$$r_\pm(\theta, t, x) = r(\theta, t, y_\pm(x, t, u_0)). \quad (2.19)$$

Since  $r_\pm(0, t, x) = y_\pm(x, t, u_0)$  and  $y_-(x, t, u_0) \leq y_+(x, t, u_0)$ , hence for all  $\theta \in [0, t]$ ,

$$r_-(\theta, t, x) \leq r_+(\theta, t, x). \quad (2.20)$$

Then we have the following

**Lemma 2.2** *Let  $u_0, w_0, \{u_0^k\}$  are in  $L^\infty(\mathbb{R})$  and  $\alpha, \{\alpha_k\}$  are in  $\mathbb{R}$ . Let  $v, W, \{v_k\}$  be the value functions defined in (2.4) with respect to the data  $u_0, w_0, \{u_0^k\}$  respectively. Let  $u = \frac{\partial v}{\partial x}, w = \frac{\partial W}{\partial x}, u_k = \frac{\partial v_k}{\partial x}$  be the solutions of (1.2). Then*

1. *Let  $x_1 < x_2, 0 \leq s < t$  and  $\beta \in \mathbb{R}$  be a minimizer for  $v(x_1, t)$  and  $v(x_2, t)$  in (2.5). Then for  $x_1 < x < x_2$ ,  $\beta$  is the unique minimizer for  $v(x, t)$  and satisfies*

$$f'(u(x, t)) = \frac{x - \beta}{t - s}. \quad (2.21)$$

2. Let  $x_k \in \mathbb{R}, r_k \in ch(x_k, t, u_0)$  such that  $\lim_{k \rightarrow \infty} (x_k, r_k(0)) = (x, \beta)$ . Then  $r(\cdot, t, x, \beta) \in ch(x, t, u_0)$ . Furthermore

$$\lim_{x_k \uparrow x} y_+(x_k, t, u_0) = y_-(x, t, u_0), \quad (2.22)$$

$$\lim_{x_k \downarrow x} y_-(x_k, t, u_0) = y_+(x, t, u_0). \quad (2.23)$$

In particular,  $y_-$  is left continuous and  $y_+$  is right continuous.

3. (i). For all  $t > 0$ ,

$$R_-(t, \alpha, u_0) \leq R_+(t, \alpha, u_0), \quad (2.24)$$

$$\begin{cases} y_-(R_-(t, \alpha, u_0), t, u_0) \leq \alpha \leq y_+(R_-(t, \alpha, u_0), t, u_0), \\ y_-(R_+(t, \alpha, u_0), t, u_0) \leq \alpha \leq y_+(R_+(t, \alpha, u_0), t, u_0). \end{cases} \quad (2.25)$$

Further more if  $R_-(t, \alpha, u_0) < R_+(t, \alpha, u_0)$ , then for all  $x \in (R_-(t, \alpha, u_0), R_+(t, \alpha, u_0))$  (see Figure 9)

$$y_{\pm}(x, t, \alpha) = \alpha, f'(u(x, t)) = \frac{x - \alpha}{t}. \quad (2.26)$$

(ii). Let  $0 < s < t$ , then

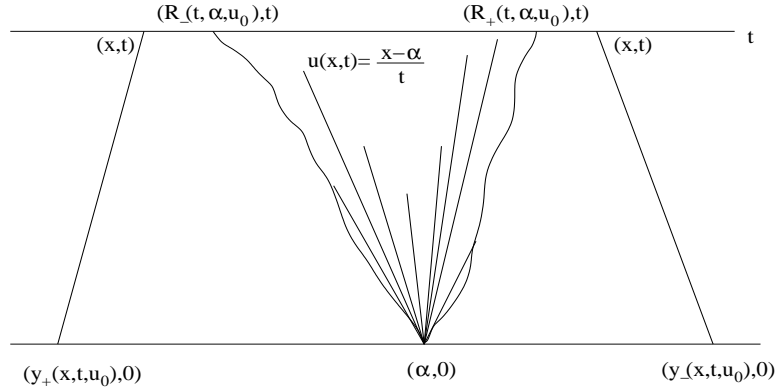


Figure 9:

$$R_-(t, s, \alpha, u_0) = R_+(t, s, \alpha, u_0). \quad (2.27)$$

4. Let  $0 \leq s < t$ . Then  $t \mapsto R_{\pm}(t, \alpha, u_0)$  are Lipschitz continuous function with Lipschitz norm depends only on  $\alpha$  and  $\|u_0\|_{\infty}$  and satisfying

$$\lim_{t \rightarrow 0} R_{\pm}(t, \alpha, u_0) = \alpha, \quad (2.28)$$

$$R_{\pm}(t, \alpha, u_0) = R_{\pm}(t, s, R_{\pm}(s, \alpha, u_0), u_0). \quad (2.29)$$

5. *Monotonicity:* Let  $u_0 \leq w_0, \alpha \leq \beta$ , then

$$R_{\pm}(t, \alpha, u_0) \leq R_{\pm}(t, \alpha, w_0), \quad (2.30)$$

$$R_{\pm}(t, \alpha, u_0) \leq R_{\pm}(t, \beta, u_0). \quad (2.31)$$

6. *Continuity with respect to data:* Let  $\alpha_k \rightarrow \alpha, u_0^k \rightarrow u_0$  in  $L^1_{loc}(\mathbb{R})$ . Then for  $t > 0$ , (see counter example 2.16).

(a). Suppose for all  $k, R_-(t, \alpha_k, u_0^k) \leq R_-(t, \alpha, u_0)$ , then

$$\lim_{k \rightarrow \infty} R_-(t, \alpha_k, u_0^k) = R_-(t, \alpha, u_0). \quad (2.32)$$

(b). Suppose for all  $k, R_+(t, \alpha_k, u_0^k) \geq R_+(t, \alpha, u_0)$ , then

$$\lim_{k \rightarrow \infty} R_+(t, \alpha_k, u_0^k) = R_+(t, \alpha, u_0). \quad (2.33)$$

(c). Suppose  $R_-(t, \alpha, u_0) < \bar{R} = \liminf_{k \rightarrow \infty} R_-(t, \alpha_k, u_0^k)$ , then for all  $x \in (R_-(t, \alpha, u_0), \bar{R}), y_{\pm}(x, t, u_0) = \alpha$  and

$$f'(u(x, t)) = \frac{x - \alpha}{t}. \quad (2.34)$$

(d). Suppose  $\lim_{k \rightarrow \infty} R_+(t, \alpha_k, u_0^k) = \bar{R} < R_+(t, \alpha, u_0)$ , then for all  $x \in (\bar{R}, R_+(t, \alpha, u_0)), y_{\pm}(x, t, u_0) = \alpha$  and

$$f'(u(x, t)) = \frac{x - \alpha}{t}. \quad (2.35)$$

As an immediate consequence of this, if  $R_-(t, \alpha, u_0) = R_+(t, \alpha, u_0)$  for  $t > 0$ , then  $R_{\pm}(t, \alpha, u_0)$  is continuous at  $(\alpha, u_0)$ .

**Proof.** (1). Let  $x \in (x_1, x_2)$  and  $r \in ch(x, s, t, u_0)$ . Suppose  $r(s) \neq \beta$ . then  $r$  intersects one of the characteristics  $(\frac{x_i - \beta}{t - s})(\theta - t) + x_i, i = 1, 2$ , which contradicts NIP of Theorem (2.1). Hence  $\beta = r(s) = y_{\pm}(x, s, t, u_0)$ . Furthermore

$$v(x, t) = v(\beta, s) + (t - s)f^*\left(\frac{x - \beta}{t - s}\right),$$

and for a.e  $x$ ,

$$u(x, t) = \frac{\partial v}{\partial x} = f'^*\left(\frac{x - \beta}{t - s}\right) = (f')^{-1}\left(\frac{x - \beta}{t - s}\right).$$

This proves (1).

(2). From the continuity of  $v$  and  $f^*$ , we have

$$\begin{aligned} v(x, t) &= \lim_{k \rightarrow \infty} v(x_k, t) \\ &= \lim_{k \rightarrow \infty} \left\{ v_0(r_k(0)) + t f^* \left( \frac{x_k - r_k(0)}{t} \right) \right\} \\ &= v_0(\beta) + t f^* \left( \frac{x - \beta}{t} \right), \end{aligned}$$

and hence  $r(\cdot, t, x, \beta) \in ch(x, t, u_0)$ . Let  $x_1 < x_2$ , then from NIC,  $y_+(x_1, t, u_0) \leq y_-(x_2, t, u_0)$ . From monotonicity of  $y_{\pm}$ , we have

$$y_-(x_1, t, u_0) \leq y_+(x_1, t, u_0) \leq y_-(x_2, t, u_0) \leq y_+(x_2, t, u_0).$$

Let  $x_k \uparrow x$ , then from above inequality,

$$\beta = \varliminf_{k \rightarrow \infty} y_+(x_k, t, u_0) \leq y_-(x, t, u_0).$$

Since a subsequence of  $y_+(x_k, t, u_0)$  converges to  $\beta$ , hence  $r(\cdot, t, x, \beta) \in ch(x, t, u_0)$ . Therefore  $\beta \leq y_-(x, t, u_0) \leq r(0, t, x, \beta) = \beta$ . This proves (2.22). Similarly (2.23) follows. This proves (2).

(3). (i). Suppose  $y_-(R_-(t, \alpha, u_0), t, u_0) > \alpha$ . Then from (2.22) there exist  $x_0 < R_-(t, \alpha, u_0)$  such that for all  $x \in (x_0, R_-(t, \alpha, u_0))$ ,  $y_+(x, t, u_0) > \alpha$ . Let  $x$  be a point of continuity of  $y_+$ , then from (3) of theorem (2.1),  $y_-(x, t, u_0) = y_+(x, t, u_0) > \alpha$  and hence  $R_-(t, \alpha, u_0) \leq x < R_-(t, \alpha, u_0)$  which is a contradiction. Suppose  $y_+(R_-(t, \alpha, u_0), t, u_0) < \alpha$ , again from (2.23) there exist  $x_0 > R_-(t, \alpha, u_0)$  such that for all  $x \in (R_-(t, \alpha, u_0), x_0)$ ,  $y_-(x, t, u_0) < \alpha$ . Therefore at points  $x$  of continuity,  $\alpha \leq y_+(x, t, u_0) = y_-(x, t, u_0) < \alpha$ , which is a contradiction. This proves (2.25) and (2.26) follows similarly.

Suppose  $R_+(t, \alpha, u_0) < R_-(t, \alpha, u_0)$ , then from (2.25), (2.26),  $y_-(R_-(t, \alpha, u_0), \alpha, u_0) \leq \alpha \leq y_+(R_+(t, \alpha, u_0), t, u_0)$ , therefore from NIC,  $y_-(R_-(t, \alpha, u_0), t, u_0) = \alpha = y_+(R_+(t, \alpha, u_0), t, u_0)$ . Hence from (2.21), for all  $x \in (R_+(t, \alpha, u_0), R_-(t, \alpha, u_0))$ ,  $\alpha$  is a minimizer for  $v(x, t)$  which implies that  $R_-(t, \alpha, u_0) \leq x < R_-(t, \alpha, u_0)$  which is a contradiction. This proves (2.24).

Suppose  $R_-(t, \alpha, u_0) < R_+(t, \alpha, u_0)$ . then from (2.24), (2.25), (2.26) we have

$$\alpha \leq y_+(R_-(t, \alpha, u_0), t, u_0) \leq y_-(R_+(t, \alpha, u_0), t, u_0) \leq \alpha.$$

Therefore from (1), for all  $x \in (R_-(t, \alpha, u_0), R_+(t, \alpha, u_0))$ ,  $y_{\pm}(x, t, u_0) = \alpha$  and  $f'(u(x, t)) = \frac{x - \alpha}{t}$ . This proves (2.26).

(3). (ii). Let  $0 < s < t$ , then as in (2.24) we have  $R_-(t, s, \alpha, u_0) \leq R_+(t, s, \alpha, u_0)$ . Suppose  $R_-(t, s, \alpha, u_0) < R_+(t, s, \alpha, u_0)$ , then as in (2.26), we have for all  $x \in (R_-(t, s, \alpha, u_0), R_+(t, s, \alpha, u_0))$ ,  $f'(u(x, t)) = \frac{x - \alpha}{t - s}$ . Let  $R_-(t, s, \alpha, u_0) < x_1 < x_2 < R_+(t, s, \alpha, u_0)$  and  $r_{\pm}(\cdot, t, x_1), r_{\pm}(\cdot, t, x_2)$  be the extreme characteristics at  $x_1, x_2$ . Hence  $r_{\pm}(s, t, x_1) = r_{\pm}(s, t, x_2) = \alpha$  contradicting NIP. This proves (ii) and hence (3).

(4). Let  $0 \leq s < t$ ,  $R_- = R_-(t, \alpha, u_0)$ ,  $y_{\pm} = y_{\pm}(R_-, t, u_0)$  and  $r_{\pm}(\theta) = r(\theta, t, R_-, y_{\pm}) \in ch(R_-, t, u_0)$ . Then from (3) of theorem 2.1,  $r_{\pm}|_{(0,s)} \in ch(r_{\pm}(s), s, u_0)$ .

**Claim** :  $r_-(s) \leq R_-(s, \alpha, u_0) \leq r_+(s)$ .

Suppose  $R_-(s, \alpha, u_0) < r_-(s)$ . For  $x \in (R_-(s, \alpha, u_0), r_-(s))$ ,  $y_-(x, s, \alpha) \geq \alpha$ . Hence if  $y_- < \alpha$  or  $y_-(x, s, \alpha) > \alpha$ , then the characteristics  $r_-(\theta), r_-(\theta, s, x)$  intersect for some  $\theta \in (0, s)$  which contradicts NIC. Therefore  $\alpha = y_- = y_-(x, s, \alpha)$  and from (2)  $\tilde{r}(\theta) = \tilde{r}(\theta, s, R_-(s, \alpha, u_0), \alpha) \in ch(R_-(s, \alpha, u_0), s, u_0)$ . From (2.22) choose a  $\xi < R_-$ ,  $y_-(\xi, t, u_0) < \alpha$  such that the characteristic  $\tilde{r}(\theta)$  and  $r(\theta, t, \xi, y_+(\xi, t, u_0))$  intersect for some  $\theta \in (0, s)$  which contradicts NIC.

Suppose  $r_+(s) < R_-(s, \alpha, u_0)$ , then for  $x \in (r_+(s), R_-(s, \alpha, u_0))$ ,  $y_-(x, s, u_0) < \alpha \leq r_+(0) = y_+$  and therefore the characteristic at  $(x, s)$  with end point  $(y_-(x, s, u_0), 0)$  intersects  $r_+(\theta)$  for some  $\theta \in (0, s)$  contradicting NIC. This proves the claim.

From (2.10) and the claim, we have

$$R_- + \left( \frac{R_- - y_-}{t} \right) (s - t) \leq R_-(s, \alpha, u_0) \leq R_- + \left( \frac{R_- - y_+}{t} \right) (s - t)$$

that is

$$\begin{aligned} |R_- - R_-(s, \alpha, u_0)| &\leq \left( \left| \frac{R_- - y_-}{t} \right| + \left| \frac{R_- - y_+}{t} \right| \right) |s - t| \\ &\leq 2M|s - t|. \end{aligned}$$

Also from (2.10) and (2.25), we have  $|R_- - y_{\pm}| = |R_- - r_{\pm}(0)| \leq Mt$ , hence  $\lim_{t \rightarrow 0} R_-(t, \alpha, u_0) = \alpha$ . Similarly for  $R_+(t, \alpha, u_0)$ .

From (c) of (3) in theorem 2.1, we have  $r_{\pm}|_{[s,t]} \in ch(R_-(t, \alpha, u_0), s, t, u_0)$ , hence from NIC and from the above claim we have for any  $x < R_-(t, \alpha, u_0) < z$ ,  $y_+(x, s, t, u_0) \leq r_-(s) \leq R_-(s, \alpha, u_0) \leq r_+(s) \leq y_-(z, s, t, u_0)$ . Therefore from the definitions it follows that  $R_-(t, \alpha, u_0) = R_-(t, s, R_-(t, s, u_0), u_0)$ . Similarly for  $R_+$  and this proves (4).

(5). From (5) of theorem (2.1), for  $t > 0$ , a.e.  $x$ ,  $u(x, t) \leq w(x, t)$ . Let  $y_{1,\pm}(x) = y_{\pm}(x, t, u_0)$ ,  $y_{2,\pm}(x) = y_{\pm}(x, t, w_0)$ . Choose a dense set  $D \subset \mathbb{R}$  such that for  $i = 1, 2$ ,  $x \in D$ ,  $u(x, t) \leq v(x, t)$ ,  $y_{i,+}(x) = y_{i,-}(x)$ . Hence from (2.12) we have for  $x \in D$ ,

$$\frac{x - y_{1,\pm}(x)}{t} = f'(u(x, t)) \leq f'(w(x, t)) = \frac{x - y_{2,\pm}(x)}{t}.$$

This implies  $y_{2,\pm}(x) \leq y_{1,\pm}(x)$ . Therefore from (2.22) and (2.23),

$$\begin{aligned} R_-(t, \alpha, u_0) &= \inf\{x \in D : y_{1,-}(x) \geq \alpha\} \\ &\leq \inf\{x \in D : y_{2,-}(x) \geq \alpha\} \\ &= R_-(t, \alpha, w_0). \end{aligned}$$

$$\begin{aligned}
R_+(t, \alpha, u_0) &= \sup\{x \in D, y_{1,+}(x) \leq \alpha\} \\
&\leq \sup\{x \in D : y_{2,+}(x) \leq \alpha\} \\
&= R_+(t, \alpha, w_0).
\end{aligned}$$

This proves (2.30).

$$\begin{aligned}
R_-(t, \alpha, u_0) &= \inf\{x : y_-(x, t, u_0) \geq \alpha\} \\
&\leq \inf\{x : y_-(x, t, u_0) \geq \beta\} \\
&= R_-(t, \beta, u_0),
\end{aligned}$$

and similarly for  $R_+$ . This proves (5).

(6). Let  $y_{\pm}^k(x) = y_{\pm}(x, t, u_0^k)$ ,  $R_{\pm}^k = R_{\pm}(t, \alpha_k, u_0^k)$ . Since  $\{y_{\pm}^k\}$  are monotone functions and  $\{R_{\pm}^k\}$  are bounded, hence from Helly's theorem and  $L_{loc}^1$ -contractivity, there exist a subsequence still denoted by  $k$  such that for *a.e.*  $x$ ,

$$\lim_{k \rightarrow \infty} u_k(x, t) = u(x, t) \quad (2.36)$$

$$\lim_{k \rightarrow \infty} y_{\pm}^k(x) = y_{\pm}(x) \quad (2.37)$$

$$\left( \lim_{k \rightarrow \infty} R_{\pm}^k, \lim_{k \rightarrow \infty} \bar{R}_{\pm}^k \right) = \left( \bar{R}_{\pm}, \tilde{R}_{\pm} \right), \quad (2.38)$$

where  $u$  is the solution of (1.2) with  $u(x, 0) = u_0(x)$ . Let  $D \subset \mathbb{R}$  be a dense set such that for all  $x \in D$ , (2.36) to (2.38) holds and for all  $k$ .

$$y_+^k(x) = y_-^k(x) \quad (2.39)$$

$$y_+(x, t, u_0) = y_-(x, t, u_0) \quad (2.40)$$

$$f'(u_k(x, t)) = \frac{x - y_{\pm}^k(x)}{t} \quad (2.41)$$

$$f'(u(x, t)) = \frac{x - y_{\pm}(x, t, u_0)}{t}. \quad (2.42)$$

Hence from (2.37), (2.41) and (2.42), for  $x \in D$ ,

$$y_{\pm}(x) = \lim_{k \rightarrow \infty} y_{\pm}^k(x) = y_{\pm}(x, t, u_0). \quad (2.43)$$

**Case (i):** Let for all  $k$ ,  $R_-^k \leq R_-(t, \alpha, u_0)$ , then  $\bar{R}_- \leq R_-(t, \alpha, u_0)$ . Suppose  $\bar{R}_- < R_-(t, \alpha, u_0)$ . Let  $I = (\bar{R}_-, R_-(t, \alpha, u_0))$ ,  $x \in D \cap I$  and choose  $k_0 = k_0(x) > 0$  such that for all  $k \geq k_0$ ,  $R_-^k < x$ , then

$$\alpha = \lim_{k \rightarrow \infty} \alpha_k \leq \lim_{k \rightarrow \infty} y_-^k(x) = y_-(x, t, u_0) < \alpha,$$

which is a contradiction. Hence  $\bar{R}_- = R_-(t, \alpha, u_0)$ .

**Case (ii) :** Let for all  $k$ ,  $R_-(t, \alpha, u_0) \leq R_-^k$ , then  $R_-(t, \alpha, u_0) \leq \tilde{R}_-$ . Suppose  $R_-(t, \alpha, u_0) < \tilde{R}_-$ , then for  $x \in D \cap (R_-(t, \alpha, u_0), \tilde{R}_-)$  choose  $k_0 = k_0(x)$  such that for  $k > k_0$ ,  $x < R_-^k$ . Hence  $\alpha \leq y_-(x, t, u_0) = \lim_{k \rightarrow \infty} y_-^k(x) \leq \alpha$  and therefore  $y_-(x, t, u_0) = \alpha$ . Therefore from (2.12),  $f'(u(x, t)) = \frac{x-\alpha}{t}$ . Similarly for  $R_+$  and this proves (6) and hence the Lemma.

Next we study the characterization of  $R_{\pm}$  and some comparison properties. For this we need some well known results which will be proved in the following Lemma.

Let  $\Omega \subset \mathbb{R}^n$  be an open set and  $B(1)$  denote the unit ball in  $\mathbb{R}^n$ . Let  $0 \leq \chi \in C_c^\infty(B(1))$  with  $\int_{\mathbb{R}^n} \chi(x) dx = 1$ . Let  $\varepsilon > 0$  and denote  $\chi_\varepsilon(x) = \frac{1}{\varepsilon^n} \chi(\frac{x}{\varepsilon})$  be the usual mollifiers. Let  $u_0 \in L_{loc}^1(\mathbb{R}^n)$  and define

$$u_0^\varepsilon(x) = (\chi_\varepsilon * u_0)(x) = \int_{B(1)} \chi(y) u_0(x - \varepsilon y) dy ,$$

then

**Lemma 2.3** *Denote ess inf and ess sup by inf and sup. Then*

1. *With the above notation, for  $x \in \Omega$ , there exists a  $\varepsilon_0 = \varepsilon_0(x) > 0$  such that for all  $0 < \varepsilon < \varepsilon_0$ ,*

$$\inf_{y \in \Omega} u_0(y) \leq u_0^\varepsilon(x) \leq \sup_{y \in \Omega} u_0(y). \quad (2.44)$$

2. *Let  $t_0, \varepsilon_0, \alpha \in \mathbb{R}$  and  $\omega \in L^\infty((0, t_0))$ . Let  $R : (0, t_0] \rightarrow \mathbb{R}$  be a locally Lipschitz continuous function such that for a.e  $t \in (0, t_0)$ ,*

$$\omega(t) \geq (f')^{-1} \left( \frac{R(t) - \alpha}{t} \right) + \varepsilon_0 \quad (2.45)$$

$$\frac{dR}{dt} = \frac{f(\omega(t)) - f((f')^{-1}(\frac{R(t)-\alpha}{t}))}{\omega(t) - (f')^{-1}(\frac{R(t)-\alpha}{t})}, \quad (2.46)$$

then

$$\overline{\lim}_{t \rightarrow 0} \left| \frac{R(t) - \alpha}{t} \right| = \infty. \quad (2.47)$$

**Proof.** (1). Let  $\Omega_\varepsilon = \{x; d(x, \Omega^c) > \varepsilon\}$ . Then for  $x \in \Omega$ , there exists an  $\varepsilon_0 > 0$ , such that  $x \in \Omega_\varepsilon$ , for all  $\varepsilon < \varepsilon_0$ . Hence  $x - \varepsilon y \in \Omega$ , for all  $y \in B(1)$  and

$$\inf_{y \in \Omega} u_0(y) \leq u_0(x - \varepsilon y) \leq \sup_{y \in \Omega} u_0(y),$$

multiply this identity by  $\chi$  and integrate over  $B(1)$  gives (2.44).

(2). Suppose (2.47) is not true. That is

$$\sup_{t>0} \left| \frac{R(t) - \alpha}{t} \right| < \infty. \quad (2.48)$$

Let  $m$  be defined by

$$m = \inf_{t \in (0, t_0)} \int_0^1 f'' \left( (f')^{-1} \left( \frac{R(t) - \alpha}{t} \right) + \theta \left( \omega(t) - (f')^{-1} \left( \frac{R(t) - \alpha}{t} \right) \right) \right) (1 - \theta) d\theta.$$

**Claim:**  $m > 0$ .

Suppose  $m = 0$ , then there exists a sequence  $t_k \rightarrow \tilde{t}$  in  $[0, t_0]$  such that

$$\lim_{k \rightarrow \infty} \int_0^1 f' \left( (f')^{-1} \left( \frac{R(t_k) - \alpha}{t_k} \right) + \theta \left( \omega(t_k) - (f')^{-1} \left( \frac{R(t_k) - \alpha}{t_k} \right) \right) \right) (1 - \theta) d\theta = 0.$$

Since  $\omega \in L^\infty((0, t_0))$  and from (2.48), choose a subsequence still denoted by  $\{t_k\}$  such that  $\omega(t_k) \rightarrow a$ ,  $(f')^{-1} \left( \frac{R(t_k) - \alpha}{t_k} \right) \rightarrow b$  as  $k \rightarrow \infty$ . Hence

$$\int_0^1 f''(b + \theta(a - b)) d\theta = 0.$$

Since  $f$  is convex and hence  $f''(a + \theta(a - b)) = 0$ , for  $\theta \in [0, 1]$ . From (2.45),  $a - b \geq \varepsilon_0$  and hence  $f(b + \theta(a - b))$  is linear in  $\theta$ , which contradicts the strict convexity of  $f$ . This proves the claim.

From Taylor's series and the claim we have

$$\begin{aligned} \frac{dR}{dt} &= \frac{R(t) - \alpha}{t} \\ &+ \int_0^1 f'' \left( (f')^{-1} \left( \frac{R(t) - \alpha}{t} \right) + \theta \left( \omega(t) - (f')^{-1} \left( \frac{R(t) - \alpha}{t} \right) \right) \right) (1 - \theta) d\theta \\ &\times \left( \omega(t) - (f')^{-1} \left( \frac{R(t) - \alpha}{t} \right) \right) \\ &\geq \frac{R(t) - \alpha}{t} + \frac{m\varepsilon_0}{2}, \end{aligned}$$

or

$$t \frac{d}{dt} \left( \frac{R(t) - \alpha}{t} \right) \geq \frac{m\varepsilon_0}{2}.$$

For  $0 < t_1 < t_0$ , integrating from  $t$  to  $t_1$ , to obtain

$$\frac{R(t) - \alpha}{t} \leq \frac{R(t_1) - \alpha}{t_1} - \frac{m\varepsilon_0}{2} \log \frac{t_1}{t} \rightarrow -\infty \quad \text{as } t \rightarrow 0,$$



which contradicts (2.48). This proves (2) and hence the Lemma.

**Lemma 2.4** *Let  $T > 0, \alpha, \beta \in \mathbb{R}, u_0, v_0$  and  $v$  be as in (2.3) and (2.4). Then*

(1). *Let  $x_0 \in \mathbb{R}, t > 0$  such that*

$$y_-(x_0, t, u_0) \leq \alpha \leq y_+(x_0, t, u_0), \quad (2.49)$$

*then*

(i). *if  $x_0 \leq R_-(t, \alpha, u_0)$ , then  $x_0 = R_-(t, \alpha, u_0)$ . If  $R_-(t, \alpha, u_0) < x_0$ , then for all  $x \in (R_-(t, \alpha, u_0), x_0)$ ,  $f'(u(x, t)) = \frac{x-\alpha}{t}$ .*

(ii). *if  $x_0 \geq R_+(t, \alpha, u_0)$ , then  $x_0 = R_+(t, \alpha, u_0)$ . If  $x_0 < R_+(t, \alpha, u_0)$ , then for all  $x \in (x_0, R_+(t, \alpha, u_0))$ ,  $f'(u(x, t)) = \frac{x-\alpha}{t}$ .*

(2). (i). *Let  $x \geq R_-(t, \alpha, u_0)$ , then*

$$v(x, t) = \inf_{y \geq \alpha} \left\{ v_0(y) + t f^* \left( \frac{x-y}{t} \right) \right\}. \quad (2.50)$$

(ii). *Let  $x \leq R_+(t, \alpha, u_0)$ , then*

$$v(x, t) = \inf_{y \leq \alpha} \left\{ v_0(y) + t f^* \left( \frac{x-y}{t} \right) \right\}. \quad (2.51)$$

(iii). *Let  $\alpha < \beta$  and for  $0 < t < T$  assume that*

$$R_+(t, \alpha, u_0) < R_-(t, \beta, u_0),$$

*then for  $R_+(t, \alpha, u_0) < x < R_-(t, \beta, u_0)$ ,*

$$v(x, t) = \inf_{\alpha \leq y \leq \beta} \left\{ v_0(y) + t f^* \left( \frac{x-y}{t} \right) \right\}, \quad (2.52)$$

$$m = \inf_{y \in [\alpha, \beta]} u_0(y) \leq u(x, t) \leq \sup_{y \in [\alpha, \beta]} u_0(y) = M. \quad (2.53)$$

$$f'(m) \leq \frac{x - y_+(x, t, u_0)}{t} \leq f'(M). \quad (2.54)$$

(3). *Let  $L(t, \alpha, u_0) \in \{R_\pm(t, \alpha, u_0)\}, R(t, \beta, u_0) \in \{R_\pm(t, \beta, u_0)\}$ . Suppose at  $t = T$ ,*

$$L(T, \alpha, u_0) = R(T, \beta, u_0), \quad (2.55)$$

then for all  $t \geq T$ , (see Figure 10).

$$L(t, \alpha, u_0) = R(t, \beta, u_0). \quad (2.56)$$

Furthermore, let  $\{u_0^k\}$  are in  $L^\infty(\mathbb{R})$  with  $\sup_k \|u_0^k\|_\infty < \infty$ . Let  $(\alpha_k, \beta_k, u_0^k) \rightarrow (\alpha, \beta, u_0)$  as  $k \rightarrow \infty$  in  $\mathbb{R}^2 \times L^1_{loc}(\mathbb{R})$  and  $T_k \rightarrow T$  in  $\mathbb{R}$  such that

$$\begin{aligned} R_-(T, \alpha, u_0) &= R_+(T, \beta, u_0) \\ R_-(T_k, \alpha_k, u_0^k) &= R_+(T_k, \beta_k, u_0^k). \end{aligned} \quad (2.57)$$

Then for  $t > T$ ,

$$\begin{aligned} \lim_{k \rightarrow \infty} R_+(t, \alpha_k, u_0^k) &= \lim_{k \rightarrow \infty} R_-(t, \beta_k, u_0^k) \\ &= R_+(t, \alpha, u_0) \\ &= R_-(t, \alpha, u_0). \end{aligned} \quad (2.58)$$

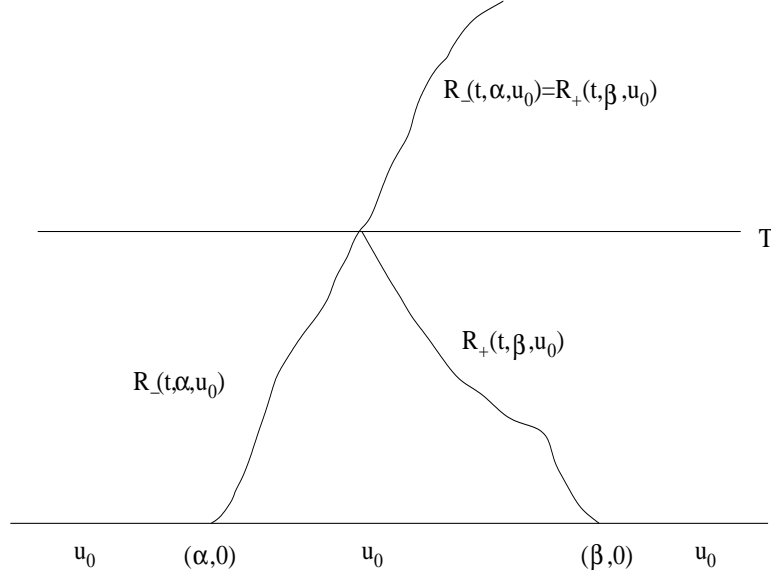


Figure 10:

**Proof.** (1). It is enough to prove (i) and (ii) follows similarly. Let  $C = R_-(t, \alpha, u_0)$ , then from (2.22)  $y_-(C, t, u_0) \leq \alpha$ . Suppose  $x_0 < C$ , then from (2.49), the characteristic line joining  $(C, t), (y_-(C, t, u_0), 0)$  and  $(x_0, t), (y_+(x_0, t, u_0), 0)$  intersect if  $y_+(x_0, t, u_0) > \alpha$  or  $y_-(C, t, u_0) < \alpha$ , which contradicts NIC. Hence  $y_+(x_0, t, u_0) = y_-(C, t, u_0) = \alpha$ . Therefore from (2.21), for  $x_0 < x < C$ ,  $f'(u(x, t)) = \frac{x-\alpha}{t}$ . This implies that  $C = R_-(t, \alpha, u_0) < x < C$ , which is a contradiction. Hence  $x_0 = R_-(t, \alpha, u_0)$ . Suppose  $C < x_0$ , then from the definition and (2.49), we have  $y_-(x_0, t, u_0)$

$\leq \alpha \leq y_-(x_0, t, u_0)$  and hence  $y_-(x_0, t, u_0) = \alpha$  and from (2.21),  $f'(u(x, t)) = \frac{x-\alpha}{t}$  for all  $C < x < x_0$ . This proves (1).

(2). It is enough to prove (i) and (ii) follows similarly. Let  $x \geq R_-(t, \alpha, u_0)$ , then from (2.25),  $y_+(x, t, u_0) \geq \alpha$ . Hence

$$\begin{aligned} & \inf \left\{ \inf_{y \geq \alpha} \{v_0(y) + tf^* \left( \frac{x-y}{t} \right)\}, \inf_{y < \alpha} \{v_0(y) + tf^* \left( \frac{x-y}{t} \right)\} \right\} \\ &= v(x, t) \\ &= v_0(y_+(x, t, u_0)) + tf^* \left( \frac{x - y_+(x, t, u_0)}{t} \right). \end{aligned}$$

Hence

$$v(x, t) = \inf_{y \geq \alpha} \{v_0(y) + tf^* \left( \frac{x-y}{t} \right)\}.$$

(iii). (2.52) follows from (2.50) and (2.51). Let  $\varepsilon > 0$ ,  $u_0^\varepsilon = \chi_\varepsilon * u_0$  and  $v_0^\varepsilon, v_\varepsilon$  be as in (2.3), (2.4) respectively. Let  $u^\varepsilon = \frac{\partial v^\varepsilon}{\partial x}$  be the solution of (1.2) in  $\Omega = \mathbb{R} \times \mathbb{R}_+$ . Since  $v_0^\varepsilon$  is differentiable and hence for a.e  $x$  and from (2.13),  $u^\varepsilon(x, t) = u_0^\varepsilon(y_+(x, t, u_0))$ . Since  $u_0^\varepsilon \rightarrow u_0$  in  $L^1_{loc}$  and hence  $u^\varepsilon \rightarrow u$  in  $L^1_{loc}$ . Therefore from (2.32) to (2.35), we have for  $0 < t < T$ ,

$$\overline{\lim}_{\varepsilon \rightarrow 0} R_+(t, \alpha, u_0^\varepsilon) \leq R_+(t, \alpha, u_0) < R_-(t, \beta, u_0) \leq \underline{\lim}_{\varepsilon \rightarrow 0} R_-(t, \beta, u_0^\varepsilon).$$

Let  $\varepsilon_k \rightarrow 0$  and choose a dense set  $D \subset (R_+(t, \alpha, u_0), R_-(t, \beta, u_0))$  such that for all  $x \in D$ ,

$$\begin{aligned} \lim_{k \rightarrow \infty} u^{\varepsilon_k}(x, t) &= u(x, t) \\ y(x) &= y_+(x, t, u_0) = y_-(x, t, u_0) \\ y_k(x) &= y_+(x, t, u_0^{\varepsilon_k}) = y_-(x, t, u_0^{\varepsilon_k}). \end{aligned}$$

For  $x \in D$ , choose  $k_0(x)$  such that for all  $k \geq k_0(x)$ ,  $x \in (R_+(t, \alpha, u_0^{\varepsilon_k}), R_-(t, \beta, u_0^{\varepsilon_k}))$ . Then from (4.52),  $y_k \in [\alpha, \beta]$ . Since  $u^{\varepsilon_k}(x, t) = u_0^{\varepsilon_k}(y_k(x))$ , hence from (2.44),

$$m \leq u_0^{\varepsilon_k}(y_k(x)) = u^{\varepsilon_k}(x, t) \leq M.$$

Letting  $k \rightarrow \infty$  to obtain (2.53). From (2.12),

$$f'(u^{\varepsilon_k}(x, t)) = \frac{x - y_k(x)}{t},$$

letting  $k \rightarrow \infty$  to obtain

$$\begin{aligned} \frac{x - y(x)}{t} &= f'(u(x, t)) = \lim_{k \rightarrow \infty} f'(u^{\varepsilon_k}(x, t)) \\ &= \lim_{k \rightarrow \infty} \frac{x - y_k(x)}{t}. \end{aligned}$$

Hence  $\lim_{k \rightarrow \infty} y_k(x) = y(x)$ ,

$$f'(m) \leq f'(u_0^{\varepsilon_k}(y_k(x))) = \frac{x - y_k(x)}{t} \leq f'(M),$$

Now letting  $k \rightarrow \infty$  to obtain

$$f'(m) \leq \frac{x - y(x)}{t} \leq f'(M),$$

For  $x \notin D$ , choose  $x_k \uparrow x$ ,  $y_+(x_k, t, u_0) = y_-(x_k, t, u_0)$ . Then from (2.22),  $y_+(x_k, t, u_0) \rightarrow y_-(x, t, u_0)$ . Now apply the inequalities for  $x_k$  and let  $k \rightarrow \infty$  to obtain (2.53), (2.54). This proves (2).

(3). Without loss of generality we can take  $L(t, \alpha, u_0) = R_-(t, \alpha, u_0)$  and  $R(t, \beta, u_0) = R_+(t, \beta, u_0)$ . Similar proof follows in all other cases. Let  $C = R_-(T, \alpha, u_0) = R_+(T, \beta, u_0)$  and  $t > T$ . Then from (2.27) and (2.29) we have

$$\begin{aligned} R_-(t, \alpha, u_0) &= R_-(t, T, C, u_0) \\ &= R_+(t, T, C, u_0) \\ &= R_+(t, \beta, u_0). \end{aligned} \tag{2.59}$$

This proves (2.56).

Let  $t > T$ , then choose  $k_0 = k_0(t)$  such that for all  $k > k_0, t > T_k$ . Then from (2.56) we have

$$\begin{aligned} R_k(t) &= R_-(t, \alpha_k, u_0^k) = R_+(t, \alpha_k, u_0^k), \\ R(t) &= R_-(t, \alpha, u_0) = R_+(t, \alpha, u_0). \end{aligned}$$

Hence from (6) of Lemma (2.2),

$$\overline{\lim}_{k \rightarrow \infty} R_k(t) \leq R_+(t, \alpha, u_0) = R_-(t, \alpha, u_0) \leq \underline{\lim}_{k \rightarrow \infty} R_k(t). \tag{2.60}$$

This proves (2.58) and hence the Lemma.

Next we give a criteria under which  $R_+ = R_-$ . Let  $\beta < \gamma$  and  $I_1 = [\beta, \gamma]$ , Define

$$m = \inf_{y \in I_1} u_0(y), \quad M = \sup_{y \in I_1} u_0(y), \quad I_2 = [f'(m), f'(M)].$$

Let

$$a_0 = \max\{f^*(q) - Mq; q \in I_2\}, \quad f'(q_0) = \max\{q; f^*(q) - Mq \leq a_0\}.$$

Then we have the following.

**Lemma 2.5** *Let  $\alpha < \beta < \gamma, \varepsilon_0 > 0$ . Let  $u_0 \in L^\infty(\mathbb{R})$  such that*

$$\inf_{[\alpha, \beta]} u_0(y) \geq q_0 + \varepsilon_0, \tag{2.61}$$

then for all  $t > 0$ ,

$$R_+(t, \beta, u_0) = R_-(t, \beta, u_0).$$

**Proof.** Suppose for some  $T > 0$ ,  $R_+(T, \beta, u_0) > R_-(T, \beta, u_0)$ , then from (2.56), for  $t < T$ ,

$$R_-(t, \beta, u_0) < R_+(t, \beta, u_0)$$

and from (2.26) for  $R_-(t, \beta, u_0) < x < R_+(t, \beta, u_0)$ .

$$f'(u(x, t)) = \frac{x - \beta}{t}. \quad (2.62)$$

From (2.28) we can choose  $T$  sufficiently small such that for all  $0 < t \leq T$ ,

$$R_+(t, \alpha, u_0) < R_-(t, \beta, u_0) < R_+(t, \beta, u_0) < R_-(t, \gamma, u_0). \quad (2.63)$$

**Claim:** For  $t \leq T$ ,

$$\frac{R_+(t, \beta, u_0) - \beta}{t} \leq f'(q_0). \quad (2.64)$$

Let  $x_k > R_+(t, \beta, u_0)$  be such that  $y_+(x_k, t, u_0) = y_-(x_k, t, u_0)$  and  $\lim_{k \rightarrow \infty} x_k = R_+(t, \beta, u_0)$ . Then from (2.54)

$$f'(m) \leq \frac{x - y_-(x_k, t, u_0)}{t} \leq f'(M).$$

Letting  $k \rightarrow \infty$  and from (2.23) we have

$$f'(m) \leq \frac{R_+(t, \beta, u_0) - y_+(R_+(t, \beta, u_0), t, u_0)}{t} \leq f'(M). \quad (2.65)$$

Let  $v_0(y) = \int_{\beta}^y u_0(\theta) d\theta$ , hence  $v_0(\beta) = 0$ . Denote

$$R(t) = R_+(t, \beta, u_0), \quad y_{\pm}(t) = y_{\pm}(R_+(t, \beta, u_0), t, u_0),$$

then from (2.62),  $y_-(t) = \beta$  and from (2.4) we have

$$\begin{aligned} tf^* \left( \frac{R(t) - \beta}{t} \right) &= v_0(y_-(t)) + tf^* \left( \frac{R(t) - y_-(t)}{t} \right) \\ &= v_0(y_+(t)) + tf^* \left( \frac{R(t) - y_+(t)}{t} \right) \\ &\leq M(y_+(t) - \beta) + tf^* \left( \frac{R(t) - y_+(t)}{t} \right) \\ &\leq M(y_+(t) - R(t)) + M(R(t) - \beta) + tf^* \left( \frac{R(t) - y_+(t)}{t} \right), \end{aligned}$$

and hence

$$f^* \left( \frac{R(t) - \beta}{t} \right) - M \left( \frac{R(t) - \beta}{t} \right) \leq f^* \left( \frac{R(t) - y_+(t)}{t} \right) - M \left( \frac{R(t) - y_+(t)}{t} \right).$$

From (2.65) it follows that

$$f^* \left( \frac{R(t) - \beta}{t} \right) - M \left( \frac{R(t) - \beta}{t} \right) \leq a_0,$$

and this proves (2.64) and hence the claim.

Let  $L(t) = R_-(t, \beta, u_0)$ , then letting  $x$  tends to  $L(t)$  in (2.62) and (2.64) to obtain

$$f'(u(L(t)+, t)) = \frac{L(t) - \beta}{t} \leq \frac{R_+(t, \beta, u_0) - \beta}{t} \leq f'(q_0). \quad (2.66)$$

From (2.53), for  $R_+(t, \alpha, u_0) < x < R_-(t, \beta, u_0) = L(t)$ ,  $u(x, t) \geq \inf_{y \in [\alpha, \beta]} u_0(y)$ , hence from (2.61) and (2.66), we have

$$\begin{aligned} u(L(t)-, t) &\geq \inf_{y \in [\alpha, \beta]} u_0(y) \geq q_0 + \varepsilon_0 \\ &\geq u(L(t)+, t) + \varepsilon_0 \\ &= f^{*'} \left( \frac{L(t) - \beta}{t} \right) + \varepsilon_0. \end{aligned} \quad (2.67)$$

From RH condition across  $L(t)$  gives

$$\frac{dL}{dt} = \frac{f(u(L(t)-, t)) - f \left( f^{*'} \left( \frac{L(t) - \beta}{t} \right) \right)}{u(L(t)-, t) - f^{*'} \left( \frac{L(t) - \beta}{t} \right)}. \quad (2.68)$$

Therefore  $L(t)$  satisfies the hypothesis (2) of Lemma (2.3) and hence from (2.47)

$$\lim_{t \rightarrow 0}^- \left| \frac{L(t) - \beta}{t} \right| = \infty,$$

which contradicts the uniform Lipschitz continuity of  $L$  from (4) of Lemma 2.2. Hence  $R_-(t, \beta, u_0) = R_+(t, \beta, u_0)$ , for all  $t$ , and this proves the Lemma.

**Remark 2.6** Observe that  $q_0$  entirely depends on the bounds of  $u_0$  in  $[\beta, \gamma]$ .

**Lemma 2.7** Let  $u$  be the solution of (1.2) with

$$\bar{u}_0(x) = u(x, 0) = \begin{cases} a & \text{if } x < \alpha, \\ u_0(x) & \text{if } x > \alpha. \end{cases}$$

Then for  $x < R_-(t, \alpha, \bar{u}_0)$ ,

$$u(x, t) = a, \quad (2.69)$$

$$f'(a) = \frac{R_-(t, \alpha, \bar{u}_0) - y_-(R_-(t, \alpha, \bar{u}_0), t, \bar{u}_0)}{t}. \quad (2.70)$$

**Proof.** Since  $\bar{v}_0(x) = \int^x \bar{u}_0(\theta) d\theta$  is differentiable for  $x < \alpha$  and hence from (2.13), for a.e.  $x < \alpha$ ,  $u(x, t) = \bar{u}_0(y_+(x, t, \bar{u}_0)) = a$  and

$$f'(a) = \frac{x - y_-(x, t, \bar{u}_0)}{t}.$$

From (2.22) and letting  $x \uparrow R_-(t, \alpha, \bar{u}_0)$  to obtain (2.70). This proves the Lemma.

Next we consider the following initial value problem taking three values. Let  $a, \lambda, m \in \mathbb{R}$ ,  $\alpha < \beta$  and consider

$$u_0^\lambda(x) = \begin{cases} a & \text{if } x < \alpha, \\ \lambda & \text{if } \alpha < x < \beta, \\ m & \text{if } x > \beta. \end{cases} \quad (2.71)$$

and denote

$$v_0^\lambda(x) = \int_\beta^x u_0^\lambda(\theta) d\theta, \quad (2.72)$$

and  $v^\lambda$  be as in (2.4). Let  $u^\lambda = \frac{\partial v^\lambda}{\partial x}$  be the entropy solution of (1.2) in  $\Omega = \mathbb{R} \times \mathbb{R}_+$  with initial data  $u_0^\lambda$ . Assume that

$$\lambda > \max(a, m), \quad (2.73)$$

then  $\alpha$  is a point of rarefaction and  $\beta$  is the shock point.

Let

$$\begin{aligned} L_1(t) &= \alpha + f'(a)t, \\ L_2^\lambda(t) &= \alpha + f'(\lambda)t, \\ S^\lambda(t) &= \beta + \left( \frac{f(\lambda) - f(m)}{\lambda - m} \right) t. \end{aligned}$$

Let  $(x_0(\lambda), T_0(\lambda))$  be the point of intersection of  $L_2^\lambda$  and  $S^\lambda$  given by

$$\begin{aligned} T_0(\lambda) &= \frac{\beta - \alpha}{f'(\lambda) - \left( \frac{f(\lambda) - f(m)}{\lambda - m} \right)}, \\ x_0(\lambda) &= \alpha + \frac{(\beta - \alpha)f'(\lambda)}{f'(\lambda) - \left( \frac{f(\lambda) - f(m)}{\lambda - m} \right)}. \end{aligned}$$

Since  $\beta$  is the point of shock and hence from (2.26) we have

$$R^\lambda(t) = R_+(t, \beta, u_0^\lambda) = R_-(t, \beta, u_0^\lambda). \quad (2.74)$$

Then the solution  $u^\lambda$  for  $t \leq T_0(\lambda)$  is given by

$$R^\lambda(t) = S^\lambda(t). \quad (2.75)$$

$$u^\lambda(x, t) = \begin{cases} m & \text{if } x > S^\lambda(t), \\ \lambda & \text{if } L_2^\lambda(t) < x < S^\lambda(t), \\ (f')^{-1}\left(\frac{x-\alpha}{t}\right) & \text{if } L_1(t) < x < L_2^\lambda(t), \\ a & \text{if } x < L_1(t). \end{cases} \quad (2.76)$$

Define  $T_1(\lambda) > T_0(\lambda)$  be the first point of intersection of  $L_2^\lambda$  and  $R^\lambda$ . If they do not meet, then define  $T_1(\lambda) = \infty$ . Next Lemma describes the behavior of  $u^\lambda$  for  $t > T_0(\lambda)$ .

**Lemma 2.8** *Let  $\lambda$  satisfies (2.73). Then  $u^\lambda$  is given by (see Figure 11).*

(i). For  $T_0(\lambda) < t < T_1(\lambda)$ ,  $y_\pm(L_1(t), t, u_0^\lambda) = a$  and

$$u^\lambda(x, t) = \begin{cases} m & \text{if } x > R^\lambda(t), \\ f'^{-1}\left(\frac{x-\alpha}{t}\right) & \text{if } L_1(t) < x < R^\lambda(t), \\ a & \text{if } x < L_1(t). \end{cases} \quad (2.77)$$

(ii).  $t > T_1(\lambda)$ , then  $u^\lambda$  is the solution of (1.2) with initial data

$$u^\lambda(x, T_1(\lambda)) = \begin{cases} a & \text{if } x < R^\lambda(T_1(\lambda)), \\ m & \text{if } x > R^\lambda(T_1(\lambda)). \end{cases} \quad (2.78)$$

Furthermore for any compact sets  $K_1$  and  $K_2$  of  $\mathbb{R}$  with  $K = K_1 \times K_2$ ,  $\eta > 0$ ,  $T \leq T_1(\lambda)$  be bounded, then

$$\lim_{\lambda \rightarrow \infty} \inf_{(a,m) \in K} T_1(\lambda) = \infty, \quad (2.79)$$

$$f'(u^\lambda(R^\lambda(t)-, t)) = \begin{cases} f'(\lambda) & \text{if } 0 < t < T_0(\lambda), \\ \frac{R^\lambda(t)-\alpha}{t} & \text{if } T_0(\lambda) < t < T_1(\lambda). \end{cases} \quad (2.80)$$

$$\lim_{\lambda \rightarrow \infty} \inf_{\substack{(a,m) \in K \\ T_0(\lambda) \leq t \leq T}} u^\lambda(R^\lambda(t)-, t) = \infty. \quad (2.81)$$

$$\lim_{\lambda \rightarrow \infty} \inf_{\eta \leq t \leq T} R^\lambda(t) = \infty, \quad (2.82)$$



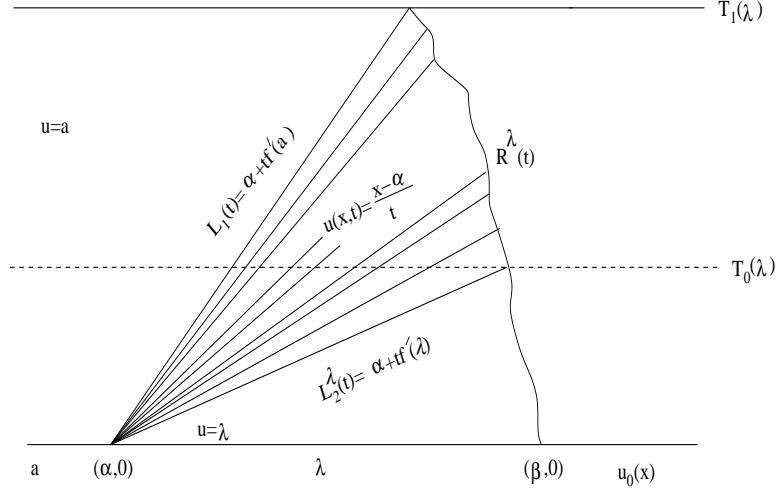


Figure 11:

**Proof.** Let  $T_0(\lambda) < t \leq T_1(\lambda)$ . Since  $v_0^\lambda(x)$  is differentiable for  $x > \beta$  and hence from (2.13) and (2.50),  $u^\lambda(x, t) = u_0(y_+(x, t, u_0^\lambda)) = m$  if  $x > R_+(t, \beta, u_0^\lambda) = R^\lambda(t)$ .

Let  $L_1(t) < x < R^\lambda(t)$ , then  $y_+(x, t, u_0^\lambda) < \beta$ . Suppose for some  $x_0 \in (L_1(t), R^\lambda(t))$ ,  $y_-(x, t, u_0^\lambda) < \alpha$ . Then for all  $x \in (L_1(t), x_0)$ ,  $y_-(x, t, u_0^\lambda) < \alpha$ ,  $u^\lambda(x, t) = u_0(y_-(x, t, u_0^\lambda)) = a$  and

$$\frac{L_1(t) - \alpha}{t} = f'(a) = f'(u^\lambda(x, t)) = \frac{x - y_-(x, t, u_0^\lambda)}{t} > \frac{L_1(t) - \alpha}{t},$$

which is a contradiction. Suppose  $y_+(x_0, t, u_0^\lambda) > \alpha$ , then for all  $x_0 < x < R^\lambda(t)$ ,  $\alpha < y_+(x, t, u_0^\lambda) < \beta$ . Since  $u_0^\lambda$  is differentiable in  $(\alpha, \beta)$  and hence from (2.13), for a.e.  $x \in (x_0, R^\lambda(t))$ ,

$$u^\lambda(x, t) = u_0^\lambda(y_+(x, t, u_0^\lambda)) = \lambda, f'(\lambda) = f'(u^\lambda(x, t)) = \frac{x - y_+(x, t, u_0^\lambda)}{t}.$$

Suppose  $x_0 < L_2^\lambda(t)$ , then for  $x_0 < x < \min(L_2^\lambda(t), R^\lambda(t))$ ,

$$f'(\lambda) = \frac{x - y_+(x, t, u_0^\lambda)}{t} < \frac{L_2^\lambda(t) - \alpha}{t} = f'(\lambda),$$

which is a contradiction. Suppose  $L_2^\lambda(t) < x_0 < R^\lambda(t)$ , then for  $x \in (x_0, R^\lambda(t))$ , characteristic  $\gamma$  at  $(x, t)$  given by  $\gamma(\theta) = y_+(x, t, u_0^\lambda) + f'(\lambda)\theta$  intersects  $S^\lambda$  at  $t_0$ , where

$$t_0 = \frac{\beta - y_+(x, t, u_0^\lambda)}{f'(\lambda) - \frac{f(\lambda) - f(m)}{\lambda - m}} < \frac{\beta - \alpha}{f'(\lambda) - \frac{f(\lambda) - f(m)}{\lambda - m}} = T_0(\lambda),$$

which contradicts NIP, since  $S^\lambda(t)$  is a characteristic for  $0 < t < T_0(\lambda)$ . Hence for  $L_1(t) < x < R^\lambda(t)$ ,  $y_+(x, t, u_0^\lambda) = y_-(x, t, u_0^\lambda) = \alpha$  and from (2.21), we have

$$f'(u^\lambda(x, t)) = \frac{x - \alpha}{t}. \quad (2.83)$$

Now letting  $x \downarrow L_1(t)$  and from (2.22) to obtain  $y_+(L_1(t), t, u_0^\lambda) = \alpha$  and  $f'(u^\lambda(L_1(t)+, t)) = \frac{L_1(t) - \alpha}{t} = f'(a)$ . This implies  $u^\lambda(L_1(t)+, t) = a$ . From RH condition across  $L_1(t)$  implies that  $u^\lambda(L_1(t)-, t) = a$ . Therefore from (2.12), (2.22), (2.23)  $y_\pm(L_1(t), t, u_0^\lambda) = a$ . This implies for  $x < L_1(t)$ ,  $y_+(x, t, u_0^\lambda) < \alpha$  and hence from (2.13),  $u^\lambda(x, t) = u_0(y_+(x, t, u_0^\lambda)) = a$ . This proves (2.77) and hence (2.78).

Let

$$\begin{aligned} y_\pm(t, \lambda) &= y_\pm(R^\lambda(t), t, u_0^\lambda), \\ y_\pm(\lambda) &= y_\pm(R^\lambda(T_1(\lambda)), T_1(\lambda), u_0^\lambda), \\ R^\lambda &= R^\lambda(T_1(\lambda)). \end{aligned}$$

Let  $T_0(\lambda) < t \leq T_1(\lambda)$  and letting  $x \uparrow R^\lambda(t)$  in (2.83) to obtain

$$\frac{R^\lambda(t) - y_-(t, \lambda)}{t} = f'(u^\lambda(R^\lambda(t)-, t)) = \frac{R^\lambda(t) - \alpha}{t}. \quad (2.84)$$

Hence  $y_-(t, \lambda) = \alpha$ . Also at  $t = T_1(\lambda)$ ,

$$f'(a) = \frac{R^\lambda - \alpha}{T_1(\lambda)} = \frac{R^\lambda - y_-}{T_1(\lambda)}. \quad (2.85)$$

$$\frac{R^\lambda(t) - y_+(t, \lambda)}{t} = \lim_{x \downarrow R^\lambda(t)} \frac{x - y_-(x, t, u_0^\lambda)}{t} \quad (2.86)$$

$$= \lim_{x \downarrow R^\lambda(t)} f'(u^\lambda(x, t)) = f'(m). \quad (2.87)$$

From (2.84) to (2.86) we can evaluate  $v^\lambda(R^\lambda(t), t)$  by

$$\begin{aligned} -(\beta - \alpha)\lambda + tf^* \left( \frac{R^\lambda(t) - \alpha}{t} \right) &= (y_+(t, \lambda) - \beta)m + tf^* \left( \frac{R^\lambda(t) - y_+(t, \lambda)}{t} \right) \\ -(\beta - \alpha)\lambda + tf^* \left( \frac{R^\lambda(t) - \alpha}{t} \right) &= m \left( \frac{y_+(t, \lambda) - R^\lambda(t)}{t} t + R^\lambda(t) - \beta \right) \\ &\quad + tf^*(f'(m)) \\ &= -tmf'(m) + m(R^\lambda(t) - \alpha) + m(\alpha - \beta) \\ &\quad + tf^*(f'(m)). \end{aligned}$$

$$\frac{(\beta - \alpha)(\lambda - m)}{t} = f^* \left( \frac{R^\lambda(t) - \alpha}{t} \right) - \frac{R^\lambda(t) - \alpha}{t} - f^*(f'(m) + mf'(m)). \quad (2.88)$$

Let  $t = T_1(\lambda)$  then  $\frac{R^\lambda - \alpha}{T_1(\lambda)} = f'(a)$  and hence the right hand side of (2.88) is bounded uniformly for  $(a, m) \in K$  and hence as  $\lambda \rightarrow \infty$ ,  $T_1(\lambda) \rightarrow \infty$ . This proves (2.79).

Observe that  $R_+(t, \alpha, u_0^\lambda) = L_2^\lambda(t)$  and  $L_2^\lambda(t) < R^\lambda(t)$  for  $0 < t < T_0(\lambda)$ . Hence for a.e  $x \in (L_2^\lambda(t), R^\lambda(t))$ ,  $y_+(x, t, u_0^\lambda) = y_-(x, t, u_0^\lambda) \in (\alpha, \beta)$  and from (2.13),

$$u^\lambda(x, t) = u_0^\lambda(y_+(x, t, u_0^\lambda)) = \lambda.$$

From this and (2.84) , (2.80) follows. Let  $T_0(\lambda) < t \leq T$ , then from superlinearity of  $f^*$ , (2.81) follows from (2.84),(2.88). Suppose  $\lim_{\lambda \rightarrow \infty} T_0(\lambda) = 0$ , and then (2.82) follows from (2.80) , (2.81). Hence assume that  $\lim_{\lambda \rightarrow \infty} T_0(\lambda) > 0$ , then if  $\eta < T_0(\lambda)$ , then (2.82) follows from (2.88). This proves the Lemma.

Next we generalize the above Lemma by replacing  $m$  by  $u_0$ . More precisely let

$$u_0^\lambda(x) = \begin{cases} a & \text{if } x < \alpha, \\ \lambda & \text{if } \alpha < x < \beta, \\ u_0(x) & \text{if } x > \beta, \end{cases} \quad (2.89)$$

and  $u^\lambda$  be the solution of (1.2) with initial data  $u_0^\lambda$ . Let

$$m_1 = \inf_{x \geq \alpha} u_0(x), m_2 = \sup_{x \geq \alpha} u_0(x). \quad (2.90)$$

For  $i = 1, 2$ , define  $u_0^{i,\lambda}$  by

$$u_0^{i,\lambda}(x) = \begin{cases} a & \text{if } x < \alpha, \\ \lambda & \text{if } \alpha < x < \beta, \\ m_i & \text{if } \beta < x, \end{cases} \quad (2.91)$$

and let  $u_i^\lambda$  be the solution of (1.2) with initial data  $u_0^{i,\lambda}$ . Let  $L_1(t), L_2^\lambda(t)$  be as in Lemma (2.8), then

**Lemma 2.9** *Let  $T > 0$  be fixed, then there exist  $\lambda_0 = \lambda_0(m_1, m_2, a, t)$  such that for  $\lambda \geq \lambda_0, 0 < t \leq T$ ,*

$$R_-(t, \beta, u_0^\lambda) = R_+(t, \beta, u_0^\lambda). \quad (2.92)$$

and denote  $R(\lambda, t) = R_-(t, \beta, u_0^\lambda)$ , then

- (i).  $t \rightarrow R(\lambda, t)$  is a strictly increasing function.
- (ii).  $\lambda \rightarrow R(\lambda, t)$  is a strictly increasing function and

$$\lim_{\lambda \rightarrow \infty} R(\lambda, T) = \infty. \quad (2.93)$$

Let  $T_0(\lambda)$  be the first point of intersection of  $L_2^\lambda(t)$  and  $R(\lambda, t)$ . Then

$$u^\lambda(x, t) = \begin{cases} a & \text{if } x < L_1(t) \\ \lambda & \text{if } L_2^\lambda(t) < x < R(\lambda, t), \quad 0 < t < T_0(\lambda). \end{cases} \quad (2.94)$$

**Proof.** Let  $q_0$  be as in (2.61), then for  $\lambda > q_0$ , from Lemma (2.5) we have for  $i = 1, 2$ ,

$$R_-(t, \beta, u_0^\lambda) = R_+(t, \beta, u_0^\lambda), \quad (2.95)$$

$$R_-(t, \beta, u_0^{i,\lambda}) = R_+(t, \beta, u_0^{i,\lambda}) \quad (2.96)$$

and denote  $R_i(\lambda, t) = R_-(t, \beta, u_0^{i,\lambda})$ . Since  $u_0^{1,\lambda} \leq u_0^\lambda \leq u_0^{2,\lambda}$ , hence from (2.30)

$$R_1(\lambda, t) \leq R(\lambda, t) \leq R_2(\lambda, t). \quad (2.97)$$

Next we obtain a bound on  $u^\lambda(R(\lambda, t)+, t)$ . For this let  $\bar{u}(x, t)$  be the solution of (1.2) with initial data  $\bar{u}_0(x)$  defined by

$$\bar{u}_0(x) = \begin{cases} \min(a, m_1) & \text{if } x < \beta, \\ u_0(x) & \text{if } x > \beta, \end{cases}$$

then for  $\lambda > m$ ,  $\bar{u}_0(x) \leq u_0^{1,\lambda}(x) \leq u_0^\lambda(x)$  and hence  $\bar{u}(x, t) \leq u^\lambda(x, t)$  and  $R_+(t, \beta, \bar{u}_0) \leq R(\lambda, t)$ . Since for  $y > \beta$ ,  $\int_\beta^y \bar{u}_0(\theta) d\theta = \int_\beta^y u_0^\lambda(\theta) d\theta$  and hence from (2.50) we have for  $x > R(\lambda, t)$ ,

$$\begin{aligned} V^\lambda(x, t) &= \inf_{y \geq \beta} \left\{ \int_\beta^y u_0^\lambda(\theta) d\theta + t f^* \left( \frac{x-y}{t} \right) \right\} \\ &= \inf_{y \geq \beta} \left\{ \int_\beta^y \bar{u}_0(\theta) d\theta + t f^* \left( \frac{x-y}{t} \right) \right\} \\ &= V(x, t), \end{aligned}$$

where  $u^\lambda = \frac{\partial V^\lambda}{\partial x}$  and  $\bar{u} = \frac{\partial V}{\partial x}$ . Hence for  $x > R(\lambda, t)$ ,

$$u^\lambda(x, t) = \bar{u}(x, t). \quad (2.98)$$

Therefore

$$\begin{aligned} |u^\lambda(R(\lambda, t)+, t)| &\leq \|\bar{u}\|_\infty \\ &\leq \max(m_2, a). \end{aligned} \quad (2.99)$$

For  $i = 1, 2$ , let  $T_{i,0}(\lambda)$  be the first intersection point of  $L_2^\lambda(t)$  and  $R_i(\lambda, t)$  and  $T_{i,1}(\lambda) > T_{i,0}(\lambda)$  be the points of intersections of  $L_1(t)$  and  $R_i(\lambda, t)$ . Then from Lemma (2.8), we can choose  $\lambda_0 \geq q_0 + \|\bar{u}\|_\infty$  such that for all  $\lambda \geq \lambda_0$ ,  $f'(\lambda) > 0$ ,  $f(\lambda) > f(\|\bar{u}\|_\infty)$  and

$$R_1(\lambda, T) > L_1(t), T_{1,1}(\lambda) > T \quad (2.100)$$

$$\inf_{T_{1,0}(\lambda) \leq t \leq T} f^{*'} \left( \frac{R_1(\lambda, t) - \alpha}{t} \right) = \inf_{T_{1,0}(\lambda) \leq t \leq T} u^{1,\lambda}(R_1(\lambda, t)-, t) > \lambda_0. \quad (2.101)$$

From (2.82) and (2.97) we have

$$\lim_{\lambda \rightarrow \infty} R(\lambda, T) \geq \lim_{\lambda \rightarrow \infty} R_1(\lambda, T) = \infty.$$

This proves (2.93).

Next imitating the proof as in Lemma (2.8) and from (2.98) we have for  $0 < t < T$ ,

$$u^\lambda(x, t) = \begin{cases} \bar{u}(x, t) & \text{if } x > R(\lambda, t), \\ (f')^{-1} \left( \frac{x - \alpha}{t} \right) & \text{if } t > T_0(\lambda), L_1(t) < x < R(\lambda, t), \\ \lambda & \text{if } 0 < t < T_0(\lambda), L_2^\lambda(t) < x < R(\lambda), \\ a & \text{if } x < L_1(t). \end{cases} \quad (2.102)$$

Let  $0 < t < T_0(\lambda)$  then from (2.99) and the choice of  $\lambda_0$ , we have for a.e.  $t$ ,

$$\begin{aligned} \frac{d}{dt} R(\lambda, t) &= \frac{f(u^\lambda(R(\lambda, t)-, t)) - f(u^\lambda(R(\lambda, t)+, t))}{u^\lambda(R(\lambda, t)-, t) - u^\lambda(R(\lambda, t)+, t)} \\ &= \frac{f(\lambda) - f(u^\lambda(R(\lambda, t)+, t))}{\lambda - u^\lambda(R(\lambda, t)+, t)} > 0. \end{aligned}$$

Let  $T_0(\lambda) < t \leq T$ , then from (2.97),  $T_{1,0}(\lambda) \leq T_0(\lambda)$ . Hence from (2.102), (2.101)

$$\begin{aligned} u^\lambda(R(\lambda, t)-, t) &= f^{*'} \left( \frac{R(\lambda, t) - \alpha}{t} \right) \\ &\geq f^{*'} \left( \frac{R_1(\lambda, t) - \alpha}{t} \right) \\ &= u^{1,\lambda}(R_1(\lambda, t)-, t) \\ &> \lambda_0. \end{aligned}$$

Since  $f'(\lambda) > 0$  for  $\lambda \geq \lambda_0$ , hence

$$f(u^\lambda(R(\lambda, t)-, t)) \geq f(\lambda_0) > f(\|\bar{u}\|_\infty).$$

Therefore from (2.98), (2.99) we have for  $T_0(\lambda) < t \leq T$ .

$$\begin{aligned} \frac{d}{dt} R(\lambda, t) &= \frac{f(u^\lambda(R(\lambda, t)-, t)) - f(u^\lambda(R(\lambda, t)+, t))}{u^\lambda(R(\lambda, t)-, t) - u^\lambda(R(\lambda, t)+, t)} \\ &= \frac{f(u^\lambda(R(\lambda, t)-, t)) - f(\bar{u}(R(\lambda, t)+, t))}{u^\lambda(R(\lambda, t)-, t) - \bar{u}(R(\lambda, t)+, t)} \\ &> 0. \end{aligned}$$

This proves that  $t \rightarrow R(\lambda, t)$  is a strictly increasing function.

**Claim:**  $R(\lambda, t) \leq L_2^\lambda(t)$  for  $t > T_0(\lambda)$ .

Suppose for some  $t_0 > T_0(\lambda)$ ,  $R(\lambda, t_0) > L_2^\lambda(t_0)$ , then for a.e  $x \in (L_2^\lambda(t_0), R(\lambda, t_0))$ ,  $y_+(x, t, u_0^\lambda) \in (\alpha, \beta)$  and hence from (2.13) and differentiability of  $u_0^\lambda$  in  $(\alpha, \beta)$  gives  $u(x, t_0) = \lambda$  and  $f'(\lambda) = \frac{x - y_+(x, t_0, u_0^\lambda)}{t_0}$ . Hence the characteristic line  $r(\theta)$  at  $(x, t_0)$  is parallel to  $L_2^\lambda$  and  $r(\theta) \geq L_2^\lambda(\theta)$  for  $\theta \in [0, t_0]$ . Since  $t \rightarrow R(\lambda, t)$  is an increasing function for  $t \in (0, T_1(\lambda))$  and  $T_0(\lambda) < t_0$ , hence  $R(\lambda, T_0(\lambda)) < x$ . Furthermore  $y_+(R(\lambda, T_0(\lambda)), T_0(\lambda), u_0^\lambda) \geq \beta$ . Hence the characteristic line at  $(R(\lambda, T_0(\lambda)), T_0(\lambda))$  intersect  $r$  which contradicts NIP. This proves the claim. Hence for  $t \geq T_0(\lambda)$ ,

$$\frac{R(\lambda, t) - \alpha}{t} \leq f'(\lambda). \quad (2.103)$$

Let  $\lambda_0 \leq \lambda_1 < \lambda_2$ , then  $u_0^{\lambda_1} \leq u_0^{\lambda_2}$  and hence  $R(\lambda_1, t) \leq R(\lambda_2, t)$  and for a.e  $x$ ,  $y_\pm(x, t, u_0^{\lambda_1}) \geq y_\pm(x, t, u_0^{\lambda_2})$ . Suppose for some  $0 < t_0 < T$ ,  $R = R(\lambda_1, t_0) = R(\lambda_2, t_0)$ . From (2.98) at  $x = R$ , we have  $\alpha \leq y_-(R, t_0, u_0^{\lambda_2}) \leq y_-(R, t_0, u_0^{\lambda_1}) < \beta$ , and  $u^{\lambda_1}(R+, t_0) = \bar{u}(R+, t_0) = u^{\lambda_2}(R+, t_0)$ . Hence  $y_+(R, t_0, u_0^{\lambda_1}) = y_+(R, t_0, u_0^{\lambda_2})$ .

Let for  $i = 1, 2$ ,  $y = y_+(R, t_0, u_0^{\lambda_i})$ ,  $y_i = y_-(R, t_0, u_0^{\lambda_i})$  and  $V_0^{\lambda_i}(y) = \int_\beta^y u_0^{\lambda_i}(\theta) d\theta$ , then  $V_0^{\lambda_1}(y) = V_0^{\lambda_2}(y)$  for  $y \geq \beta$ . Hence from (2.4) we have

$$\begin{aligned} \lambda_2(y_2 - \beta) + t_0 f^* \left( \frac{R - y_2}{t_0} \right) &= V_0^{\lambda_2}(y_2) + t f^* \left( \frac{R - y_2}{t_0} \right) \\ &= V_0^{\lambda_2}(y) + t f^* \left( \frac{R - y}{t_0} \right) \\ &= V_0^{\lambda_1}(y) + t f^* \left( \frac{R - y}{t_0} \right) \\ &= V_0^{\lambda_1}(y_1) + t f^* \left( \frac{R - y_1}{t_0} \right) \\ &= \lambda_1(y_1 - \beta) + t_0 f^* \left( \frac{R - y_1}{t_0} \right). \end{aligned}$$

Let  $f'(\theta_i) = \frac{R - y_i}{t_0}$ , then  $R = f'(\theta_i)t_0 + y_i$  and since  $y_2 \leq y_1$  implies that  $f'(\theta_2) \geq f'(\theta_1)$ , hence  $\theta_2 \geq \theta_1$ . Substituting this in the above expression and using  $f^*(f'(p)) = pf'(p) - f(p)$  to obtain

$$(R - t_0 f'(\theta_2))\lambda_2 + t_0 f^*(f'(\theta_2)) = (R - t_0 f'(\theta_1))\lambda_1 + t_0 f^*(f'(\theta_1)) + \beta(\lambda_2 - \lambda_1)$$

$$R = \beta + \frac{t_0}{(\lambda_2 - \lambda_1)} [(\lambda_2 - \theta_2)f'(\theta_2) - (\lambda_1 - \theta_1)f'(\theta_1)] + \left( \frac{f(\theta_2) - f(\theta_1)}{\lambda_2 - \lambda_1} \right) t_0.$$

That is for  $i = 1, 2$ ,

$$y_i = \beta + \frac{t_0}{(\lambda_2 - \lambda_1)} [(\lambda_2 - \theta_2)f'(\theta_2) - (\lambda_1 - \theta_1)f'(\theta_1)] + t_0 \left[ \frac{f(\theta_2) - f(\theta_1)}{\lambda_2 - \lambda_1} - f'(\theta_i) \right]. \quad (2.104)$$

**Case (i) :** Let  $y_2 = y_1$ . Then  $\theta_2 = \theta_1$  and hence from (2.104),  $\beta = y_1 < \beta$  which is a contradiction.

**Case (ii):** Let  $\alpha < y_2 < y_1$ .

Since  $V_0^{\lambda_i}$  is differentiable for  $y \in (\alpha, \beta)$  and hence from (2.13) , (2.23), we have  $f'(\lambda_i) = \frac{R-y_i}{t_0}$ . Therefore from (2.104) and from strict convexity of  $f$  we have

$$y_1 = \beta + t_0 \left[ \frac{f(\lambda_2) - f(\lambda_1)}{\lambda_2 - \lambda_1} - f'(\lambda_1) \right] > \beta.$$

which is a contradiction.

**Case(iii):** Let  $\alpha = y_2 < y_1$ .

Since  $y_1 > \alpha$ , hence  $f'(\theta_1) = \frac{R-y_1}{t_0} = f'(\lambda_1)$  and  $\frac{R-\alpha}{t_0} = f'(\theta_2)$ . From (2.103),  $f'(\theta_2) \leq f'(\lambda_2)$  and hence  $\lambda_2 \geq \theta_2$ . Since  $\lambda_1 \geq \lambda_0$  and hence  $f'(\theta_2) \geq f'(\lambda_1) > 0$ . From (2.104),  $\theta_1 = \lambda_1$  and convexity of  $f$  we have

$$\begin{aligned} 0 > \frac{(\lambda_2 - \lambda_1)(y_1 - \beta)}{t_0} &= (\lambda_2 - \theta_2)(f'(\theta_2) - f'(\lambda_1)) + f(\theta_2) - f(\lambda_1) \\ &\quad - (\theta_2 - \lambda_1)f'(\lambda_1) \\ &> 0, \end{aligned}$$

which is a contradiction. This proves  $\lambda \rightarrow R(\lambda, t)$  is a strictly increasing function for  $\lambda \geq \lambda_0$  and  $0 < t \leq T$ . This proves the Lemma.

Next we consider the variation from the right, Let  $u^\mu$  be the solution of (1.2) with initial data  $u_0^\mu$  given by

$$u_0^\mu = \begin{cases} u_0(x) & \text{if } x < \alpha, \\ \mu & \text{if } \alpha < x < \beta, \\ a & \text{if } x > \beta. \end{cases}$$

We state the following Lemma without proof since the proof follows exactly as that of Lemma 2.9.

Define

$$L_1(t) = \beta + f'(a)t, L_2^\mu(t) = \beta + f'(\mu)t.$$

**Lemma 2.10** *There exist  $\mu_1 = \mu_1(m_1, m_2, a)$  such that for  $\mu < \mu_1, t > 0$ ,*

$$R_-(t, \alpha, u_0^\mu) = R_+(t, \alpha, u_0^\mu), \quad (2.105)$$

and denote  $R(\mu, t) = R_-(t, \alpha, u_0^\mu)$ . Let  $T_0(\mu) > 0$  be the first point of intersection of  $R(\mu, t)$  and  $L_2^\mu(t)$  and  $T_1(\mu) > T_0(\mu)$  be the first point of intersection of  $R(\mu, t)$  and  $L_1(t)$ . Then

$$\lim_{\mu \rightarrow -\infty} T_1(\mu) = \infty. \quad (2.106)$$

For  $0 < t < T_1(\mu)$ ,

$$u^\mu(x, t) = \begin{cases} a & \text{if } x > L_1(t), \\ (f')^{-1}\left(\frac{x-\beta}{t}\right) & \text{if } T_0(\mu) < t < T_1(\mu), \\ & R(\mu, t) < x < L_1(t), \\ \mu & \text{if } 0 < t < T_0(\mu), \\ & R(\mu, t) < x < L_2^\mu(t). \end{cases}$$

Furthermore let  $T > 0$  be fixed, then there exist  $\mu_0 = \mu_0(T, \mu_1) < \mu_1$  such that

(i).  $\mu \rightarrow R(\mu, t)$  is a strictly increasing function for  $0 < t \leq T$  and

$$\lim_{\mu \rightarrow -\infty} R(\mu, t) = -\infty. \quad (2.107)$$

(ii). For  $0 < t < T_1(\mu)$ ,  $t \rightarrow R(\mu, t)$  is a strictly decreasing function of  $t$ .

Next we study the interaction of  $R_\pm$  with varying parameters in the data. For this first we need the following elementary results.

Let  $B_1, B_2, \mu_0 < \lambda_0$ ,  $L, R \in C([0, \infty])$ , be given and for  $\lambda \geq \lambda_0, \mu \leq \mu_0$ ,  $L$  and  $R$  satisfies the following hypothesis,

(H<sub>1</sub>).  $\lambda \mapsto L(t, \lambda)$ ,  $\mu \mapsto R(t, \mu)$  are strictly increasing functions such that for all  $\lambda \geq \lambda_0$ ,  $\mu \leq \mu_0$ ,

$$L(0, \lambda) = B_1, \quad R(0, \mu) = B_2, \quad (2.108)$$

and for any  $0 < \alpha < \beta$ ,

$$\lim_{\lambda \rightarrow \infty} \inf_{t \in [\alpha, \beta]} L(t, \lambda) = \infty, \quad \lim_{\mu \rightarrow -\infty} \sup_{t \in [\alpha, \beta]} R(t, \mu) = -\infty. \quad (2.109)$$

(H<sub>2</sub>). For  $\lambda \geq \lambda_0, \mu \leq \mu_0$ ,  $t \mapsto L(t, \lambda)$ , is a strictly increasing function and  $t \mapsto R(t, \mu)$  is a strictly decreasing function.

Let  $I = [\lambda_0, \infty) \times (-\infty, \mu_0]$  and define  $x_0(t), y_0(t), \lambda(x, t), \mu(y, t), \delta(\lambda, \mu), c(\lambda, \mu)$  as follows:

$$x_0(t) = L(t, \lambda_0), \quad y_0(t) = R(t, \mu_0) \quad (2.110)$$

$$L(t, \lambda(x, t)) = x, \quad R(t, \mu(y, t)) = y \quad (2.111)$$

$$L(\delta(\lambda, \mu), \lambda) = R(\delta(\lambda, \mu), \mu) = c(\lambda, \mu), \quad (2.112)$$

then we have the following

**Lemma 2.11**



1.  $x_0$  is a strictly increasing continuous and  $y_0$  is a strictly decreasing function satisfying

$$(x_0(0), y_0(0)) = (B_1, B_2). \quad (2.113)$$

2. For  $x \geq x_0(t), y \leq y_0(t), (\lambda(x, t), \mu(y, t)) \in I, x \mapsto \lambda(x, t), t \mapsto \mu(y, t)$  are strictly increasing functions and  $t \mapsto \lambda(x, t), y \mapsto \mu(y, t)$  are strictly decreasing continuous functions in  $(0, \infty)$ . Also for  $x > B_1, y < B_2$

$$\lim_{t \rightarrow 0} (\lambda(x, t), \mu(y, t)) = (\infty, -\infty). \quad (2.114)$$

3. Let  $B_1 < B_2$  and  $(\lambda, \mu) \in I$ . Then  $\delta(\lambda, \mu)$  exist and is a continuous function. Furthermore  $\lambda \rightarrow \delta(\lambda, \mu)$  is an decreasing function and  $\mu \mapsto \delta(\lambda, \mu)$  is an increasing function and

$$\lim_{\lambda \rightarrow \infty} \delta(\lambda, \mu) = \lim_{\mu \rightarrow -\infty} \delta(\lambda, \mu) = 0 \quad (2.115)$$

$$\lim_{\mu \rightarrow -\infty} c(\lambda, \mu) = B_1, \quad \lim_{\lambda \rightarrow \infty} c(\lambda, \mu) = B_2. \quad (2.116)$$

**Proof.**

1. Follows from  $(H_1)$ .
2. From (2.109) for  $t > 0, L(t, \cdot) : [\lambda_0, \infty) \rightarrow [x_0(t), \infty)$  is a homeomorphism and hence  $\lambda(x, t)$  exist and  $x \mapsto \lambda(x, t)$  is a strictly increasing function. Let  $t_1 < t_2$  and suppose  $\lambda(x, t_1) \leq \lambda(x, t_2)$ , then

$$x = L(t_1, \lambda(x, t_1)) \leq L(t_1, \lambda(x, t_2)) < L(t_2, \lambda(x, t_2)) = x,$$

which is a contradiction. Hence  $t \mapsto \lambda(x, t)$  is a strictly decreasing function. Let  $(x_n, t_n) \rightarrow (x, t), \lambda(x_n, t_n) \rightarrow \lambda$ , then

$$x = \lim_{n \rightarrow \infty} L(t_n, \lambda(x_n, t_n)) = L(t, \lambda),$$

and hence  $\lambda = \lambda(x, t)$ . This proves the continuity of  $\lambda(x, t)$ . Suppose as  $t_n \rightarrow 0, \{\lambda(x, t_n)\}$  is bounded. Then for a subsequence still denote by  $n$  such that  $\lambda(x, t_n) \rightarrow \lambda$  as  $n \mapsto \infty$ . Therefore by continuity of  $L$  and (2.108)

$$B_1 < x = \lim_{n \rightarrow \infty} L(t_n, \lambda(x, t_n)) = L(0, \lambda) = B_1,$$

which is a contradiction. Hence  $\lambda(x, t) \rightarrow \infty$  as  $t \rightarrow 0$ . Similarly for  $\mu(y, t)$  and this proves (2).

3. For  $(\lambda, \mu) \in I, t \mapsto L(t, \lambda) \geq B_1$  and is a strictly increasing function and  $t \mapsto R(t, \mu) \leq B_2$  is a strictly decreasing function. Hence there exist a unique  $\delta(\lambda, \mu)$  satisfying (2.112) and  $B_1 \leq c(\lambda, \mu) \leq B_2$  and continuity follows from the uniqueness of  $\delta(\lambda, \mu)$ .

Let  $\lambda_1 < \lambda_2$  and  $\delta(\lambda_1, \mu) \leq \delta(\lambda_2, \mu)$ . Then

$$\begin{aligned} R(\delta(\lambda_1, \mu), \mu) &= L(\delta(\lambda_1, \mu), \lambda_1) \leq L(\delta(\lambda_2, \mu), \lambda_1) \\ &< L(\delta(\lambda_2, \mu), \lambda_2) \\ &= R(\delta(\lambda_2, \mu), \mu) \end{aligned}$$

and hence  $\delta(\lambda_2, \mu) < \delta(\lambda_1, \mu)$  which is a contradiction. Suppose  $\lim_{\lambda \rightarrow \infty} \delta(\lambda, \mu) = \delta_0 > 0$ , then from (2.109),

$$\infty = \lim_{\lambda \rightarrow \infty} L(\delta(\lambda, \mu), \lambda) = \lim_{\delta(\lambda, \mu) \rightarrow \delta_0} R(\delta(\lambda, \mu), \mu) = R(\delta_0, \mu) < \infty,$$

which is a contradiction hence  $\delta_0 = 0$  and

$$\begin{aligned} \lim_{\lambda \rightarrow \infty} c(\lambda, \mu) &= \lim_{\lambda \rightarrow \infty} L(\delta(\lambda, \mu), \lambda) \\ &= \lim_{\delta(\lambda, \mu) \rightarrow 0} R(\delta(\lambda, \mu), \mu) \\ &= B_2, \end{aligned}$$

similarly for  $\mu \rightarrow \delta(\lambda, \mu)$ . This proves (3) and hence the Lemma.

**Corollary 2.12** *Let  $\delta_0 > 0$ , then there exist  $\lambda_1 \geq \lambda_0, \mu_1 \leq \mu_0$  such that for all  $\lambda \geq \lambda_1, \mu \leq \mu_1$ ,*

$$\delta(\lambda, \mu) \leq \delta_0. \quad (2.117)$$

**Proof.** Since  $\delta(\lambda, \mu_0) \rightarrow 0$  as  $\lambda \rightarrow \infty$ , hence choose  $\lambda_1 \geq \lambda_0$  such that  $\delta(\lambda_1, \mu_0) \leq \delta_0$ . Let  $\mu_1 = \mu_0$ , then for  $\lambda \geq \lambda_1, \mu \leq \mu_1$ , we have,

$$\delta(\lambda, \mu) \leq \delta(\lambda_1, \mu) \leq \delta(\lambda_1, \mu_1) \leq \delta_0.$$

This proves the Corollary.

Let  $T > 0$  and  $A_1 < B_1 \leq C \leq B_2 < A_2$  and for  $i = 1, 2$ , define  $a_i, l_i, 0 < \delta_0 < T$  by

$$\begin{aligned} f'(a_i) &= \frac{C - A_i}{T} \\ l_i(t) &= A_i + t f'(a_i) \\ \delta_0 &= \min\{l_1(B_1), l_2(B_2)\}. \end{aligned}$$

Let  $u_1^\lambda$  and  $u_2^\mu$  be solutions of (1.2) with respective initial data  $u_0^\lambda, u_0^\mu$  given by

$$u_0^{1,\lambda}(x) = \begin{cases} a_1 & \text{if } x < A_1, \\ \lambda & \text{if } A_1 < x < B_1, \\ u_0(x) & \text{if } B_1 < x < B_2, \\ \theta_f & \text{if } x > B_2. \end{cases} \quad (2.118)$$

$$u_0^{2,\mu}(x) = \begin{cases} \theta_f & \text{if } x < B_1, \\ u_0(x) & \text{if } B_1 < x < B_2, \\ \mu & \text{if } B_2 < x < A_2, \\ a_2 & \text{if } x > A_2. \end{cases} \quad (2.119)$$

From Lemma (2.9) and (2.10) we can choose  $\lambda_0 = \lambda_0(\|u_0\|_\infty)$ ,  $\mu_0 = \mu_0(\|u_0\|_\infty)$  such that for all  $\lambda \geq \lambda_0$ ,  $\mu \leq \mu_0$ ,  $t > 0$ ,

$$L(t, \lambda) = R_-(t, B_1, u_0^{1,\lambda}) = R_+(t, B_1, u_0^{1,\lambda}) \quad (2.120)$$

$$R(t, \mu) = R_-(t, B_2, u_0^{2,\mu}) = R_+(t, B_2, u_0^{2,\mu}), \quad (2.121)$$

and for  $0 < t \leq T$ ,  $L$  and  $R$  satisfies the hypothesis  $(H_1)$ ,  $(H_2)$  of Lemma (2.11). Let  $(C(\lambda, \mu), \delta(\lambda, \mu))$  be the point of intersection of  $L(t, \lambda)$  and  $R(t, \mu)$  as defined in (2.112). From Corollary (2.12), choose  $\lambda_1 \geq \lambda_0$ ,  $\mu_1 \leq \mu_0$  such that for all  $\lambda \geq \lambda_1$ ,  $\mu \leq \mu_1$

$$\delta(\lambda, \mu) < \delta_0. \quad (2.122)$$

**Lemma 2.13** *With the above notation and  $u(x, t, \lambda, \mu)$  be the solution of (1.2) with initial condition  $u_0^{\lambda,\mu}$  given by*

$$u_0^{\lambda,\mu}(x) = \begin{cases} a_1 & \text{if } x < A_1, \\ \lambda & \text{if } A_1 < x < B_1, \\ u_0 & \text{if } B_1 < x < B_2, \\ \mu & \text{if } B_2 < x < A_2, \\ a_2 & \text{if } x > A_2. \end{cases} \quad (2.123)$$

then for  $0 < t < \delta(\lambda, \mu)$ ,

$$u_1^\lambda(x, t) = u_2^\mu(x, t) \quad \text{if } L(t, \lambda) < x < R(t, \mu), \quad (2.124)$$

$$u(x, t, \lambda, \mu) = \begin{cases} u_1^\lambda(x, t) & \text{if } x < L(t, \lambda), \\ u_1^\lambda(x, t) & \text{if } L(t, \lambda) < x < R(t, \mu), \\ u_2^\mu(x, t) & \text{if } x > R(t, \mu). \end{cases} \quad (2.125)$$

**Proof.** Let  $\gamma = \frac{A_1+A_2}{2}$  and define  $v_0^{1,\lambda}(x) = \int_\gamma^x u_0^{1,\lambda}(\theta)d\theta$ ,  $v_0^{2,\mu}(x) = \int_\gamma^x u_0^{2,\mu}(\theta)d\theta$ ,  $V_0^{\lambda,\mu}(x) = \int_\gamma^x u_0^{\lambda,\mu}(\theta)d\theta$ . Then for  $x \in [B_1, B_2]$ ,

$$v_0^{1,\lambda}(x) = v_0^{2,\mu}(x) = \int_{\frac{A_1+A_2}{2}}^x u_0(\theta)d\theta. \quad (2.126)$$

$$v_0^{\lambda,\mu}(x) = \begin{cases} v_0^{1,\lambda}(x) & \text{if } x < B_1, \\ v_0^{2,\mu}(x) & \text{if } x > B_2. \end{cases} \quad (2.127)$$

**Claim:** Let  $v^{1,\lambda}, v^{2,\mu}$  be the corresponding value functions defined in (2.4). Then

$$v^{1,\lambda}(x, t) = \inf_{y \in [B_1, B_2]} \left\{ v_0^{1,\lambda}(y) + t f^* \left( \frac{x-y}{t} \right) \right\}, \text{ if } L(t, \lambda) < x < B_2 \quad (2.128)$$

$$v^{2,\mu}(x, t) = \inf_{y \in [B_1, B_2]} \left\{ v_0^{2,\mu}(y) + t f^* \left( \frac{x-y}{t} \right) \right\}, \text{ if } B_1 < x < R(t, \lambda). \quad (2.129)$$

Let  $L(t, \lambda) < x < B_2$ , then  $y_{\pm}(x, t, u_0^{1,\lambda}) > B_1$ . Suppose for some  $x_0 \in (L(t, \lambda), B_2)$ ,  $y_+(x_0, t, u_0^{1,\lambda}) > B_2$ . Since  $v_0^{1,\lambda}$  is differentiable in  $(B_2, \infty)$  and hence from (2.13) for a.e.  $x \in (x_0, B_2)$ ,  $u^{1,\lambda}(x, t) = \frac{\partial v^{1,\lambda}}{\partial x}(x, t) = \theta_f$  and  $0 = f'(\theta_f) = \frac{x-y_+(x, t, u_0^{1,\lambda})}{t}$ . Hence  $B_2 > x = y_+(x, t, u_0^{1,\lambda}) > B_2$ , which is a contradiction. Therefore  $y_{\pm}(x, t, u_0^{1,\lambda}) \in [B_1, B_2]$  and hence (2.128) follows. Similarly (2.129) holds. This proves the claim.

From (2.126), (2.128), (2.129), for  $L(t, \lambda) < x < R(t, \mu)$ ,  $v^{1,\lambda}(x, t) = v^{2,\mu}(x, t)$  and hence for a.e.  $x$ ,  $u^{1,\lambda}(x, t) = \frac{\partial v^{1,\lambda}}{\partial x}(x, t) = \frac{\partial v^{2,\mu}}{\partial x}(x, t) = u^{2,\mu}(x, t)$ . This proves (2.124). In view of (2.14), RHS of (2.125) is a solution of (1.2) with initial data  $u_0^{\lambda, \mu}$ . Hence from uniqueness of solutions (2.125) follows. This proves the Lemma.

As an immediate consequence of Lemma (2.13) and (2.27), (2.120), (2.121) we have

**Corollary 2.14** *Let  $\lambda \geq \lambda_1, \mu \leq \mu_1$ , then*

$$\begin{aligned} R_{\pm}(t, B_1, u_0^{\lambda, \mu}) &= L(t, \lambda) \quad 0 < t < \delta(\lambda, \mu), \\ R_{\pm}(t, B_2, u_0^{\lambda, \mu}) &= R(t, \mu) \quad 0 < t < \delta(\lambda, \mu), \\ R_{\pm}(t, B_1, u_0^{\lambda, \mu}) &= R_{\pm}(t, B_2, u_0^{\lambda, \mu}), \quad t \geq \delta(\lambda, \mu). \end{aligned}$$

Furthermore, denote  $S(t, \lambda, \mu) = R_+(t, B_1, u_0^{\lambda, \mu})$  for  $t > \delta(\lambda, \mu)$ , then

$$u(x, t, \lambda, \mu) = \begin{cases} u^{1,\lambda}(x, t) & \text{if } x < S(t, \lambda, \mu), \\ u^{2,\mu}(x, t) & \text{if } x > S(t, \lambda, \mu), \end{cases} \quad (2.130)$$

and  $(t, \lambda, \mu) \mapsto S(t, \lambda, \mu)$  is continuous.

**Proof.** Let  $(t_k, \lambda_k, \mu_k) \rightarrow (t, \lambda, \mu)$ . From lemma (2.11),  $\delta(\lambda_k, \mu_k) \rightarrow \delta(\lambda, \mu)$  and hence for  $t > \delta(\lambda, \mu)$

$$\begin{aligned} |S(t_k, \lambda_k, \mu_k) - S(t, \lambda, \mu)| &\leq |S(t_k, \lambda_k, \mu_k) - S(t, \lambda_k, \mu_k)| \\ &\quad + |S(t, \lambda_k, \mu_k) - S(t, \lambda, \mu)|. \end{aligned}$$

From (4) of Lemma (2.2) and from (3) of Lemma (2.4), the right hand side tends to zero as  $k \rightarrow \infty$ . For  $x < S(t, \lambda, \mu)$ ,  $y_{\pm}(x, t, u_0^{\lambda, \mu}) < B_1$  and hence from (2.127),  $v^{\lambda, \mu}(x, t) = v^{1,\lambda}(x, t)$ , where  $\frac{\partial v^{\lambda, \mu}}{\partial x} = u(x, t, \lambda, \mu)$ , hence  $u(x, t, \lambda, \mu) = \frac{\partial v^{1,\lambda}}{\partial x}(x, t) = u^{1,\lambda}(x, t)$ . Similarly for  $x > S(t, \lambda, \mu)$ ,  $u(x, t, \lambda, \mu) = u^{2,\mu}(x, t)$ , this proves (2.125) and hence the Lemma.

**Lemma 2.15** *Let  $\lambda \geq \lambda_1, \mu \leq \mu_1$  and  $\delta(\lambda, \mu) < t_0 \leq T$ , then*

(i). Suppose  $l_1(t_0) = S(t_0, \lambda, \mu)$ . Then for all  $t_0 < t < T$ ,

$$S(t, \lambda, \mu) < l_1(t). \quad (2.131)$$

$$u(x, t, \lambda, \mu) = \begin{cases} a_2 & \text{if } 0 < t < T, x > l_2(t) \\ a_1 & \text{if } x < \min(l_1(t), S(t, \lambda, \mu)). \end{cases} \quad (2.132)$$

(ii). Suppose  $l_2(t_0) = S(t_0, \lambda, \mu)$ . Then for all  $t_0 < t < T$ ,

$$S(t, \lambda, \mu) > l_2(t). \quad (2.133)$$

$$u(x, t, \lambda, \mu) = \begin{cases} a_1 & \text{if } 0 < t < T, x < l_1(t), \\ a_2 & \text{if } x > \max(l_2(t), S(t, \lambda, \mu)). \end{cases} \quad (2.134)$$

Furthermore there exist  $\lambda$  and  $\mu$  such that  $S(T, \lambda, \mu) = C$ , for  $0 < t < T$ ,  $u$  satisfies

$$u(x, t, \lambda, \mu) = \begin{cases} a_1 & \text{if } x < l_1(t), \\ a_2 & \text{if } x > l_2(t). \end{cases} \quad (2.135)$$

**Proof.** (See Figure 12) Let  $g(t) = \min(l_1(t), S(t, \lambda, \mu))$ . Then we claim that for all  $x < g(t)$ ,

$$u(x, t, \lambda, \mu) = a_1. \quad (2.136)$$

Suppose  $x < l_1(t) \leq S(t, \lambda, \mu)$ , then from (2.130), (2.94) we have  $u(x, t, \lambda, \mu) = u^{1,\lambda}(x, t) = a_1$ . Hence assume that  $S(t, \lambda, \mu) < l_1(t)$ . Suppose there exist  $x_0 < S(t, \lambda, \mu)$  such that  $y_+(x_0, t, u_0^{\lambda,\mu}) > A_1$ , then for all  $x \in (x_0, S(t, \lambda, \mu))$ ,  $A_1 < y_+(x, t, u_0^{\lambda,\mu}) < B_1$ . Since  $u_0^{\lambda,\mu}$  is differentiable in  $(A_1, B_1)$  and hence from (2.13), for a.e.  $x \in (x_0, S(t, \lambda, \mu))$

$$\begin{aligned} f'(\lambda) = f'(u(x, t, \lambda, \mu)) &= \frac{x - y_+(x, t, u_0^{\lambda,\mu})}{t} \\ &< \frac{l_1(t) - A_1}{t} = f'(a_1), \end{aligned}$$

which is a contradiction since  $\lambda > a_1$ . Hence  $y_+(x, t, u_0^{\lambda,\mu}) \leq A_1$  for all  $x \in (x_0, S(t, \lambda, \mu))$ . Suppose  $y_+(x_0, t, u_0^{\lambda,\mu}) = A_1$ . Then from (2.21)  $f'(u(x, t)) = \frac{x-A_1}{t}$  for  $x \in (x_0, S(t, \lambda, \mu))$ . Let  $\gamma_x(\theta) = A_1 + \theta \left( \frac{x-A_1}{t} \right) < l_1(\theta)$  be the characteristic at  $(x, t)$ , then from (c) of (3) in theorem 2.1,  $\gamma_x$  is also a characteristic at  $(\gamma_x(s), s)$  for  $0 < s < t$  and  $f'(u(\gamma_x(s), s, \lambda, \mu)) = \frac{\gamma_x(s)-A_1}{s} < \frac{l_1(s)-A_1}{s} = f'(a_1)$ . Let  $s < \delta(\lambda, \mu)$ , then  $l_1(s) < L(s, \lambda)$  and hence  $f'(a_1) > f'(u(\gamma_x(s), s)) = f'(a_1)$  which is a contradiction. This proves the claim.

Let  $t_0 > \delta(\lambda, \mu)$  such that  $l(t_0) = S(t_0, \lambda, \mu)$ . Hence for  $x > S(t_0, \lambda, \mu), y_-(x, t_0, u_0^{\lambda, \mu}) \geq B_1$ . Therefore

$$a_2 = \max(\mu, a_2) \geq u(x, t_0, \lambda, \mu). \quad (2.137)$$

Let  $t_0 < t < T$  and  $w$  be the solution of (1.2) with initial data  $w_0$  at  $t_0$  is given by

$$w_0(x) = \begin{cases} a_1 & \text{if } x < S(t_0, \lambda, \mu) = l_1(t_0), \\ a_2 & \text{if } x > S(t_0, \lambda, \mu) = l_1(t_0). \end{cases}$$

Then  $w$  admits a shock at  $l_1(t_0)$  and for  $t > t_0$  is given by

$$\begin{aligned} \eta(t) &= l_1(t_0) + \frac{f(a_1) - f(a_2)}{a_1 - a_2} (t - t_0) \\ &< l_1(t_0) + f'(a_1)(t - t_0) \\ &= A_1 + f'(a_1)t \\ &= l_1(t), \end{aligned} \quad (2.138)$$

since  $f$  is strictly convex and  $f'(a_1) > 0 > f'(a_2)$ . From the claim and (2.137),

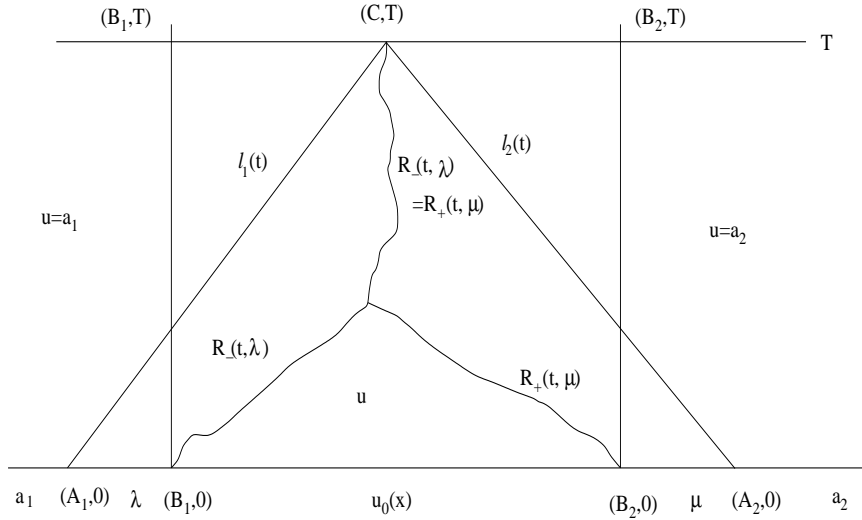


Figure 12:

$w_0(x) \geq u(x, t_0, \lambda, \mu)$  and therefore from (2.30) and (2.29) we have for  $t > t_0$ ,  $l_1(t) > \eta(t) \geq S(t, \lambda, \mu)$ . This proves (2.131).

From (3) of Lemma (2.4),  $(\lambda, \mu) \rightarrow S(T, \lambda, \mu)$  is a continuous function for  $\lambda \geq \lambda_1$  and  $\mu \leq \mu_1$ . From (2.93), choose a  $\tilde{\lambda}_1 > \lambda_1$  such that  $S(T, \tilde{\lambda}_1, \mu_1) > T$  and from (2.107) choose  $\tilde{\mu}_1 < \mu_1$  such that  $S(T, \lambda_1, \tilde{\mu}_1) < T$ . From Corollary 2.14,  $S$  is continuous in  $[\lambda_1, \tilde{\lambda}_1] \times [\mu_1, \tilde{\mu}_1]$  there exist a  $(\lambda, \mu) \in [\lambda_1, \tilde{\lambda}_1] \times [\mu_1, \tilde{\mu}_1]$  such that  $S(T, \lambda, \mu) = C$ . Hence (2.135) follows from (2.134). This proves the Lemma.

**Counter Example 2.16:** Let  $\alpha = 0, x_k < 0, \lim_{k \rightarrow \infty} x_k = 0, \lambda > \theta_f$  and define  $u_0, u_0^k$  by

$$u_0(x) = \begin{cases} \theta_f & \text{if } x < 0, \\ \lambda & \text{if } x > 0. \end{cases}$$

$$u_0^k(x) = \begin{cases} \theta_f & \text{if } x < x_k, \\ \lambda & \text{if } x > x_k. \end{cases}$$

Then the solution  $u$  and  $u_k$  with respective initial datas  $u_0$  and  $u_0^k$  are given by

$$u(x, t) = \begin{cases} \theta_f & \text{if } x < 0, t > 0, \\ (f')^{-1}\left(\frac{x}{t}\right) & \text{if } 0 < x \leq f'(\lambda)t, \\ \lambda & \text{if } x > f'(\lambda)t, \end{cases}$$

then

$$R_-(t, 0, u_0) = 0.$$

$$u_k(x, t) = \begin{cases} \theta_f & \text{if } x < x_k, t > 0, \\ (f')^{-1}\left(\frac{x-x_k}{t}\right) & \text{if } x_k < x < f'(\lambda)t + x_k, \\ \lambda & \text{if } x > f'(\lambda)t + x_k, \end{cases}$$

then

$$R_-(t, 0, u_0^k) = f'(\lambda)t,$$

$$\int_{\mathbb{R}} |u_0(x) - u_0^k(x)| dx = \int_{x_k}^0 (\lambda - \theta_f) = (\lambda - \theta_f)|x_k| \rightarrow 0 \text{ as } k \rightarrow \infty.$$

But

$$\lim_{k \rightarrow \infty} R_-(t, 0, u_0^k) = f'(\lambda)t > 0 = R_-(t, 0, u_0).$$

### 3 Shock Profile:

In this section we study the behavior of solutions of (1.2) in an explicit manner.

Let  $-\infty \leq A_1 < A_2 \leq \infty, I = (A_1, A_2), u_{\pm} \in \mathbb{R}, u_0 \in L^\infty((A_1, A_2))$  and define  $m, M, k_1, k_2, \gamma_1$  and  $\gamma_2$  as follows:

$$m = \inf_{x \in I} \{u_0(x), u_+\}, \quad M = \sup_{x \in I} \{u_0(x), u_-\} \quad (3.1)$$

$$f'(k_1) = \begin{cases} f'(u_-) & \text{if } u_- < m, \\ \frac{f(u_-) - f(m)}{u_- - m} & \text{if } u_- \geq m. \end{cases} \quad (3.2)$$

$$f'(k_2) = \begin{cases} f'(u_+) & \text{if } u_+ > M, \\ \frac{f(u_+) - f(M)}{u_+ - M} & \text{if } u_+ \leq M. \end{cases} \quad (3.3)$$

$$\gamma_1(t) = A_1 + f'(k_1)t, \quad \gamma_2(t) = A_2 + f'(k_2)t.$$

Let  $u_m, u_M$  be the solutions of (1.2) with respective initial data  $u_0^m, u_0^M$  given by

$$u_0^m(x) = \begin{cases} u_- & \text{if } x < A_1, \\ m & \text{if } x > A_1, \end{cases} \quad (3.4)$$

$$u_0^M(x) = \begin{cases} M & \text{if } x < A_2, \\ u_+ & \text{if } x > A_2. \end{cases}$$

Then  $u_m, u_M$  are given by

$$u_m(x, t) = \begin{cases} u_- & \text{if } x < \gamma_1(t), \\ (f')^{-1}\left(\frac{x-A_1}{t}\right) & \text{if } \gamma_1(t) < x < \text{Max}(\gamma_1(t), A_1 + tf'(m)), \\ m & \text{if } x > \text{Max}(\gamma_1(t), A_1 + tf'(m)). \end{cases} \quad (3.5)$$

$$u_M(x, t) = \begin{cases} M & \text{if } x < \text{Min}(\gamma_2(t), A_2 + tf'(M)), \\ (f')^{-1}\left(\frac{x-A_2}{t}\right) & \text{if } \text{Min}(\gamma_2(t), A_2 + tf'(M)) < x < \gamma_2(t), \\ u_+ & \text{if } x > \gamma_2(t). \end{cases} \quad (3.6)$$

Hence it follows that

$$\gamma_1(t) = R_-(t, A_1, u_0^m), \quad \gamma_2(t) = R_+(t, A_2, u_0^M). \quad (3.7)$$

Let

$$\bar{u}_0(x) = \begin{cases} u_- & \text{if } x < A_1, \\ u_0(x) & \text{if } A_1 < x < A_2, \\ u_+ & \text{if } x > A_2. \end{cases} \quad (3.8)$$

$$v_0(x) = \int_{A_1}^x \bar{u}_0(\theta) d\theta.$$

Let  $v$  be the corresponding value function defined in (2.4) and  $u = \frac{\partial v}{\partial x}$  be the solution of (1.2) with initial data  $\bar{u}_0$ . Since  $u_0^m \leq \bar{u}_0 \leq u_0^M$ , hence from lemma (2.2) and for all  $t > 0$ ,

$$\gamma_1(t) \leq R_-(t, A_1, \bar{u}_0) \leq R_+(t, A_2, \bar{u}_0) \leq \gamma_2(t). \quad (3.9)$$

Furthermore if  $x < R_-(t, A_1, \bar{u}_0)$ , then  $y_+(x, t, \bar{u}_0) < A_1$  and hence from (2.13) for a.e.  $x$ ,  $u(x, t) = u_0(y_+(x, t, \bar{u}_0)) = u_-$ . Similarly for  $x > R_+(t, A_2, \bar{u}_0)$ ,  $u(x, t) = u_+$ . Now letting  $x \uparrow R_-(t, A_1, \bar{u}_0)$  and  $x \downarrow R_+(t, A_2, \bar{u}_0)$  and from (2.12), (2.22) and (2.23) we have

$$\frac{R_-(t, A_1, \bar{u}_0) - y_-(R_-(t, A_1, \bar{u}_0), t, \bar{u}_0)}{t} = f'(u_-). \quad (3.10)$$

$$\frac{R_+(t, A_2, \bar{u}_0) - y_+(R_+(t, A_2, \bar{u}_0), t, \bar{u}_0)}{t} = f'(u_+). \quad (3.11)$$



$$u(x, t) = \begin{cases} u_- & \text{if } x < R_-(t, A_1, u_0), \\ u_+ & \text{if } x > R_+(t, A_2, u_0). \end{cases} \quad (3.12)$$

Now the main question is **how does the solution  $u$  behaves for  $R_-(t, A_1, \bar{u}_0) < x < R_+(t, A_2, \bar{u}_0)$ ?** In order to answer this question we have to consider two cases.

**Case 1:** For some  $T > 0$ ,  $R_-(T, A_1, \bar{u}_0) = R_+(T, A_2, \bar{u}_0)$ .

**Case 2:**  $R_-(t, A_1, \bar{u}_0) < R_+(t, A_2, \bar{u}_0)$ , for all  $t > 0$ .

Case 1 is a single shock and we have the following

**LEMMA 3.1** *Suppose for some  $T > 0$ ,*

$$R_-(T, A_1, \bar{u}_0) = R_+(T, A_2, \bar{u}_0) \quad (3.13)$$

*and denote  $S(T) = R_-(T, A_1, \bar{u}_0)$  and for  $t > T$*

$$S(t) = S(T) + \frac{f(u_+) - f(u_-)}{u_+ - u_-}(t - T), \quad (3.14)$$

*Then  $u_- > u_+$  and for  $t > T$ ,*

$$u(x, t) = \begin{cases} u_- & \text{if } x < S(t), \\ u_+ & \text{if } x > S(t). \end{cases} \quad (3.15)$$

**Proof.** From (3.12) and (3.13) we have

$$u(x, t) = \begin{cases} u_- & \text{if } x < S(T), \\ u_+ & \text{if } x > S(T). \end{cases} \quad (3.16)$$

From (2.27), for  $t > T$ ,  $R_-(t, A_1, \bar{u}_0) = R_+(t, A_2, u_0) = R_+(t, T, S(T), \bar{u}_0) = R_-(t, T, S(T), \bar{u}_0)$ . Hence  $S(T)$  is not a rarefaction point and therefore  $u_- > u_+$  and (3.15) follows. This proves the theorem.

Case 2 is quite involved and we need few preliminary results. From now on assume that for all  $t > 0$ ,

$$R_-(t, A_1, \bar{u}_0) < R_+(t, A_2, \bar{u}_0). \quad (3.17)$$

For  $\alpha$ ,  $x$  in  $\mathbb{R}$ ,  $t > 0$  denote

$$\begin{aligned} y_{\pm}(x, t) &= y_{\pm}(x, t, \bar{u}_0) \\ R_{\pm}(t, \alpha) &= R_{\pm}(t, \alpha, \bar{u}_0) \\ y_{\pm}(t, \alpha) &= y_{\pm}(R_-(t, \alpha), \alpha) \\ Y_{\pm}(t, \alpha) &= y_{\pm}(R_+(t, \alpha), \alpha). \end{aligned} \quad (3.18)$$

At the end points  $A_1$  and  $A_2$ , let

$$\begin{aligned} L(t) &= R_-(t, A_1, \bar{u}_0) \\ R(t) &= R_+(t, A_2, \bar{u}_0) \\ y_{\pm}(t, A_1) &= y_{\pm}(t) = y_{\pm}(R_-(t, A_1), t) \\ Y_{\pm}(t, A_2) &= Y_{\pm}(t) = y_{\pm}(R_+(t, A_2), t). \end{aligned} \quad (3.19)$$

From (2.4) we have for all  $x \in \mathbb{R}$ ,  $t > 0$ ,

$$\int_{A_1}^{y_-(x,t)} \bar{u}_0(\theta) d\theta + t f^* \left( \frac{x - y_-(x,t)}{t} \right) = \int_{A_1}^{y_+(x,t)} \bar{u}_0(\theta) d\theta + t f^* \left( \frac{x - y_+(x,t)}{t} \right). \quad (3.20)$$

If  $y_-(x,t) < A_1$ , then (3.20) becomes

$$(y_-(x,t) - A_1)u_- + t f^* \left( \frac{x - y_-(x,t)}{t} \right) = \int_{A_1}^{y_+(x,t)} \bar{u}_0(\theta) d\theta + t f^* \left( \frac{x - y_+(x,t)}{t} \right).$$

If  $y_+(x,t) > A_2$ , then

$$\begin{aligned} \int_{A_1}^{y_-(x,t)} \bar{u}_0(\theta) d\theta + t f^* \left( \frac{x - y_-(x,t)}{t} \right) &= \int_{A_1}^{A_2} \bar{u}_0(\theta) d\theta + (y_+(x,t) - A_2)u_+ \\ &+ t f^* \left( \frac{x - y_+(x,t)}{t} \right). \end{aligned} \quad (3.21)$$

**LEMMA 3.2** *Let  $r(t) = \alpha + t f'(p)$  be a straight line such that for all  $t > 0$ , (i). If  $y_-(r(t), t) = \alpha$ , then*

$$y_+(r(t), t) = \alpha \quad (3.22)$$

$$u(r(t)-, t) = u(r(t)+, t) = p. \quad (3.23)$$

(ii). If  $y_+(r(t), t) = \alpha$ , then

$$y_-(r(t), t) = \alpha \quad (3.24)$$

$$u(r(t)-, t) = u(r(t)+, t) = p. \quad (3.25)$$

**Proof.** It is enough to prove (i) and (ii) follows similarly. From (2.12) and (2.22) choose a sequence  $x_k < r(t)$  such that

$$\lim_{k \rightarrow \infty} (x_k, y_+(x_k, t)) = (r(t), y_-(r(t), t)), f'(u(x_k, t)) = \frac{x_k - y_+(x_k, t)}{t}. \quad (3.26)$$

Then

$$\begin{aligned} f'(u(r(t)-, t)) &= \frac{r(t) - y_-(r(t), t)}{t} \\ &= \frac{r(t) - \alpha}{t} \\ &= f'(p). \end{aligned}$$

Hence  $u(r(t)-, t) = p$  and from Rankine-Hugoniot condition across  $r(t)$ , we obtain  $u(r(t)+, t) = p$ . Again from (2.12) and (2.22) choose a sequence  $y_k > r(t)$  such that

$$\lim_{k \rightarrow \infty} (y_k, y_-(y_k, t)) = (r(t), y_+(r(t), t)), f'(u(y_k, t)) = \frac{y_k - y_-(y_k, t)}{t}$$

letting  $k \rightarrow \infty$  to obtain

$$\frac{r(t) - \alpha}{t} = f'(p) = f'(u(r(t)+, t)) = \frac{r(t) - y_+(r(t), t)}{t},$$

and hence  $y_+(r(t), t) = \alpha$ . This proves the lemma.

**Lemma 3.3** 1. Suppose for all  $t > 0$ ,  $y_-(t, \alpha) = \alpha$ , then there exists  $p_\alpha$  such that

$$R_-(t, \alpha) = \alpha + t f'(p_\alpha). \quad (3.27)$$

2. Suppose for all  $t > 0$ ,  $Y_+(t, \alpha) = \alpha$ , then there exists  $q_\alpha$  such that

$$R_+(t, \alpha) = \alpha + t f'(q_\alpha). \quad (3.28)$$

3.  $y_-(t, \alpha)$ ,  $Y_-(t, \alpha)$ , are non-increasing functions and  $y_+(t, \alpha)$ ,  $Y_+(t, \alpha)$  are non-decreasing functions of  $t$ . Moreover we have

**Boundary estimates:** Here we take  $\alpha = A_1$  or  $A_2$ . Let

$$\lim_{t \rightarrow \infty} (y_+(t), Y_-(t)) = (B_1, B_2). \quad (3.29)$$

Then (i).  $A_1 \leq B_1 \leq B_2 \leq A_2$  and following limits exist.

$$f'(u_-) = \lim_{t \rightarrow \infty} \frac{L(t) - y_+(t)}{t} \quad (3.30)$$

$$f'(u_+) = \lim_{t \rightarrow \infty} \frac{R(t) - Y_-(t)}{t}. \quad (3.31)$$

(ii). Let  $s_1 \geq 2$ ,  $s_2 \geq 2$ ,  $s = \max(s_1, s_2)$  and  $2 \leq j \leq s_1 - 1$ ,  $2 \leq l \leq s_2 - 1$ . Suppose  $f \in C^s(\mathbb{R})$  and satisfies for all  $j$  and  $l$ ,

$$f^{(j)}(u_-) = f^{(l)}(u_+) = 0, f^{(s_1)}(u_-) \neq 0, f^{(s_2)}(u_+) \neq 0,$$

then

$$\left| \frac{L(t) - y_+(t)}{t} - f'(u_-) \right| \leq \frac{M}{t^{1/s_1}} \quad (3.32)$$

$$\left| \frac{R(t) - Y_-(t)}{t} - f'(u_+) \right| \leq \frac{M}{t^{1/s_2}}, \quad (3.33)$$

where  $M$  depends only on  $[A_1, A_2], \|\bar{u}_0\|_\infty$ .

(iii). Define  $\Gamma_1(t) = B_1 + tf'(u_-)$ ,  $\Gamma_2(t) = B_2 + tf'(u_+)$ , then for all  $t > 0$ ,

$$\Gamma_1(t) \leq \Gamma_2(t). \quad (3.34)$$

Furthermore

$$y_-(\Gamma_1(t), t) = B_1, Y_+(\Gamma_2(t), t) = B_2 \quad (3.35)$$

$$\Gamma_1(t) = R_-(t, B_1), \Gamma_2(t) = R_+(t, B_2). \quad (3.36)$$

Let  $a \in (A_1, B_1)$ ,  $b \in (B_2, A_2)$  then there exist  $T_a > 0, T_b > 0$  such that for all  $t > T_a, s > T_b$

$$R_{\pm}(t, a) = L(t) \quad (3.37)$$

$$R_{\pm}(s, b) = R(s). \quad (3.38)$$

**Proof.** It is enough to prove (3.27) and (3.28) follows similarly. Let  $t_0 > 0$  and since  $y_-(t_0, \alpha) = \alpha$  and hence  $\gamma(\theta) = \alpha + \left(\frac{R_-(t_0, \alpha) - \alpha}{t_0}\right)\theta$  is the left extreme characteristic at  $(R_-(t_0, \alpha), t_0)$ . Let  $0 < t < t_0$ , then  $\gamma|_{[0, t]}$  is a characteristic and hence  $R_-(t, \alpha) \leq \gamma(t)$ . Suppose for some  $0 < t_1 < t_0$ ,  $R_-(t_1, \alpha) < \gamma(t_1)$ . Then from (2.22) we can choose a sequence  $x_k < R_-(t_0, \alpha)$  such that

$$y_+(x_k, t_0) = y_-(x_k, t_0) < \alpha, \lim_{k \rightarrow \infty} (x_k, y_+(x_k, t_0)) = (R_-(t_0, \alpha), \alpha).$$

Since  $y_-(t_1, \alpha) = y_-(R_-(t_1, \alpha), t_1) = \alpha$  and hence for  $k$  large the left extreme characteristic at  $(x_k, t_0)$  intersect with extreme characteristics at  $R_-(t_1, \alpha), t_1$  which contradicts NIP. Hence  $R_-(t, \alpha) = \gamma(t)$  for  $0 < t < t_0$  and  $t_0$  is arbitrary implies that  $p_{\alpha} = \frac{R_-(t_0, \alpha) - \alpha}{t_0}$  is independent of  $t_0$ . This proves (3.27).

(3). It is enough to prove for  $y_-(t, \alpha)$  and all other cases follow similarly. Suppose for  $0 < t_1 < t_2$ ,  $\gamma_-(0) = y_-(R_-(t_1, \alpha), t_1) < y_-(R_-(t_2, \alpha), t_2) \leq \alpha \leq \gamma_+(0)$  where  $\gamma_{\pm}$  are the extreme characteristic at  $(R_-(t_1, \alpha), t_1)$ . From (2.22), choose  $x_1 < x_2 < R_-(t_2, \alpha)$  such that  $y(x_i, t_2) = y_{\pm}(x_i, t_2)$  for  $i = 1, 2$  and

$$\gamma_-(0) < y(x_1, t_2) \leq y(x_2, t_2) < y_-(R_-(t_2, \alpha), t_2) \leq \gamma_+(0). \quad (3.39)$$

Let  $r_1, r_2$  be the characteristics at  $(x_1, t_2), (x_2, t_2)$  respectively. Then from (3.39), one of the characteristics  $r_1, r_2$  intersect  $\gamma_{\pm}(\theta)$  in  $(0, t_1)$  contradicting NIP. Hence  $y_-(t, \alpha)$  is a non increasing function.

First we claim that  $y_+(t) \leq A_2$ . Suppose not, then there exist  $t_0 > 0$  such that  $y_+(t_0) > A_2$ . Since  $Y_-(t_0) \leq A_2$  and  $L(t_0) < R(t_0)$ , therefore the characteristic joining  $(L(t_0), t_0), (y_+(t_0), t_0)$  and  $(R(t_0), t_0), (Y_-(t_0), t_0)$  intersects, which contradicts NIP. This proves the claim. Similarly  $A_1 \leq Y_-(t) \leq A_2$ . Again from NIP and  $L(t) < R(t)$ , we have  $y_+(t) \leq Y_-(t)$  for all  $t > 0$ . Therefore  $A_1 \leq B_1 \leq B_2 \leq A_2$ .

From (3.10) and (3.21), we have at  $x = L(t)$ ,

$$\begin{aligned}
u_-(y_-(t) - A_1) + tf^*\left(\frac{L(t) - y_-(t)}{t}\right) &= \int_{A_1}^{y_+(t)} u_0(\theta)d\theta + tf^*\left(\frac{L(t) - y_+(t)}{t}\right) \\
&\quad - \left(\frac{L(t) - y_-(t)}{t}\right)u_- + f^*\left(\frac{L(t) - y_-(t)}{t}\right) \\
&= \frac{1}{t} \int_{A_1}^{y_+(t)} u_0(\theta)d\theta + \left(\frac{A_1 - y_+(t)}{t}\right)u_- - \left(\frac{L(t) - y_+(t)}{t}\right)u_- \\
&\quad + f^*\left(\frac{L(t) - y_+(t)}{t}\right) - f'(u_-)u_- + f^*(f'(u_-)) \\
&= O\left(\frac{1}{t}\right) - \left(\frac{L(t) - y_+(t)}{t}\right)u_- + f^*\left(\frac{L(t) - y_+(t)}{t}\right).
\end{aligned}$$

Let  $f'(p_t) = \frac{L(t) - y_+(t)}{t}$ , then from (2.1) and above equality we have

$$f(u_-) - f(p_t) - (u_- - p_t)f'(p_t) = O\left(\frac{1}{t}\right). \quad (3.40)$$

That is

$$(p_t - u_-)^2 \int_0^1 (1 - \theta)f''(p_t + \theta(u_- - p_t))d\theta = O\left(\frac{1}{t}\right). \quad (3.41)$$

From (3.9) we have  $A_1 + f'(k_1)t \leq L(t) \leq A_2 + f'(k_2)t$  and hence

$$\frac{A_1 - y_+(t)}{t} + f'(k_1) \leq f'(p_t) = \frac{L(t) - y_+(t)}{t} \leq \frac{A_2 - y_+(t)}{t} + f'(k_2).$$

Therefore  $\{p_t\}$  is bounded. Let  $t_k \rightarrow \infty$  such that  $p_{t_k} \rightarrow p$ , then from (3.41) if  $p \neq u_-$ , then

$$\int_0^1 (1 - \theta)f''(p + \theta(u_- - p))d\theta = 0,$$

and hence  $f(p + \theta(u_- - p))$  is linear in  $\theta \in [0, 1]$  which contradicts the strict convexity of  $f$ . Hence  $p = u_-$  and

$$\lim_{t \rightarrow \infty} \frac{L(t) - y_+(t)}{t} = f'(u_-). \quad (3.42)$$

This proves (3.30) and similarly (3.31) follows.

Let  $f^{(j)}(u_-) = 0$  for  $2 \leq j \leq s_1 - 1$  and  $f^{(s_1)}(u_-) \neq 0$ . Let  $T_0 > 0$  such that

$$0 < C = \sup_{t > T_0} \frac{1}{(s_1 - 1)!} \left| \int_0^1 (1 - \theta)^{s_1 - 1} f^{(s_1)}(p_t + \theta(u_- - p_t)) d\theta \right|. \quad (3.43)$$

From (3.40) and by Taylor's series expansion

$$(u_- - p_t)^{s_1} \frac{1}{(s_1 - 1)!} \int_0^1 (1 - \theta)^{s_1 - 1} f^{(s_1)}(p_t + \theta(u_- - p_-)) d\theta = O\left(\frac{1}{t}\right)$$

and therefore from (3.43) for  $t \geq T_0$ ,

$$|p_t - u_-| = O\left(\frac{1}{t^{s_1}}\right)$$

or

$$|f'(p_t) - f'(u_-)| \leq M/t^{s_1},$$

where  $M$  depends only on  $\|\bar{u}_0\|_\infty$  and  $[A_1, A_2]$ . This proves (3.32). Similarly (3.33) follows.

Next consider the extreme right characteristic  $r_+(\theta, t) = y_+(t) + \theta f'(p_t)$  at  $(L(t), t)$  and for  $0 < t_0 < t$ , define  $x(t_0, t) = r_+(t_0, t)$ . Then  $r_+(\cdot, t)|_{[0, t_0]}$  is a characteristic and is given by

$$\begin{aligned} x(t_0, t) &= y_+(t) + t_0 f'(p_t) \\ r_+(\theta, t) &= x(t_0, t) + (\theta - t_0) f'(p_t). \end{aligned}$$

Let  $t_2 > t_1 > t_0$ , since  $y_+(t)$  is a non decreasing function, hence from NIP we have  $x(t_0, t_1) \leq x(t_0, t_2)$  and therefore for  $0 \leq \theta \leq t_0$

$$\begin{aligned} x(t_0) &= \lim_{t \rightarrow \infty} x(t_0, t) \\ &= B_1 + t_0 f'(u_-) = \Gamma_1(t_0). \end{aligned}$$

$$\begin{aligned} \lim_{t \rightarrow \infty} r_+(\theta, t) &= x(t_0) + (\theta - t_0) f'(u_-) \\ &= B_1 + \theta f'(u_-) \\ &= \Gamma_1(\theta). \end{aligned} \quad (3.44)$$

From (2) of Lemma (4.2),  $\Gamma_1(\theta)$  is a characteristic at  $(\Gamma_1(t_0), t_0)$  for all  $t_0 > 0$  and  $\Gamma_1(0) = B_1$ . Hence  $y_-(\Gamma_1(t_0), t_0) \leq B_1$ . If  $y_-(\Gamma_1(t_0), t_0) < B_1$ , then from (3.29) for large  $t$ ,  $r_+(\cdot, t)$  intersect the extreme left characteristic at  $(\Gamma_1(t_0), t_0)$  contradicting NIP. Hence  $y_-(\Gamma_1(t_0), t_0) = B_1$ , and from (3.22), (3.24)  $R_-(t_0, B_1) = \Gamma_1(t_0)$ . This proves (3.35) and (3.36).

Let  $a \in (A_1, B_1)$  and choose  $T_a > 0$  such that for  $t \geq T_a$ ,  $y_+(t) \geq y_+(T_a) > a$ . Suppose for some  $t > T_a$ ,  $R_-(t, a) > L(t)$ , then  $a \geq y_-(t, a) \geq y_+(t) > a$ , which is a contradiction. Hence  $R_-(t, a) = L(t)$  for all  $t \geq T_a$ . This proves (3.37) and (3.38) follows similarly. This proves the Lemma.

**Behaviour of  $\mathbf{R}_\pm(t, \alpha)$  for  $\alpha \in (\mathbf{B}_1, \mathbf{B}_2)$ :** From Monotonicity of  $y_\pm$  and from (3.34) we have

$$\Gamma_1(t) = R_-(t, B_1) \leq R_+(t, B_1) \leq R_-(t, \alpha) \leq R_+(t, \alpha) \leq R_-(t, B_2) \leq R_+(t, B_2) = \Gamma_2(t). \quad (3.45)$$

$$B_1 \leq y_-(t, \alpha) \leq Y_-(t, \alpha) \leq \alpha \leq y_+(t, \alpha) \leq Y_+(t, \alpha) \leq B_2. \quad (3.46)$$

Next define the regular points as follows:

**Definition 3.4.** Let  $\alpha \in [B_1, B_2]$ , then

(i)  $\alpha$  is said to be a left regular point if for all  $t > 0$ ,

$$y_-(R_-(t, \alpha), t) = \alpha.$$

(ii)  $\alpha$  is said to be a right regular point if for all  $t > 0$ ,

$$y_+(R_+(t, \alpha), t) = \alpha.$$

(iii)  $\alpha$  is said to be a regular point if for all  $t > 0$ ,

$$y_-(R_-(t, \alpha), \alpha) = y_+(R_+(t, \alpha), \alpha) = \alpha.$$

**Definition 3.5. (characteristic Line):** Let  $r(t) = \alpha + tf'(p)$  be a straight line.  $r$  is called a characteristic line if  $y_-(r(t), t) = \alpha$  for all  $t > 0$  or  $y_+(r(t), t) = \alpha$  for all  $t > 0$ .

**Definition 3.6.**  $u_0$  is said to be mildly oscillating at  $a$  if there exist  $r_1 < a < r_2$  such that  $u_0$  is monotone in  $(r_1, a) \cup (a, r_2)$ .

**Definition 3.7.** Let  $\alpha < \beta$  and  $u_0$  is said to have same parity at  $\alpha, \beta$ , if there exist  $\alpha < r_1 < r_2 < \beta$  such that

$$u_0(\alpha) = u_0(\beta) \quad (3.47)$$

and  $u_0$  is a non decreasing function in  $(\alpha, r_1) \cup (r_2, \beta)$ .

**Lemma 3.8** Let  $\alpha \in \mathbb{R}$  be such that either  $\{Y_\pm(t, \alpha)\}$  is bounded or  $\{y_\pm(t, \alpha)\}$  is bounded for all  $t > 0$ . Then there exist  $A_{1, \alpha} \leq A_{2, \alpha}$  and  $p_\alpha$  and denote for  $i = 1, 2$

$$r_{i, \alpha}(t) = A_{i, \alpha} + tf'(p_\alpha) \quad (3.48)$$

$$D_\alpha = \{(x, t) : r_{1,\alpha}(t) < x < r_{2,\alpha}(t)\}, \quad (3.49)$$

then

1. Following limit exist. If  $\{y_\pm(t, \alpha)\}$  is bounded then

$$(A_{1,\alpha}, A_{2,\alpha}) = \lim_{t \rightarrow \infty} (y_-(t, \alpha), y_+(t, \alpha)). \quad (3.50)$$

If  $\{Y_\pm(t, \alpha)\}$  is bounded, then

$$(A_{1,\alpha}, A_{2,\alpha}) = \lim_{t \rightarrow \infty} (Y_-(t, \alpha), Y_+(t, \alpha)). \quad (3.51)$$

2.  $A_{1,\alpha} \leq \alpha \leq A_{2,\alpha}$  and for  $i = 1, 2$ ,  $r_{i,\alpha}$  are characteristic lines.

3. Let  $A_{1,\alpha} < \beta_1 \leq \beta_2 < A_{2,\alpha}$ , then  $\beta_i$  are neither a left nor right regular point and there exist  $T > 0$  such that for all  $t > T$ .

$$R_-(t, \alpha) = R_-(t, \beta_1) = R_+(t, \beta_2) \quad (3.52)$$

$$y_\pm(t, \beta_1) = Y_\pm(t, \beta_2). \quad (3.53)$$

$$\lim_{t \rightarrow \infty} (y_-(t, \beta_1), y_+(t, \beta_2)) = (A_{1,\alpha}, A_{2,\alpha}) \quad (3.54)$$

$$D_{\beta_1} = D_{\beta_2} = D_\alpha. \quad (3.55)$$

Furthermore  $D_\alpha$  does not contain a characteristic line and for any  $\alpha, \beta$  either  $D_\alpha = D_\beta$  or  $D_\alpha \cap D_\beta = \phi$ .

4. If  $\alpha$  is a left regular point then  $A_{1,\alpha} = \alpha$ . If  $\alpha$  is a right regular point, then  $A_{2,\alpha} = \alpha$ .

5. For all  $t > 0$ ,

$$\int_{A_{1,\alpha}}^{A_{2,\alpha}} \bar{u}_0(x) dx = \int_{r_{1,\alpha}(t)}^{r_{2,\alpha}(t)} u(x, t) dx \quad (3.56)$$

$$\int_{r_{1,\alpha}(t)}^{r_{2,\alpha}(t)} |f'(u(x, t)) - f'(p_\alpha)| \leq \frac{2(A_{2,\alpha} - A_{1,\alpha})}{t}, \quad (3.57)$$

and

$$\int_{A_{1,\alpha}}^{A_{2,\alpha}} \bar{u}_0(x) dx = p_\alpha(A_{2,\alpha} - A_{1,\alpha}). \quad (3.58)$$



6. If  $\bar{u}_0$  is continuous in neighbourhoods of  $\{A_{1,\alpha}, A_{2,\alpha}\}$  then

$$\bar{u}_0(A_{1,\alpha}) = \bar{u}_0(A_{2,\alpha}) = p_\alpha. \quad (3.59)$$

7. If  $\bar{u}_0$  is mildly oscillatory at  $A_{1,\alpha}$  and  $A_{2,\alpha}$  then  $\bar{u}_0$  have the same parity at  $A_{1,\alpha}, A_{2,\alpha}$ .

8. If  $\alpha \in [B_1, B_2]$ , then  $\{y_\pm(t, \alpha)\}, \{Y_\pm(t, \alpha)\}$  are bounded and

$$B_1 \leq A_{1,\alpha} \leq \alpha \leq A_{2,\alpha} \leq B_2 \quad (3.60)$$

$$u_- \leq p_\alpha \leq u_+. \quad (3.61)$$

**Proof.** Without loss of generality we can assume that  $\{y_\pm(t, \alpha)\}$  are bounded. Similar arguments follow if  $\{Y_\pm(t, \alpha)\}$  are bounded. Then from (3) of Lemma (3.2),  $y_-(t, \alpha), y_+(t, \alpha)$  are non increasing and non decreasing functions of  $t$  and  $y_-(t, \alpha) \leq \alpha \leq y_+(t, \alpha)$ . Hence

$$(A_{1,\alpha}, A_{2,\alpha}) = \lim_{t \rightarrow \infty} (y_-(t, \alpha), y_+(t, \alpha))$$

exist and  $A_{1,\alpha} \leq \alpha \leq A_{2,\alpha}$ . If  $\alpha$  is a left regular point then  $y_-(t, \alpha) = \alpha$  and hence  $A_{1,\alpha} = \alpha$ . If  $\alpha$  is a right regular point. Then one must, take  $Y_\pm(t, \alpha)$  and  $A_{2,\alpha} = Y_+(t, \alpha)$ .

**Case (1):** Let  $\alpha$  be a regular point. Then  $\alpha = y_-(t, \alpha) \leq Y_+(t, \alpha) = \alpha$ . Hence  $A_{1,\alpha} = A_{2,\alpha}$  and from Lemma (3.3), there exist  $p_\alpha$  such that

$$r_{1,\alpha}(t) = r_{2,\alpha}(t) = R_-(t, \alpha) = R_+(t, \alpha) = \alpha + tf'(p_\alpha), \quad (3.62)$$

is a characteristic line.

**Case (2):** Let  $\alpha$  not a regular point. Without loss of generality we can assume that  $\alpha$  is not a right regular point. Hence there exist  $T > 0$  such that for all  $t > T$ ,  $A_{1,\alpha} \leq y_-(t, \alpha) \leq \alpha < y_+(t, \alpha) \leq A_{2,\alpha}$ . Let  $r_{\pm,t}(\theta)$  be the extreme characteristics at  $(R_-(t, \alpha), t)$  and

$$f'(p_{\pm,t}) = \frac{R_-(t, \alpha) - y_\pm(t, \alpha)}{t}$$

$$r_{\pm,t}(\theta) = y_\pm(t, \alpha) + \theta f'(p_{\pm,t}).$$

Since  $\{y_\pm(t, \alpha)\}$  are bounded and from (4) of Lemma (2.1), there exist a  $c > 0$  such that

$$\left| \frac{R_-(t, \alpha) - y_\pm(t, \alpha)}{t} \right| \leq c.$$

Hence  $\{f'(p_{\pm,t})\}$  is bounded as  $t \rightarrow \infty$ .

**Claim 1:** Following limits exist and are equal

$$\lim_{t \rightarrow \infty} f'(p_{\pm,t}) = f'(p_{\pm,\alpha}) \quad (3.63)$$

$$p_{+,\alpha} = p_{-,\alpha} = p_\alpha \quad (3.64)$$

and  $r_{1,\alpha}, r_{2,\alpha}$  are characteristic lines.

Let  $0 < t_0 < t, x(t_0, t) = r_{+,t}(t_0)$ , then for  $0 < \theta < t_0, r_{+,t}(\theta)$  is a characteristic at  $(x(t_0, t), t_0)$  and is given by

$$x(t_0, t) = y_+(t, \alpha) + t_0 f'(p_{+,t}) \quad (3.65)$$

$$r_{+,t}(\theta) = x(t_0, t) + (\theta - t_0) f'(p_{+,t}). \quad (3.66)$$

Let  $t_2 > t_1 > t_0$ , then from (3) of Lemma (3.3) we have  $y_+(t_2, \alpha) \geq y_+(t_1, \alpha) \geq y_+(t_0, \alpha)$  and hence from NIP,  $x(t_0, t_2) \geq x(t_0, t_1)$ . Since  $f'(p_{+,t})$  is bounded as  $t \rightarrow \infty$  and hence from (3.65)  $x(t_0, t)$  is bounded as  $t \rightarrow \infty$ . Let  $x(t_0) = \lim_{t \rightarrow \infty} x(t_0, t)$ . Let  $t_2 > t_1 > t_0$ , then from (3.65)

$$\begin{aligned} f'(p_{+,t_2}) - f'(p_{-,t_2}) &= \frac{x(t_0, t_2) - y_+(t_2, \alpha)}{t_0} - \frac{x(t_0, t_1) - y_+(t_1, \alpha)}{t_0} \\ &= \frac{x(t_0, t_2) - x(t_0, t_1)}{t_0} + \frac{y_+(t_1, \alpha) - y_+(t_2, \alpha)}{t_0} \\ &\rightarrow 0 \text{ as } t_2, t_1 \rightarrow \infty. \end{aligned}$$

Therefore  $p_{+,\alpha}$  exist and similarly  $p_{-,\alpha}$  exist and this proves (3.63). From (2) of Lemma (2.1), limit of a characteristic is a characteristics, hence by taking  $t \rightarrow \infty$  in (3.65) and (3.66) to obtain

$$x(t_0) = A_{2,\alpha} + t_0 f'(p_{+,\alpha}). \quad (3.67)$$

$$\begin{aligned} \lim_{t \rightarrow \infty} r_{+,t}(\theta) &= x(t_0) + (\theta - t_0) f'(p_{+,\alpha}) \\ &= A_{2,\alpha} + \theta f'(p_{+,\alpha}) \\ &= r_{2,\alpha}(\theta). \end{aligned} \quad (3.68)$$

Suppose  $y_-(r_{2,\alpha}(t_0), t_0) < A_{2,\alpha}$ , then choose  $t_1 > t_0$  such that  $y_-(r_{2,\alpha}(t_0), t_0) < y_+(t_1, \alpha) \leq A_{2,\alpha}$  and hence  $r_{+,t_1}$  intersects the extreme left characteristic at  $(r_{2,\alpha}(t_0), t_0)$  contradicting NIP. Hence  $y_-(r_{2,\alpha}(t), t) = A_{2,\alpha}$  and therefore  $r_{2,\alpha}$  is a characteristic line. Similarly  $r_{1,\alpha}$  is a characteristic line. Since  $y_-(t, \alpha) \leq \alpha \leq y_+(t, \alpha)$  and therefore

$$\begin{aligned} f'(p_{-,\alpha}) &= \lim_{t \rightarrow \infty} \frac{R_-(t, \alpha) - y_-(t, \alpha)}{t} \\ &\geq \lim_{t \rightarrow \infty} \frac{R_-(t, \alpha) - y_+(t, \alpha)}{t} \\ &= f'(p_{+,\alpha}). \end{aligned}$$

Suppose  $f'(p_{+,\alpha}) < f'(p_{-,\alpha})$ , then  $r_{1,\alpha}$  and  $r_{2,\alpha}$  intersects at  $t_0$  given by

$$t_0 = \frac{A_{2,\alpha} - A_{1,\alpha}}{f'(p_{-,\alpha}) - f'(p_{+,\alpha})} > 0.$$

Let  $t > t_0$ , then  $r_{1,\alpha}$  and  $r_{2,\alpha}$  intersects at  $t_0 \in [0, t]$  contradicting NIP, since  $r_{i,\alpha}$  are characteristic lines for  $i = 1, 2$ . Hence  $p_{+,\alpha} = p_{-,\alpha}$  and this proves the claim.

**Claim 2:** Let  $A_{1,\alpha} < \beta < A_{2,\alpha}$ , then there exist  $T > 0$  such that for all  $t > T$

$$R_-(t, \beta) = R_+(t, \beta) = R(t, \alpha). \quad (3.69)$$

Choose  $T > 0$  such that for  $t > T$

$$y_-(t, \alpha) \leq y_-(T, \alpha) < \beta < y_+(T, \alpha) \leq y_+(t, \alpha). \quad (3.70)$$

Suppose for some  $t_0 > T$ ,  $R_-(t_0, \beta) < R_-(t_0, \alpha)$ , then from (2.22), (3.70),  $\beta \leq y_+(R_-(t_0, \beta), \beta) \leq y_-(R_-(t_0, \alpha), \alpha) = y_-(t_0, \alpha) < \beta$  which is a contradiction. Suppose  $R_+(t_0, \beta) > R_-(t_0, \alpha)$ , then from (2.23) and (3.70)  $\beta < y_+(t_0, \alpha) \leq y_-(R_+(t_0, \beta), t_0) \leq \beta$  which is a contradiction. Hence  $R_-(t, \beta) = R_-(t, \alpha)$  for  $t > T$ . Similarly  $R_+(t, \beta) = R_+(t, \alpha)$  for  $t \geq T$  and this proves the claim.

**Claim 3:**  $D_\alpha$  does not contain a characteristic line.

Suppose  $r(\theta) = \beta + \theta f'(a)$  be a characteristic line in  $D_\alpha$ . Then  $A_{1,\alpha} + \theta f'(p_\alpha) < r(\theta) < A_{2,\alpha} + \theta f'(p_\alpha)$  for all  $\theta$ . Hence  $p_\alpha = p$  and  $A_{1,\alpha} < \beta < A_{2,\alpha}$  and  $R_-(t, \beta) \leq r(t) \leq R_+(t, \beta)$ . From (3.69), there exist  $T > 0$  such that for  $t \geq T$ ,  $r(t) = R_-(t, \alpha)$  and  $\beta = y_-(r(t), t) = y_-(t, \alpha) \rightarrow A_{2,\alpha}$  as  $t \rightarrow \infty$ , which is a contradiction and hence the claim.

(2) and (4) follows from claim 1. Let  $A_{1,\alpha} < \beta < A_{2,\alpha}$  and suppose  $\beta$  is left regular point, then from (3.27),  $D_\alpha$  contains a characteristic line which contradicts claim 3. Similarly  $\beta$  cannot be right regular point. Let  $D_\alpha \cap D_\beta \neq \phi$ . Since  $\partial D_\alpha$  consists of characteristic lines therefore  $D_\beta$  contains a characteristic line which is a contradiction. Hence  $\partial D_\alpha \cap D_\alpha = \phi$  and similarly  $\partial D_\beta \cap D_\alpha = \phi$ . This shows that  $D_\alpha = D_\beta$ .

(3.52) to (3.55) follows from claim (2). This proves (3).

Let  $t_0 > 0$ , then from (2.22) and (2.12) choose a sequence  $x_k \uparrow r_{2,\alpha}(t_0)$  such that

$$f'(u(r_{2,\alpha}(t_0)-, t_0)) = \lim_{k \rightarrow \infty} \frac{x_k - y_+(x_k, t_0)}{t_0}. \quad (3.71)$$

From (3.65) to (3.68) choose a  $t_k \rightarrow \infty$  such that  $y_+(t_k, \alpha) \leq y_+(x_k, t_0) \leq y_+(t_{k+1}, \alpha)$  as  $k \rightarrow \infty$ . Hence from (3.71) we have

$$\begin{aligned} f'(u(r_{2,\alpha}(t_0)-, t_0)) &= \lim_{k \rightarrow \infty} \frac{x_k - y_+(t_k, \alpha)}{t_0} \\ &= \frac{r_{2,\alpha}(t_0) - A_{2,\alpha}}{t_0} \\ &= f'(p_\alpha). \end{aligned}$$

Hence  $u(r_{2,\alpha}(t_0)-, t_0) = p_\alpha$ . Similarly at  $r_{1,\alpha}(t_0)$ . Hence for all  $t_0 > 0$ ,

$$u(r_{1,\alpha}(t_0)+, t_0) = u(r_{2,\alpha}(t_0)-, t_0) = p_\alpha. \quad (3.72)$$

Let  $D_\alpha(t_0) = \{(x, t) \in D_\alpha; 0 < t < t_0\}$ , then from (3.72) we have

$$0 = \int_{D_\alpha(t_0)} (u_t + f(u)_x) dx dt = \int_{r_{1,\alpha}(t_0)}^{r_{2,\alpha}(t_0)} u(x, t_0) dx - \int_{A_{1,\alpha}}^{A_{2,\alpha}} \bar{u}_0(x) dx.$$

This proves (3.56).

From (2.12) we have

$$\begin{aligned} \int_{r_{1,\alpha}(t_0)}^{r_{2,\alpha}(t_0)} |f'(u(x, t)) - f'(p_\alpha)| dx &= \int_{r_{1,\alpha}(t_0)}^{r_{2,\alpha}(t_0)} \left| \frac{x - y_+(x, t_0)}{t_0} - f'(p_\alpha) \right| \\ &= \int_{A_{1,\alpha} + t_0 f'(p_\alpha)}^{A_{2,\alpha} + t_0 f'(p_\alpha)} \left| \frac{x - t_0 f'(p_\alpha)}{t_0} - \frac{y_+(x, t_0)}{t_0} \right| dx. \end{aligned}$$

By change of variables  $x \rightarrow x - t_0 f'(p_\alpha)$  and observing  $A_{1,\alpha} \leq y_+(x, t_0) \leq A_{2,\alpha}$  to obtain

$$\int_{r_{1,\alpha}(t_0)}^{r_{2,\alpha}(t_0)} |f'(u(x, t)) - f'(p_\alpha)| dx \leq \frac{2(A_{2,\alpha} - A_{1,\alpha})}{t_0}.$$

This proves (3.57).

From (3.56) to (3.57) we have for  $t > 0$ ,

$$\begin{aligned}
\left| \int_{A_{1,\alpha}}^{A_{2,\alpha}} \bar{u}_0(x) dx \right| &= \int_{r_{1,\alpha}(t)}^{r_{2,\alpha}(t)} u(x, t) dx \\
&= \int_{A_{1,\alpha}+tf'(p_\alpha)}^{A_{2,\alpha}+tf'(p_\alpha)} (f')^{-1} \left( \frac{x - y_+(x, t)}{t} \right) dx \\
&= \int_{A_{1,\alpha}}^{A_{2,\alpha}} (f')^{-1} \left( \frac{\xi - y_+(\xi + tf'(p_\alpha), t)}{t} + f'(p_\alpha) \right) d\xi \\
&\rightarrow p_\alpha(A_{2,\alpha} - A_{1,\alpha}) \text{ as } t \rightarrow \infty
\end{aligned}$$

this proves (3.58) and hence (5).

Let  $\bar{u}_0$  is continuous in a neighbourhood of  $A_{1,\alpha}$  then  $v_0$  is differentiable in the same neighbourhood. Let  $t_0 > 0$  and  $x(t_0, t)$  be as in (3.65). Then from (2.13) for a.e.,  $r_{1,\alpha}(t_0) < x < x(t_0, t)$  and  $t$  large,  $u(x, t) = u_0(y_+(x, t))$ . Hence letting  $t \rightarrow \infty$  and from (3.72)

$$\begin{aligned}
p_\alpha = u(r_{1,\alpha}(t_0)+, t_0) &= \lim_{t \rightarrow \infty} u_0(y_+(x, t)) \\
&= u_0(A_{1,\alpha}).
\end{aligned}$$

Similarly  $p_\alpha = u_0(A_{2,\alpha})$ . This proves (6).

Let  $\bar{u}_0$  be mildly oscillatory at  $A_{1,\alpha}$  and  $A_{2,\alpha}$ . Suppose they are not of same parity. Therefore assume that there exist  $A_{1,\alpha} < r_1 < r_2 < A_{2,\alpha}$  such that  $u_0$  is a non decreasing function in  $(A_{1,\alpha}, r_1)$  and  $u_0$  is non increasing function in  $(r_2, A_{2,\alpha})$ . Then from (3.52) choose  $T > 0$  such that for all  $t > T$ .

$$R_-(t, r_1) = R_+(t, r_2) = R_-(t, \alpha).$$

Since  $\bar{u}_0$  is continuous in  $[A_{1,\alpha}, A_{2,\alpha}]$  and hence from (2.13), for a.e.  $x \in (r_{1,\alpha}(t), R_-(t, \alpha))$  and  $z \in (R_-(t, \alpha), r_{2,\alpha}(t))$

$$\begin{aligned}
u(x, t) &= \bar{u}_0(y_+(x, t)), u(z, t) = \bar{u}_0(y_+(z, t)) \\
y_+(x, t) &\in (A_{1,\alpha}, r_1), y_+(z, t) \in (r_2, A_{2,\alpha}).
\end{aligned}$$

Hence from (3.59), we have

$$p_\alpha = \bar{u}_0(A_{1,\alpha}) \leq \bar{u}_0(y_+(x, t)) = u(x, t) \quad (3.73)$$

$$p_\alpha = \bar{u}_0(A_{2,\alpha}) \leq \bar{u}_0(y_+(z, t)) = u(z, t). \quad (3.74)$$

**Claim 4:** There exist an  $r > 0$  such that either  $\bar{u}_0 > p_\alpha$  for  $x \in (A_{1,\alpha}, A_{1,\alpha} + r)$  or  $x \in (A_{2,\alpha} - r, A_{2,\alpha})$ .

Suppose not, then by shrinking  $r_1$  and  $r_2$  if necessary we can assume that  $u_0$  is constant in  $(A_{1,\alpha}, r_1)$  and  $(r_2, A_{2,\alpha})$  and from (3.59) for all  $\theta \in (A_{1,\alpha}, r_1) \cup (r_2, A_{2,\alpha})$ .

$$\bar{u}_0(\theta) = p_\alpha. \quad (3.75)$$

From (3.73) , (2.12) , (2.22), (2.23), (3.74) we have

$$\begin{aligned} f'(p_\alpha) &= \lim_{x \uparrow R_-(t,\alpha)} f'(u_0(y_+(x,t))) \\ &= \lim_{x \uparrow R_-(t,\alpha)} f'(u(x,t)) \\ &= \lim_{x \uparrow R_-(t,\alpha)} \frac{x - y_+(x,t)}{t} \\ &= \frac{R_-(t,\alpha) - y_-(t,\alpha)}{t}, \end{aligned}$$

hence  $R_-(t,\alpha) = y_-(t,\alpha) + tf'(p_\alpha)$ . Similarly  $R_+(t,\alpha) = y_+(t,\alpha) + tf'(p_\alpha)$ . This implies  $y_+(t,\alpha) = y_-(t,\alpha)$  for all  $t > T$ , which is a contradiction since  $A_{1,\alpha} < A_{2,\alpha}$ . This proves the claim.

As a consequence of this claim, (3.72), (3.73) we have for  $t > T$ ,

$$\int_{r_{1,\alpha}(t)}^{r_{2,\alpha}(t)} u(x,t)dx = \int_{r_{1,\alpha}(t)}^{R_-(t,\alpha)} u(x,t)dx + \int_{R_-(t,\alpha)}^{r_{2,\alpha}(t)} u(x,t)dx > p_\alpha(A_{2,\alpha} - A_{1,\alpha}). \quad (3.76)$$

On the other hand from (3.55) , (3.58) and (3.75)

$$\begin{aligned} (A_{2,\alpha} - A_{1,\alpha})p_\alpha &= \int_{A_{1,\alpha}}^{A_{2,\alpha}} \bar{u}_0(\theta)d\theta \\ &= \int_{r_{1,\alpha}(t)}^{r_{2,\alpha}(t)} u(x,t)dx \\ &> p_\alpha(A_{2,\alpha} - A_{1,\alpha}), \end{aligned}$$

which is a contradiction.

Similar proof follows if  $u_0$  cannot be a non increasing function in  $(A_{1,\alpha}, r_1)$  and non decreasing function in  $(r_2, A_{2,\alpha})$ .

Suppose  $u_0$  is a non increasing function in  $(A_{1,\alpha}, r_1)$  and non increasing function in  $(r_2, A_{2,\alpha})$ . For  $t > T$  and for a.e.  $x, \xi$  with

$$A_{1,\alpha} + tf'(p_\alpha) < x < R(t,\alpha) < \xi < A_{2,\alpha} + tf'(p_\alpha),$$

we have  $y_+(x,t) \in (A_{1,\alpha}, r_1)$  and  $y_-(\xi,t) \in (r_2, A_{2,\alpha})$ . Therefore  $f'(u_0(y_+(x,t))) \leq f'(u_0(A_{1,\alpha})) = f'(p_\alpha)$  and  $f'(u_0(y_-(\xi,t))) \geq f'(u_0(A_{2,\alpha})) = f'(p_\alpha)$ . Hence from

(2.13),(2.22) we have

$$\begin{aligned}
\frac{R(t, \alpha) - y_-(t, \alpha)}{t} &= \lim_{x \uparrow R(t, \alpha)} \frac{x - y_+(x, t)}{t} \\
&= \lim_{x \uparrow R(t, \alpha)} f'(u(x, t)) \\
&= \lim_{x \uparrow R(t, \alpha)} f'(u_0(y_+(x, t))) \\
&\leq f'(p_\alpha).
\end{aligned}$$

Hence

$$R(t, \alpha) \leq y_-(t, \alpha) + tf'(p_\alpha).$$

Similarly by letting  $z \downarrow R(t, \alpha)$  to obtain  $R(t, \alpha) \geq y_+(t, \alpha) + tf'(p_\alpha)$ . Hence  $y_+(t, \alpha) \leq y_-(t, \alpha)$  for all  $t > T$ , which contradicts (3.50). This proves (7).

Let  $B_1 \leq \alpha \leq B_2$ , then from (3.45) and (3.46) we have

$$\begin{aligned}
f'(u_-) &\leq \lim_{t \rightarrow \infty} \frac{R_-(t, \alpha) - y_\pm(t, \alpha)}{t} \leq f'(u_+) \\
f'(u_-) &\leq \lim_{t \rightarrow \infty} \frac{R_+(t, \alpha) - Y_\pm(t, \alpha)}{t} \leq f'(u_+).
\end{aligned}$$

This implies  $u_- \leq p_\alpha \leq u$ . This proves (8) and hence the Lemma.

**Definition 3.9 (Asymptotically single shock packet ( ASSP )):** Let  $B_1 \leq c_1 < c_2 \leq B_2$  and  $u_- \leq p \leq u_+$  are given. Denote the parallel lines at  $c_1$  and  $c_2$  by

$$\begin{aligned}
r(t, c_1, p) &= c_1 + tf'(p) \\
r(t, c_2, p) &= c_2 + tf'(p) \\
D(c_1, c_2, p) &= \{(x, t); c_1 + tf'(p) < x < c_2 + tf'(p)\}.
\end{aligned}$$

$D(c_1, c_2, p)$  is called an Asymptotically single shock packet ( ASSP) if there exist  $\alpha \in (B_1, B_2)$  such that  $D(c_1, c_2, p) = D_\alpha$ . Denote

$$ASH = \{D(c_1, c_2, p); D(c_1, c_2, p) \text{ is ASSP} \}$$

called the Asymptotically shock set.

**Definition (3.10):** Let  $\alpha \in [B_1, B_2]$  is called a singular point if  $\alpha$  is not a left or a right regular point.

**Lemma 3.11**

1. Let  $D(c_1, c_2, p)$  be ASSP. Then  $D(c_1, c_2, p)$  does not contain a characteristic line and every  $\alpha \in (c_1, c_2)$  is a singular point.

2. *ASH consists of countable disjoint open sets given by  $ASH = \{D_i = D(c_{1,i}, c_{2,i}, p_i)\}_{i \in I}$  and  $\cup_{i \in I} (c_{1,i}, c_{2,i})$  consists of all singular points in  $(B_1, B_2)$ .*
3. *Let  $\Gamma_1(t_0) \leq x_0 \leq \Gamma_2(t_0)$ . If  $(x_0, t_0) \notin \cup_{i \in I} D_i$ , then  $(x_0, t_0)$  lies on a characteristic line.*

**Proof.** From (3) of Lemma 3.8,  $D_\alpha$  does not contain a characteristic line. Hence if  $\alpha \in (c_1, \alpha_2)$  is a left or right regular point, then  $D_\alpha$  contains a characteristic line, which is a contradiction. This proves (1).

From Lemma 3.8 either  $D_\alpha = D_\beta$  or  $D_\alpha \cap D_\beta = \phi$ . Hence ASH is countable. Let  $\alpha \in (B_1, B_2)$  be a singular point. Then there exist  $T > 0$  such that for all  $t > T$ ,  $B_1 \leq y_-(t, \alpha) < \alpha < y_+(t, \alpha) \leq B_2$ . Hence from Lemma 3.8,  $D_\alpha$  is an ASSP and hence for some  $i$ ,  $D_\alpha = D(c_{1,i}, c_{2,i}, p_i)$ . This proves (2).

Let  $(x_0, t_0) \notin \cup_{i \in I} D_i$ ,  $\Gamma_1(t_0) \leq x_0 \leq \Gamma_2(t_0)$  and  $\alpha = y(x_0, t_0)$ . Then  $\alpha \in [B_1, B_2]$  and  $R_-(t_0, \alpha) \leq x_0 \leq R_+(t_0, \alpha)$ . If  $\alpha$  is a singular point, then from (2),  $(x_0, t_0) \in D_i$  for some  $i$ , which is a contradiction. Hence  $\alpha$  is not a singular point. Now we have to consider three cases.

**Case (1) :**  $\alpha$  is regular point.

In this case  $R_-(t, \alpha)$  and  $R_+(t, \alpha)$  are characteristic line denoted by

$$R_\pm(t, \alpha) = \alpha + t f'(p_\pm).$$

Then from (2.27), for  $R_-(t, \alpha) < x < R_+(t, \alpha)$ ,  $f'(u(x, t)) = \frac{x-\alpha}{t}$  and hence  $(x_0, t_0)$  lies on the characteristic line  $\alpha_0 + t \left( \frac{x_0-\alpha}{t_0} \right)$ .

**Case (2) :**  $\alpha$  is left regular but not right regular. Then from (4) of Lemma 3.8  $D_\alpha = D(\alpha, A_{2,\alpha}, p_\alpha)$  be in ASSP. Since  $(x_0, t_0) \notin D_\alpha$  and hence

$$R_-(t_0, \alpha) \leq x_0 \leq \alpha + t_0 f'(p_\alpha) = r(t_0) \leq R_+(t_0, \alpha)$$

and  $\alpha + t f'(p_\alpha)$  is a characteristic line. Since  $\alpha$  is left regular point, hence  $R_-(t, \alpha)$  is a characteristic line. Hence from (2.21),  $f'(u(x_0, t_0)) = \frac{x_0-\alpha}{t}$  and  $\alpha + \theta \left( \frac{x_0-\alpha}{t_0} \right)$  is a characteristic line. Hence  $(x_0, t_0)$  lies on a characteristic line. Similar reasoning follows if  $\alpha$  is right regular but not left regular. This proves the Lemma.

Next we decompose the region  $\Omega = R \times (0, \infty)$  into several parts such that the behavior of the solution  $u$  is well understood.

Define  $F_\pm$  the region of constants,  $D_\pm$  the rarefaction regions,  $S$  the region of shocks,  $R$  the regular region,  $E$  the effective region where shocks and rarefaction occurs.

Let  $\{D_i = D(c_{1,i}, c_{2,i}, p_i)\}$  be the collection of all ASSP. Then define

$$F_- = \{(x, t) : x \leq R_-(t, A_1) = L(t)\} \quad (3.77)$$



$$F_+ = \{(x, t) : x \geq R_+(t, A_2) = R(t)\} \quad (3.78)$$

$$D_- = \{(x, t) : L(t) < x < \Gamma_1(t)\} \quad (3.79)$$

$$D_+ = \{(x, t) : \Gamma_2(t) < x < R(t)\} \quad (3.80)$$

$$E = \{(x, t) : \Gamma_1(t) < x < \Gamma_2(t)\} \quad (3.81)$$

$$S = \cup_i D_i, R = E \setminus S. \quad (3.82)$$

They are mutually disjoint and have the following decomposition holds:

1.  $\Omega = \mathbb{R} \times (0, \infty) = F_- \cup F_+ \cup D_- \cup D_+ \cup E$ .
2.  $E = S \cup R$ .
3.  $F_{\pm}, R$  are closed sets and  $D_{\pm}, S$  are open sets.

From Lemma (3.11) if  $(x, t) \in R$ , then  $(x, t)$  lies on a characteristic line denoted by  $r_{x,t}(\theta)$  and is given by

$$\begin{aligned} r_{x,t}(\theta) &= y_+(x, t) + \theta f'(p_{x,t}) \\ &= x + (\theta - t)f'(p_{x,t}). \end{aligned} \quad (3.83)$$

Now define the  $N$  wave by

$$f'(N(x, t)) = \begin{cases} f'(u_-) & \text{if } (x, t) \in F_-, \\ f'(u_+) & \text{if } (x, t) \in F_+, \\ \frac{x-B_1}{t} & \text{if } (x, t) \in D_-, \\ \frac{x-B_2}{t} & \text{if } (x, t) \in D_+, \\ f'(p_i) & \text{if } (x, t) \in D(c_{1,i}, c_{2,i}, p_i), \\ f'(p_{x,t}) & \text{if } (x, t) \in R. \end{cases} \quad (3.84)$$

For  $G \subset R \times (0, \infty), t > 0$ , define the  $t$  section of  $G$  by

$$G_t = \{x : (x, t) \in G\}. \quad (3.85)$$

Then we have the following main result:

**Theorem 3.12** *Let  $u$  be the solution of (1.2) with initial data  $\bar{u}_0$  given by (3.8). With the notations as above we have*

(1). (i).  $u$  is a single shock solution if and only if  $u_- > u_+$  and there exist  $T > 0$  such that  $u$  is given by

$$u(x, t) = \begin{cases} u_- & \text{if } x < S(t), \\ u_+ & \text{if } x > S(t), \end{cases} \quad (3.86)$$

where

$$S(t) = L(T) + \left( \frac{f(u_+) - f(u_-)}{u_+ - u_-} \right) (t - T).$$

(ii). Let  $u_- \leq u_+$  and for  $t > 0$ ,  $f'(p_{-,t}) = \frac{L(t) - y_+(t)}{t}$ ,  $f'(p_{+,t}) = \frac{R(t) - Y_-(t)}{t}$ , then

$$\lim_{t \rightarrow \infty} (p_{-,t}, p_{+,t}) = (u_-, u_+) \quad (3.87)$$

$$f'(p_{-,t}) + \frac{y_+(t) - B_1}{t} \leq f'(N(x, t)) \leq f'(u_-) \quad \text{if } (x, t) \in D_- \quad (3.88)$$

$$f'(p_{+,t}) + \frac{y_+(t) - B_2}{t} \geq f'(N(x, t)) \geq f'(u_+) \quad \text{if } (x, t) \in D_+. \quad (3.89)$$

(2). Suppose there exist  $s_1 \geq s, s_2 \geq 2, 2 \leq j \leq s_1 - 1, 2 \leq l \leq s_2 - 1$ , such that  $f \in C^s(\mathbb{R})$ ,  $s = \max(s_1, s_2)$  and satisfying for all  $j$  and  $l$ ,

$$\begin{aligned} f^{(j)}(u_-) &= f^{(l)}(u_+) = 0, \\ f^{(s_1)}(u_-) &\neq 0, f^{(s_2)}(u_+) \neq 0, \end{aligned}$$

then there exist a  $M_1 > 0$  such that for  $t \geq 1$ ,

$$\int_{D_{-,t}} |f'(u(x, t)) - f'(N(x, t))| \leq \frac{M_1}{t^{1/s_1}} \quad (3.90)$$

$$\int_{D_{+,t}} |f'(u(x, t)) - f'(N(x, t))| \leq \frac{M_1}{t^{1/s_2}} \quad (3.91)$$

(See also Remark 3.21 for generalization).

(3).  $N$  is a non decreasing continuous function in  $D_{-,t} \cup D_{+,t} \cup E_t$  and satisfying

$$u_- \leq N(x, t) \leq u_+ \quad \text{if } (x, t) \in E \quad (3.92)$$

$$u(x, t) = N(x, t) \quad \text{if } (x, t) \in R \quad (3.93)$$

$$\int_{E_t} |f'(u(x, t)) - f'(N(x, t))| dx \leq 2 \frac{(B_2 - B_1)}{t}. \quad (3.94)$$

(4). Let  $I = [-\|\bar{u}_0\|_\infty + 1, \|\bar{u}_0\|_\infty + 1]$  and suppose there exists  $C > 0, r > 0$  such that for all  $x, y \in I$

$$\frac{|x - y|^r}{N} \leq C |f'(x) - f'(y)|, \quad (3.95)$$

then there exists  $T > 0$  such that for all  $t \geq T$ ,

$$\int_{-\infty}^{\infty} |u(x, t) - N(x, t)|^r dx \leq CM \left( \frac{1}{t^{1/s_1}} + \frac{1}{t^{1/s_2}} \right) + \frac{2N(B_2 - B_1)}{t}.$$

(5). Let  $\alpha, \beta$  ( may be different from  $k_1, k_2$  as defined in (3.2) and (3.3)) be such that for  $t > 0$

$$A_1 + tf'(\alpha) \leq L(t) \leq R(t) \leq A_2 + tf'(\beta)$$

then

$$\alpha \leq u_- \leq u_+ \leq \beta. \quad (3.96)$$

If  $\alpha = \beta$ , then for all  $(x, t) \in \mathbb{R} \times \mathbb{R}_+$

$$N(x, t) = u_- = u_+. \quad (3.97)$$

### Proof.

(1). (i). First deal with the single shock case. That is there exists  $T > 0$  such that  $L(T) = R(T)$  and therefore from Lemma 3.1  $u_- > u_+$  and  $u$  is given by (3.86). Conversely, let  $u_- > u_+$ . Suppose for all  $t > 0, L(t) < R(t)$  then from (3.34),  $\Gamma_1(t) \leq \Gamma_2(t)$  for all  $t > 0$  and hence  $f'(u_-) \leq f'(u_+)$  which contradicts  $u_- > u_+$ . Therefore there exist  $T > 0$  such that  $L(T) = R(T)$  and (3.86) follows from Lemma 3.1.

(ii). Let  $u_- \leq u_+$ , (3.87) follow from (3.30) and (3.31). Let  $(x, t) \in D_-$ , then  $f'(N(x, t)) = \frac{x - B_1}{t}$  and hence

$$\begin{aligned} f'(p_{-,t}) + \frac{y_+(t) - B_1}{t} &= \frac{L(t) - B_1}{t} \\ &\leq \frac{x - B_1}{t} = f'(N(x, t)) \\ &\leq \frac{\Gamma_1(t) - B_1}{t} = f'(u_-) \end{aligned}$$

this proves (3.88) and (3.89) follows similarly.

(2). From (3.32) we have

$$L(t) \geq y_+(t) + tf'(u_-) - \frac{Mt}{t^{1/s_1}}$$

and for a.e  $x \in D_{-,t}$ ,  $f'(u(x,t)) = \frac{x-y_+(x,t)}{t}$ . Since  $L(t) < x < \Gamma_1(t)$  and  $y_{\pm}(\Gamma_1(t), t) = B_1$ , hence from monotonicity,  $A_1 \leq y_+(x, t) \leq B_1$ . Therefore

$$\begin{aligned} & \int_{L(t)}^{\Gamma_1(t)} |f'(u(x,t)) - f'(N(x,t))| dx \\ & \leq \int_{y_+(t)+tf'(u_-)-\frac{Mt}{t^{1/s}}}^{B_1+tf'(u_-)} \left| \frac{x-y_+(x,t)}{t} - \frac{x-B_1}{t} \right| dx \\ & \leq \frac{B_1-A_1}{t} [B_1 - y_+(t) + \frac{Mt}{t^{1/s}}]. \end{aligned}$$

This proves (3.90) and (3.91) follows similarly.

- (3). Since  $N$  is a rarefaction wave in  $D_{\pm}$  and hence it is continuous and non decreasing function in  $\bar{D}_{\pm,t}$ . Let  $y \in E_t$ , then from (3) of Lemma (3.9) either  $y \in D_{i,t}$  for some  $i$  or  $y \in R_t$ . Since  $N$  is constant on  $D_{i,t}$  hence to prove continuity or monotonicity of  $N$  in  $E_t$ , it is enough to prove this in  $R_t$ . Let  $y_k \leq y_1 < y_2$  are in  $R_t$  with  $\lim_{k \rightarrow \infty} y_k = y_1$ . Let  $r_k, r_1, r_2$  be the characteristic lines with reciprocal slopes  $f'(p_k), f'(q_1), f'(q_2)$  respectively. Hence  $y_k = r_k(t), y_1 = r_1(t), y_2 = r_2(t)$  and from monotonicity of  $x$  in  $y_{\pm}(x, t)$ , and from Lemma (3.2),  $r_k(0) \leq r_1(0) \leq r_2(0)$ . This implies  $r_k(s) \leq r_1(s) \leq r_2(s)$  for all  $s$ ,  $p_k \leq q_1 \leq q_2$  and  $\lim_{k \rightarrow \infty} p_k = q_1$ . Therefore from Lemma 3.2,

$$\begin{aligned} u(y_1, t) &= q_1 = N(y_1, t), N(y_1, t) = q_1 \leq q_2 = N(y_2, t) \\ N(y_1-, t) &= \lim_{k \rightarrow \infty} N(y_k, t) \\ &= \lim_{k \rightarrow \infty} p_k \\ &= q_1 \\ &= N(y_1, t). \end{aligned}$$

Similarly for the right limit. Since  $\partial E = \Gamma_1(t) \cup \Gamma_2(t)$  and from monotonicity of  $N$ , it follows that  $u_- \leq N(x, t) \leq u_+$  and

$$\begin{aligned} \int_{E_t} |f'(u(x,t)) - f'(N(x,t))| dx &= \sum_{i \in I} \int_{D_{i,t}} |f'(u(x,t)) - f'(p_i)| \\ &= \sum_i \int_{c_{1,i}+tf'(p_i)}^{c_{2,i}+tf'(p_i)} \left| \frac{x-y_+(x,t)}{t} - f'(p_i) \right| \\ &= \sum_i \int_{c_{1,i}+tf'(p_i)}^{c_{2,i}+tf'(p_i)} \left| \frac{x-tf'(p_i)}{t} - \frac{y_+(x,t)}{t} \right| dx \end{aligned}$$

$$\leq \frac{2}{t} \sum |c_{2,i} - c_{1,i}| \leq \frac{2}{t} |B_2 - B_1|$$

since  $c_{1,i} \leq y_+(x, t) \leq c_{2,i}$ . This proves (3).

- (4). From (3.87) to (3.95) there exist a  $T > 0$  such that for all  $t \geq T, N(x, t) \in I$ .  
Hence

$$\begin{aligned} & \int_{-\infty}^{\infty} |u(x, t) - N(x, t)|^r dx = \int_{D_{-,t}} |u(x, t) - N(x, t)|^r dx + \\ & \int_{E_t} |u(x, t) - N(x, t)|^r dx + \int_{D_{+,t}} |u(x, t) - N(x, t)|^r dx \\ & \leq C \left[ \int_{D_{-,t}} |f'(u(x, t)) - f'(N(x, t))| dx + C \int_{E_t} |f'(u(x, t)) - f'(N(x, t))| dx \right. \\ & \left. + C \int_{D_{+,t}} |f'(u(x, t)) - f'(C(x, t))| dx \right] \\ & \leq CM \left( \frac{1}{t^{1/s_2}} + \frac{1}{t^{1/s_2}} \right) + \frac{2C(B_2 - B_1)}{t}. \end{aligned}$$

This proves (4).

- (5). Since  $L(t) \leq \Gamma_1(t) \leq \Gamma_2(t) \leq R(t)$ , hence dividing by  $t$  and letting  $t \rightarrow \infty$  to obtain,  $f'(\alpha) \leq f'(u_-) \leq f'(u_+) \leq f'(\beta)$ . If  $\alpha = \beta$ , then  $u_- = u_+$  and hence from (3.92),  $N = u_-$ . This proves (5) and hence the theorem.

Next we give some criterion for non existence of ASSP.

**Theorem 3.13** *Let  $\bar{u}_0$  be a continuous function with compact support. Let*

$$G = \{\alpha \in \mathbb{R} : \bar{u}_0(\alpha) = 0\} \quad (3.98)$$

*and assume that for any  $\alpha < \beta, \alpha, \beta \in G$*

$$\int_{\alpha}^{\beta} \bar{u}_0(\theta) d\theta \neq 0, \quad (3.99)$$

*then ASSP does not exist.*

**Proof.** Let  $D_i = D(c_{1,i}, c_{2,i}, p_i)$  be a ASSP. Since  $u_- = u_+ = 0$  and hence  $p_i = 0$  and from (3.59)  $\bar{u}_0(c_{1,i}) = \bar{u}_0(c_{2,i}) = 0$ . Hence  $c_{1,i}, c_{2,i} \in G$  and from (3.99) and (3.58) we have

$$\int_{c_{1,\alpha}}^{c_{2,\alpha}} \bar{u}_0(\theta) d\theta = 0,$$

which is a contradiction. This proves the theorem.

**Example 3.14. (Existence of  $u_0 \in C_c^\infty$  for which the solution of (1.2) admits infinitely many ASSP):** Let  $u_0 \in C_c^\infty(\mathbb{R})$  and  $u$  be the solution of (1.2) with initial data  $u_0$ . First observe that if an ASSP exist, then  $u_0$  necessarily satisfy the compatibility conditions (3.58), (3.59) and having the same parity at the end points. Hence we look for data satisfying these conditions.

First we construct a solution having single ASSP. From this we construct a data having infinitely ASSP.

Let  $A_1 < \alpha_1 < \alpha_2 < A_2$  and  $u_0 \in C_c^\infty(\mathbb{R})$  such that

1. Support of  $u_0 \subset [A_1, A_2]$ .
2.  $\int_{A_1}^{A_2} u_0(x) dx = 0$ .
3.  $0 < u(\alpha_1) = \max u$ ,  $0 > u(\alpha_2) = \min u$ ,

and  $u_0$  is strictly increasing in  $(A_1, \alpha_1) \cup (\alpha_2, A_2)$  and strictly decreasing in  $(\alpha_1, \alpha_2)$ . Then

**Lemma 3.15** *Assume that  $f(0) = f'(0) = 0$  and  $u$  be the solution of (1.2) with initial data  $u_0$ . Then  $u$  admits a single ASSP in  $D = (A_1, A_2) \times (0, \infty)$  and satisfies for all  $x \notin (A_1, A_2), t > 0$*

$$u(x, t) = u(A_1+, t) = u(A_2-, t) = 0. \quad (3.100)$$

**Proof.** Let  $\alpha_1 < \beta < \alpha_2$  be such that  $u_0(\beta) = 0$ . Then  $u_0 > 0$  in  $(A_1, \beta)$  and  $u_0 < 0$  in  $(\beta, A_2)$ . Let  $R_1(t) = R_-(t, \alpha_1, u_0), R_2(t) = R_+(t, \alpha_2, u_0)$ .

$$y_\pm(t) = y_\pm(R_1(t), t, u_0), Y_\pm(t) = y_\pm(R_2(t), t, u_0). \\ y_\pm(x, t) = y_\pm(x, t, u_0).$$

**Claim 1:** Let  $t_0 > 0$  such that for  $0 < t < t_0, A_1 < R_1(t)$ . Then for all  $z < A_1 < x < R_1(t)$

$$A_1 \leq y_-(x, t) \leq y_+(x, t) \leq \alpha_1 \quad (3.101)$$

$$u(A_1+, t) = u(z, t) = 0. \quad (3.102)$$

Suppose for some  $x_1 \in (A_1, R_1(t)), y_-(x_1, t) < A_1$ , then for all  $x < x_1, y_-(x, t) < A_1$ . Since  $u_0$  is differentiable and hence from (2.12) and (2.13) for a.e.  $x \in (A_1, x_1)$

$$0 = f'(0) = f'(u_0(y_-(x, t))) = f'(u(x, t)) = \frac{x - y_-(x, t)}{t}$$

and hence  $y_-(x, t) < A_1 < x = y_-(x, t)$  which is a contradiction. This proves (3.101).

Let  $z_0 < A_1$  be such that  $y_+(z_0, t) > A_1$ , then for all  $z \in (z_0, A_1)$ ,  $y_+(z, t) > A_1$ . Then from NIP, it follows that  $y_+(z, t) \leq y_-(t) \leq \alpha_1$  and hence  $u_0(y_+(z, t)) > 0$ . Hence from (2.12) and (2.13)

$$0 < f'(u_0(y_+(z, t))) = f'(u(z, t)) = \frac{z - y_+(z, t)}{t}$$

and hence  $A_1 > z > y_+(z, t) \geq A_1$  which is a contradiction. Hence  $y_+(z, t) \leq A_1$  for all  $z < A_1$ . Suppose for some  $z_0 < A_1$ ,  $y_+(z_0, t) = A_1$ , this implies that for all  $z \in (z_0, A_1)$ ,  $y_\pm(z, t) = A_1$ . For  $z < R_-(A_1, t)$ ,  $y_+(z, t) < A_1$  and hence from (2.13),

$$\frac{z - y_+(z, t)}{t} = f'(u(z, t)) = f'(u_0(y_+(z, t))) = f'(0) = 0.$$

Hence  $z = y_+(z, t)$  and hence from (2.22),  $y_-(R_-(A_1, t), t) = R_-(A_1, t)$ . Let  $v_0 = \int_{A_1}^x u_0(\theta) d\theta$ , and  $y_\pm = y_\pm(R_-(A_1, t), t)$ . Since  $y_- = R_-(A_1, t)$ ,  $y_+ = A_1$ , hence from (2.3)

$$\begin{aligned} v_0(y_-) + t f^* \left( \frac{R_-(y_-, t) - y_-}{t} \right) &= v_0(y_+) + t f^* \left( \frac{R_-(A_1, t) - y_+}{t} \right) \\ 0 = f^*(f'(0)) = f^*(0) &= f^* \left( \frac{R_-(A_1, t) - y_+}{t} \right). \end{aligned}$$

Hence from the strict convexity,  $A_1 > R_-(A_1, t) = y_+ = A_1$  which is a contradiction. Therefore  $y_+(z, t) < A_1$  for  $z < A_1$  and from (2.13),  $0 = f'(u_0(y_+(z, t))) = f'(u(z, t)) = \frac{z - y_+(z, t)}{t}$ . Hence  $z = y_+(z, t)$  and  $u(z, t) = 0$ . Therefore  $u(A_1-, t) = \lim_{z \uparrow A_1} u(z, t) = 0$ . Hence from RH condition across  $x = A_1$ ,  $0 < t < t_0$  gives  $u(A_1+, t) = 0$ . This proves (3.102).

**Claim 2:** Let  $t_1 > 0$  such that for  $0 < t < t_1$ ,  $R_2(t) < A_2$ , then for  $R_2(t) < x < A_2 < z$

$$\alpha_2 \leq y_-(x, t) \leq y_+(x, t) \leq A_2 \quad (3.103)$$

$$u(A_2-, t) = u(z, t) = 0. \quad (3.104)$$

Proof follows exactly as in claim 1.

**Claim 3:** Let  $t_0 > 0$  such that for all  $0 < t < t_0$ ,

$$A_1 < R_1(t) \leq R_2(t) < A_2 \quad (3.105)$$

then

$$A_1 < R_1(t_0) < A_2, A_1 < R_2(t_0) < A_2. \quad (3.106)$$

Suppose  $R_1(t_0) = A_1$ . Then  $A_1 = R_1(t_0) \leq R_2(t_0) \leq A_2$ . At  $R_1(t_0), y_+(t_0) \geq \alpha_1$ , hence for  $R_1(t_0) < x < \alpha_1, y_+(x, t_0) \geq \alpha_1$ . Hence from (2.12) and (2.13) for a.e.  $x \in (R_1(t_0), \alpha_1)$ ,

$$f'(u_0(y_+(x, t))) = f'(u(x, t)) = \frac{x - y_+(x, t_0)}{t_0} < \frac{\alpha_1 - \alpha_1}{t_0} = 0.$$

Therefore  $u_0(y_+(x, t)) < 0$  and hence  $y_+(x, t) > \beta$ . Hence from monotonicity, for all  $x > R_1(t_0) = A_1, y_+(x, t) > \beta$ . Hence from (3.103), for all  $x \in (A_1, A_2)$ .

$$\beta \leq y_+(x, t) < A_2$$

. Therefore from the hypothesis on  $u_0$  and from (2.13) we have for a.e.  $x \in (A_1, A_2)$

$$u(x, t_0) = u_0(y_+(x, t_0)) < 0. \quad (3.107)$$

From (3.103), (3.103) and (3.104)  $u(A_1+, t) = u(A_2-, t) = 0$ . Hence from (1.107) we have

$$\begin{aligned} 0 &= \int_{A_1}^{A_2} \int_0^{t_0} (u_t + f(u)_x) dx dt = \int_{A_1}^{A_2} u(x, t_0) dx - \int_{A_1}^{A_2} u_0(x) dx \\ &= \int_{A_1}^{A_2} u(x, t_0) dx < 0, \end{aligned}$$

which is a cotradiction. Similarly  $R_2(t_0) \in (A_1, A_2)$  and this proves the claim.

Since for  $t$  small,  $A_1 < R_1(t) < R_2(t) < A_2$  and hence from claim (3),  $A_1 < R_1(t) \leq R_2(t) < A_2$  for all  $t > 0$ . Since  $A_1 \leq y_{\pm}(t) \leq A_2$  and  $A_1 < R_1(t) < A_2$  hence from Lemma 3.8 there exist ASSP  $D = (\tilde{A}_1, \tilde{A}_2, p)$  such that

$$\begin{aligned} (\tilde{A}_1, \tilde{A}_2) &= \lim_{t \rightarrow \infty} (y_-(t), y_+(t)) \\ f'(p) &= f'(0) = 0 \\ u_0(\tilde{A}_1) &= u_0(\tilde{A}_2) = 0, \end{aligned}$$

and  $\tilde{A}_1$  and  $\tilde{A}_2$  have the same parity. Since  $u_0$  has only three zeros  $\{A_1, \beta, A_2\}$  and  $A_1$  and  $A_2$  are the only pair of points having same parity. Hence  $\tilde{A}_1 = A_1, \tilde{A}_2 = A_2$  and this proves the Lemma.

**Theorem 3.16** *Let  $f(0) = f'(0) = 0$ . Then there exist a  $\bar{u}_0 \in C_c^\infty(\mathbb{R})$  such that the corresponding solution  $u$  of (1.2) with initial data has infinitely ASSP.*

**Proof.** Let  $u_0$  be as in Lemma (3.15) with  $A_1 = -1, A_2 = 1$ . For  $n \geq 2$ . define  $\{\psi_{0,n}, u_n\}$  as follows

$$\psi_{0,n}(x) = e^{-n} u_0(2n^2(x - \frac{1}{n})).$$



Then  $\psi_{0,n} \in C_c^\infty(\mathbb{R})$  and support of  $\psi_{0,n}$  is contained in  $(\frac{1}{n} - \frac{1}{2n^2}, \frac{1}{n} + \frac{1}{2n^2})$  and for each  $k$ , there exists  $c(k) > 0$  such that

$$\left\| \frac{d^k \psi_{0,n}}{dx^k} \right\|_\infty \leq c(k)n^2 e^{-n} \rightarrow 0 \text{ as } n \rightarrow \infty. \quad (3.108)$$

$\psi_{0,n}$  satisfies all the hypothesis of Lemma 3.14 and let  $u_n$  be the corresponding solution. Define  $\bar{u}_0$  and  $u$  by

$$\bar{u}_0(x) = \begin{cases} \psi_{0,n}(x) & \text{if } x \in (\frac{1}{n} - \frac{1}{2n^2}, \frac{1}{n} + \frac{1}{2n^2}), \\ 0 & \text{otherwise.} \end{cases} \quad (3.109)$$

$$u(x, t) = \begin{cases} u_n(x, t) & \text{if } x \in (\frac{1}{n} - \frac{1}{2n^2}, \frac{1}{n} + \frac{1}{2n^2}), \\ 0 & \text{otherwise,} \end{cases} \quad (3.110)$$

then from (3.102),(3.104) ,  $u$  is a solution of (1.2) with initial condition  $\bar{u}_0$ . From (3.108),  $\bar{u}_0 \in C_c^\infty(\mathbb{R})$  and  $u$  is ASSP in  $(\frac{1}{n} - \frac{1}{2n^2}, \frac{1}{n} + \frac{1}{2n^2})$  for all  $n \geq 2$ . This proves the theorem.

**Example 3.17:** (See Figure 13) Next we construct a ASSP which contains infinitely many shocks. Let  $f(u) = \frac{u^2}{2}$  and  $0 = x_0 < x_1 < x_2 < \dots < 1$  and  $0 = t_0 < t_1 <$

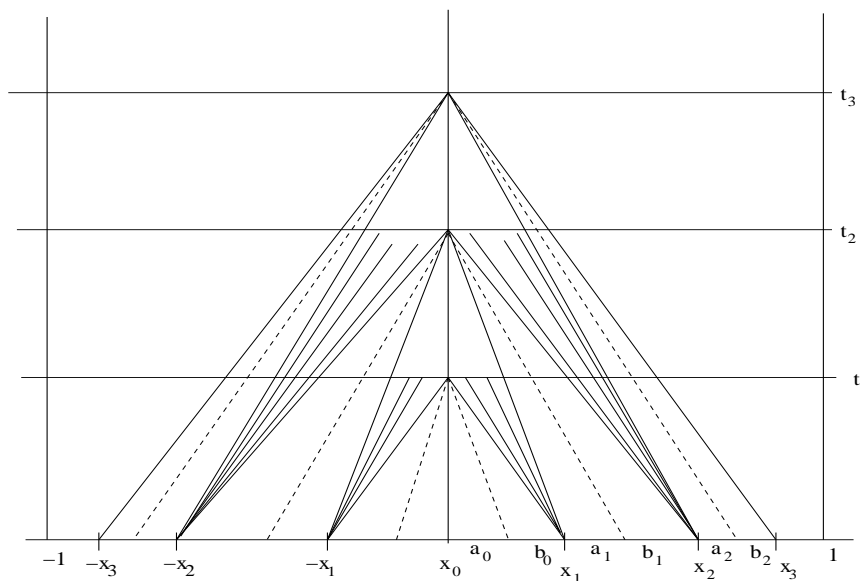


Figure 13:

$t_2 \dots < \infty$  be such that

$$\lim_{n \rightarrow \infty} x_n = 1, \lim_{n \rightarrow \infty} \frac{x_n}{t_n} = 0.$$

Define for  $n \geq 1$ ,  $a_n, b_n, l_n, m_n, \tilde{a}_n, \tilde{b}_n, \tilde{l}_n, \tilde{m}_n$  as follows:

$$\begin{aligned}
f'(a_n) &= -f'(\tilde{a}_n) = \frac{-x_{n-1}}{t_n} \\
f'(b_n) &= -f'(\tilde{b}_n) = \frac{-x_n}{t_n} \\
l_n(t) &= -\tilde{l}_n(t) = x_{n-1} + t f'(a_n) \\
m_n(t) &= -\tilde{m}_n(t) = x_n + t f'(b_n). \\
s_n(t) &= (t - t_n) \frac{f(a_n) - f(b_n)}{a_n - b_n} \\
\tilde{s}_n(t) &= -s_n(t) \\
-\tilde{\alpha}_n &= \alpha_n = s_n(0).
\end{aligned}$$

Since  $x_{n-1} < x_n$  and hence  $f'(a_n) = -\frac{x_{n-1}}{t_n} > -\frac{x_n}{t_n} = f'(b_n)$ , therefore  $b_n < a_n$  and

$$\begin{aligned}
f'(b_n) &< \frac{f(a_n) - f(b_n)}{a_n - b_n} < f'(a_n), \\
x_{n-1} = -t_n f'(a_n) &< -t_n \frac{f(a_n) - f(b_n)}{a_n - b_n} < -t_n f'(b_n) = x_n, \\
l_n(0) &< s_n(0) < m_n(0).
\end{aligned}$$

Define  $u_+(x, t)$  for  $x > 0, t > 0$  by

$$u_+(x, t) = \begin{cases} a_n & \text{if } 0 < t < t_n, l_n(t) < x < s_n(t), \\ b_n & \text{if } 0 < t < t_n, s_n(t) < x < m_n(t), \\ (f')^{-1} \left( \frac{x - x_{n+1}}{t} \right) & \text{if } 0 < t < t_n, m_n(t) < x < l_{n+1}(t), \\ 0 & \text{otherwise,} \end{cases}$$

and  $u$  and  $u_0$  by

$$\begin{aligned}
u(x, t) &= \begin{cases} u_+(x, t) & \text{if } x > 0, t > 0, \\ -u_+(-x, t) & \text{if } x < 0, t > 0, \end{cases} \\
u_0(x) &= u(x, 0).
\end{aligned}$$

On the line  $x = 0$ ,  $u(0+, t) = -u(0-, t)$  and hence  $\frac{1}{2}(u(0+, t) + u(0-, t)) = 0$ . this implies  $u$  satisfies RH condition across  $x = 0$  and hence  $u$  is the solution of (1.2) with initial data  $u_0$ . Furthermore  $u = 0$  for  $|x| \geq 1$  and  $D = (-1, 1) + (0, \infty)$  is an ASSP and each line  $s_n(t)$  and  $\tilde{s}_n(t)$  for  $0 < t < t_n$  is a shock curve.

**Remark 3.18** *In example (3.14), one can relax the conditions on  $u_0$  as follows Let  $u_0$  be a bounded measurable function with support of  $u_0$  is in  $[A_1, A_2]$ . Let*

$$z(u_0) = \{x \in [A_1, A_2] : u_0(x) = 0\}$$

*be its zero set and satisfies the following conditions*

(1).  $u_0$  is monotone in a neighbourhood of  $z(u_0)$ .

(2).  $\int_{A_1}^{A_2} u_0(x)dx = 0$  and whenever  $\alpha < \beta, \alpha, \beta \in z(u_0), \int_{\alpha}^{\beta} u_0(x)dx = 0$ , then  $\alpha = A_1, \beta = A_2$ .

(3).  $u_0$  is a non decreasing in a neighbourhood of  $A_1, A_2$ , then

**Lemma 3.19** *Let  $u_0$  satisfies the above conditions and  $u$  be the solution of (1.2) with initial data  $u_0$ . Then  $D = (A_1, A_2) \times (0, \infty)$  is the only ASSP for  $u$  and  $u(x, t) = 0$  for  $x \notin (A_1, A_2)$ .*

Proof follows exactly as in example (3.14).

**Remark 3.20** *First observe that if  $u$  is a solution of (1.2) such that  $u(x, t)$  is non decreasing function in  $(\alpha, \beta)$ . Then  $u(\cdot, t)$  is continuous in  $(\alpha, \beta)$ . This follows easily from entropy condition. For  $\alpha < x_1 < x < x_2 < \beta$ , then  $u(x, t) \leq u(x, t) \leq u(x_2, t)$  and hence  $u(x-, t) \leq u(x+, t)$ . From the entropy condition  $u(x-, t) \geq u(x+, t)$  and hence  $u(x-, t) = u(x+, t)$  and this proves the continuity.*

**Remark 3.21** *In Theorem 3.21, the decay estimates (3.90), (3.91) are obtained under the assumption that  $f$  is smooth. If  $f(u) = |u|^p$  for  $1 < p < 2$ , then  $f$  is strictly convex and  $C^1$  but not  $C^2$ . This case had been dealt by Liu-Pierre [20] and generalised by Kim [17] to obtain decay estimates when  $u_- = u_+ = 0$ .*

Since decay estimates of Theorem 3.21 depends on (3.40). Hence here also one can relax the condition on  $f$  so is to give the proper decay estimates and is as follows: Assume that  $f$  satisfies

(1).  $f$  is  $C^1$  and strictly convex. That is for  $a, b \in \mathbb{R}$

$$f(a) - f(b) - (a - b)f'(b) = 0 \text{ if and only if } a = b. \quad (3.111)$$

(2).  $f^* \in C^1$  and both  $f$  and  $f^*$  are of super linear growth.

(3). At  $u_{\pm}$ , there exist a  $r > 0, \delta > 0, C > 0$  such that for  $|h| \leq \delta$

$$f(u_{\pm}) - f(u_{\pm} + h) - hf'(u_{\pm} + h) \geq C|h|^{\gamma}. \quad (3.112)$$

(4). For any compact interval  $I$ , there exist  $C(I) > 0$  such that

$$|f'(a) - f'(b)| \leq C(I)|a - b|^{\gamma-1}. \quad (3.113)$$

Then we have the following

**Decay estimates at the boundary:** Let  $f$  satisfies (1) to (4). Let  $L(t), R(t), y_+(t)$ ,

$Y_-(t)$  be above and define by

$$f'(P_{+,t}) = \frac{L(t) - y_+(t)}{t} \quad (3.114)$$

$$f'(P_{-,t}) = \frac{R(t) - Y_-(t)}{t}. \quad (3.115)$$

Then from superlinearity of  $f^*$  and from Lemma 3.2, 3.40,  $\{P_{\pm,t}\}$  are bounded and satisfies

$$f(u_{\pm}) - f(P_{\pm,t}) - (u_{\pm} - P_{\pm,t})f'(P_{\pm,t}) = O\left(\frac{1}{t}\right). \quad (3.116)$$

Let for a sequence  $t_k \rightarrow \infty$ ,  $P_{\pm,t_k} \rightarrow P_{\pm}$ . Then letting  $t_k \rightarrow \infty$  in (3.111), to obtain

$$f(u_{\pm}) - f(P_{\pm}) - (u_{\pm} - P_{\pm})f'(P_{\pm}) = 0.$$

Hence from (3.11),  $u_{\pm} = P_{\pm}$  and therefore

$$\lim_{t \rightarrow \infty} (P_{+,t}, P_{-,t}) = (u_+, u_-). \quad (3.117)$$

From (3.12) and (3.117), for large  $t$ , it follows that

$$|u_{\pm} - P_{\pm,t}| = O\left(\frac{1}{t^{1/\gamma}}\right), \quad (3.118)$$

and from (3.114)

$$|f'(u_{\pm}) - f'(P_{\pm,t})| = O\left(\frac{1}{t^{(\gamma-1)/\gamma}}\right). \quad (3.119)$$

This implies that

$$\int_{-\infty}^{\infty} |f'(u(x,t)) - f'(N(x,t))| = O\left(\frac{1}{t^{(\gamma-1)/\gamma}}\right). \quad (3.120)$$

Furthermore, if  $f$  satisfies (3.95) then

$$\int_{-\infty}^{\infty} |u(x,t) - N(x,t)|^r = O\left(\frac{1}{t^{(\gamma-1)/\gamma}}\right). \quad (3.121)$$

**Lemma 3.21** *Let  $u$  and  $u_0$  be as in Lemma 3.19. Assume that  $u_0$  is continuous in a neighbourhood of  $A_1$  and  $A_2$ . Then there exists  $T > 0$  such that for all  $t > T$ ,  $u(x,t)$  has just one discontinuity in  $x \in (A_1, A_2)$ .*

**Proof.** Let  $A_1 < r_1 < r_2 < A_2$  be such that  $u_0$  is continuous non decreasing function in  $(A_1, r_1) \cup (r_2, A_2)$ . Let  $T$  be the first point at which  $R_0 = R_-(T, r_1, u_0) = R_+(T, r_2, u_0) \in D$ . Then from (2.27), for all  $t > T$ ,  $R(t) = R_-(t, r_1, u_0) = R_+(t, r_2, u_0)$ . Let  $A_1 < x_1 < x_2 < R(t)$ , then  $A_1 \leq y_{\pm}(x_1, t, u_0) \leq y_{\pm}(x_2, t, u_0) \leq r_2$ . Since  $u_0$  is non decreasing function, hence  $u_0(y_{\pm}(x_1, t, u_0)) \leq u_0(y_{\pm}(x_2, t, u_0))$  and hence from Remark 2.20  $u_0(\cdot, t)$  is continuous in  $(A_1, R(t))$ . Similarly  $u(\cdot, t)$  is continuous in  $(R(t), A_2)$ . This proves the Lemma.

## 4 Exact Controllability:

In this section we give the proof of theorems (1.1) to (1.3). Basically following two main ideas are used to prove these results

- (a) Free regions: Using the proper choice of the parameters for initial value problems, we create a region (called free region) on which the solution will remain constant. This is achieved in Lemmas 2.9 and 2.10. For example from (2.94), the region

$$\{(x, t) : x < L_1(t)\} \quad (4.1)$$

is a free region since  $u^\lambda$  is constant.

- (b) Identify the regions where we would like to construct a solution with given target functions as free regions and can be achieved from Lemma 2.9 and 2.10. Then construct the entropy solutions in these free region and using RH condition, glue all the solutions so that it turns out to be the required solution.

We state the following Lemmas which deal with this construction. First we complete the proof of the theorems(1.1) to (1.3) and then give the proof of these Lemmas.

Let  $u_0 \in L^\infty(\mathbb{R})$ ,  $0 \leq \delta < T$ ,  $A, C \in \mathbb{R}$ . Let  $l(\cdot, \delta, A, C)$  be the line joining between  $(C, T)$  and  $(A, \delta)$  with slope  $1/f'(a(\delta, A, C))$ , intersecting  $t = 0$  axis at  $D(\delta, A, C)$  and is given by

$$f'(a(\delta, A, C)) = \frac{C - A}{T - \delta}, \quad (4.1)$$

$$l(t, \delta, A, C) = A + f'(a(\delta, A, C))(t - \delta), \quad (4.2)$$

$$D(\delta, A, C) = A - \delta f'(a(\delta, A, C)), \quad (4.3)$$

$$= A - \frac{\delta(C - A)}{T - \delta}. \quad (4.4)$$

**LEMMA 4.1** 1. Let  $\wedge > 0$ ,  $A < C$  and  $\rho \in LA((A, C))$  satisfying

$$\delta \leq \rho(x) \leq T, \quad (4.5)$$

$$\left| \frac{x - A}{T - \rho(x)} \right| \leq \wedge. \quad (4.6)$$

Let  $\Omega = (A, \infty) \times (\delta, T)$ . Then there exists a  $\tilde{b}_1(t, \delta, A, C) \in L^\infty((\delta, T))$  and a solution  $\tilde{u}_1(x, t, \delta, A, C)$  of (1.2) satisfying

$$f'(\tilde{u}_1(x, T, \delta, A, c)) = \frac{x - A}{T - \rho(x)}, \quad x \in (A, C), \quad (4.7)$$

with initial and boundary conditions

$$\tilde{u}_1(A, t, \delta, a, C) = \tilde{b}_1(t, \delta, A, C), \quad t \in (\delta, T), \quad (4.8)$$

$$\tilde{u}_1(x, t, \delta, a, C) = a(\delta, A, C), \quad x > l(t, \delta, A, C), \quad (4.9)$$

$$\tilde{u}_1(l(t, \delta, A, C)-, t, \delta, a, C) = a(\delta, A, C). \quad (4.10)$$

2. Let  $C < A$  and  $\rho \in RA((C, A))$  satisfying (4.5) and (4.6). Let  $\Omega = (-\infty, A) \times (\delta, T)$ . Then there exist  $\tilde{b}_2(t, \delta, A, C) \in L^\infty((\delta, T))$  and a solution  $\tilde{u}_2(x, t, \delta, a, C)$  of (1.2) satisfying

$$f'(\tilde{u}_2(x, T, \delta, A, C)) = \frac{x - A}{T - \rho(x)}, \quad x \in (C, A), \quad (4.11)$$

with initial and boundary conditions

$$\tilde{u}_2(A, t, \delta, A, C) = \tilde{b}_2(t, \delta, A, C), \quad t \in (\delta, T), \quad (4.12)$$

$$\tilde{u}_2(x, t, \delta, A, C) = a(\delta, a, C), \quad x < l(t, \delta, A, C), \quad (4.13)$$

$$\tilde{u}_2(l(t, \delta, A, C)+, t, \delta, A, C) = a(\delta, A, C), \quad t \in (\delta, T). \quad (4.14)$$

**LEMMA 4.2** Let  $A_1 < A_2$ ,  $C_1 < C_2$ ,  $\rho \in IA((C_1, C_2))$  such that for all  $x \in (C_1, C_2)$ ,

$$A_1 \leq \rho(x) \leq A_2. \quad (4.15)$$

Let  $\Omega = \mathbb{R} \times \mathbb{R}_+$ , for  $i = 1, 2$ ,  $l_i(t) = l(t, \delta, A_i, C_i)$ ,  $a_i = a_i(\delta, A_i, C_i)$ , then there exist  $\tilde{u}_0 \in L^\infty((A_1, A_2))$  and a solution  $\tilde{u}$  of (1.2) such that for  $\delta < t < T$ ,

$$f'(\tilde{u}(x, T)) = \frac{x - \rho(x)}{T - \delta}, \quad \text{for } x \in (C_1, C_2), \quad (4.16)$$

$$\tilde{u}(l_1(t)+, t) = a_1, \quad (4.17)$$

$$\tilde{u}(l_2(t)-, t) = a_2, \quad (4.18)$$

with initial conditions

$$\tilde{u}(x, \delta) = \begin{cases} a_1 & \text{if } x < A_1, \\ \tilde{u}_0(x) & \text{if } A_1 < x < A_2, \\ a_2 & \text{if } x > A_2. \end{cases} \quad (4.19)$$

**Proof of theorem 1.1:** Let  $\Omega = \mathbb{R} \times (0, T)$ ,  $A_i, B_i, C_i, g$  and  $s$  be as in theorem (1.1). Let

$$f'(a_1) = \frac{C_1 - A_1}{T}, \quad f'(a_2) = \frac{C_2 - A_2}{T}, \quad l_1(t) = A_1 + tf'(a_1), \quad l_2(t) = A_2 + tf'(a_2).$$

Then from Lemmas 2.9 and 2.10 we can choose  $\lambda$  and  $\mu$  and solutions  $u_1$  and  $u_2$  in  $\Omega$  with initial data's  $u_0^1$  and  $u_0^2$  respectively and is given by

$$u_0^2(x) = \begin{cases} a_2 & \text{if } x < A_2, \\ \lambda & \text{if } A_2 < x < B_2, \\ u_0(x) & \text{if } x > B_2. \end{cases} \quad (4.19)$$

$$u_2(x, t) = a_2 \text{ if } x < l_2(t), \quad (4.20)$$

$$u_2(l_2(t)+, t) = a_2. \quad (4.21)$$

$$u_0^1(x) = \begin{cases} a_1 & \text{if } x > A_1, \\ \mu & \text{if } B_1 < x < A_1, \\ u_0(x) & \text{if } x < B_1. \end{cases} \quad (4.22)$$

$$u_1(x, t) = a_1 \text{ if } x > l_1(t). \quad (4.23)$$

$$u_1(l_1(t)-, t) = a_1. \quad (4.24)$$

From (1.35) and Lemma 4.2 there exist a solution  $u_3$  of (1.2) and  $\bar{u}_0 \in L^\infty(A_1, A_2)$  satisfying

$$u_3(x, T) = g(x), \text{ if } x \in (C_1, C_2) \quad (4.25)$$

$$u_3(x, 0) = \begin{cases} a_1 & \text{if } x < A_1, \\ \bar{u}_0(x) & \text{if } A_1 < x < A_2, \\ a_2 & \text{if } x > A_2, \end{cases} \quad (4.26)$$

and

$$u_3(x, t) = \begin{cases} a_1 & \text{if } x < l_1(t), \\ a_2 & \text{if } x > l_2(t). \end{cases} \quad (4.27)$$

$$u_3(l_1(t)+, t) = a_1, u_3(l_2(t)-, t) = a_2. \quad (4.28)$$

From (4.21), (4.24), (4.28) and RH condition, glue  $u_1, u_2, u_3$  to form a single solution  $u$  of (1.2) for  $0 < t < T$  by

$$u(x, t) = \begin{cases} u_1(x, t) & \text{if } x < l_1(t), \\ u_3(x, t) & \text{if } l_1(t) < x < l_2(t), \\ u_2(x, t) & \text{if } l_2(t) < x. \end{cases} \quad (4.29)$$

Then from (4.25) and (4.26),  $(u, \bar{u}_0)$  is the required solution. This proves the theorem.

**Proof of Theorem 1.2:** Let  $f'(a) = \frac{C}{T-\delta}$  and  $l(t)$  be the line joining  $(C, T)$  and  $(0, \delta)$  given by  $l(t) = (t - \delta)f'(a)$ . Let  $A = l(0) = -\delta f'(a) < 0$ . From Lemma (2.9) by choosing  $\lambda$  large, we can find a solution  $u_1$  of (1.2) in  $\Omega = \mathbb{R} \times (0, T)$  satisfying

$$u_1(x, 0) = \begin{cases} a & \text{if } x < A, \\ \lambda & \text{if } A < x < 0, \\ u_0(x) & \text{if } x > 0. \end{cases} \quad (4.30)$$

$$u_1(x, t) = a \text{ if } x < l(t), \quad (4.31)$$

$$u_1(l(t)+, t) = a. \quad (4.32)$$

From (1.36) , (1.37) and (1) of Lemma 4.1, choose a solution  $u_2$  of (1.2) and  $b_1 \in L^\infty(\delta, T)$  such that

$$u_2(x, T) = g(x) \quad (4.33)$$

$$u_2(0, t) = b_1(t) \text{ if } \delta < t < T, \quad (4.34)$$

$$u_2(x, t) = a \quad \text{if } x > l(t), t > \delta, \quad (4.35)$$

$$u_2(l(t)-, t) = a \quad \text{if } t > \delta. \quad (4.36)$$

From (4.30), (4.32), (4.36) and RH conditions we glue the solutions  $u_1$  and  $u_2$  to obtain a solution  $u$  of (1.2) by

$$u(x, t) = \begin{cases} u_1(x, t) & \text{if } x > l(t), 0 < t < T, \\ u_2(x, t) & \text{if } 0 < x < l(t), \delta < t < T. \end{cases} \quad (4.37)$$

Define  $b \in L^\infty(0, T)$  by

$$b(t) = \begin{cases} u_1(0, t) & \text{if } 0 < t < \delta, \\ b_1(t) & \text{if } \delta < t < T. \end{cases} \quad (4.38)$$

Then from (4.30) , (4.33),  $(u, b)$  is the require solution. This proves the theorem.

**Proof of theorem (1.3):** Let  $f'(a_1) = \frac{C-A_1}{T}$ ,  $f'(a_2) = \frac{C-A_2}{T}$ ,  $l_1(t) = A_1 + tf'(a_1) = A_2 + tf'(a_2)$  be the respective lines joining  $(C, T)$ ,  $(A_1, 0)$  and  $(C, T)$ ,  $(A_2, 0)$ .

From (2.135), choose  $(\lambda, \mu)$  and a solution  $u_3$  of (1.2) in  $\mathbb{R} \times (0, T)$  satisfying

$$u_3(x, t) = \begin{cases} a_1 & \text{if } x < l_1(t), \\ a_2 & \text{if } x > l_2(t), \end{cases} \quad (4.39)$$

with initial condition

$$u_3(x, 0) = \begin{cases} a_1 & \text{if } x < A_1, \\ \lambda & \text{if } A_1 < x < B_1, \\ u_0(x) & \text{if } B_1 < x < B_2, \\ \mu & \text{if } B_2 < x < A_2, \\ a_2 & \text{if } x > A_2. \end{cases} \quad (4.40)$$

(a). Since  $g_i$  is a non decreasing function for  $i = 1, 2$  satisfying (1.38) , (1.39) and hence

$$D_1 = g_1(B_1) \leq A_1, A_2 \leq g_2(B_2) = D_2.$$



Let  $\eta_i$  be the line joining  $(B_i, T)$  and  $(D_i, 0)$  with  $f'(m_i) = \frac{B_i - D_i}{T}$  for  $i = 1, 2$ . Then from Lemma 4.2, there exist solutions  $u_i$  of (1.2) in  $\mathbb{R} \times (0, T)$  with initial condition  $u_0^i \in L^\infty(D_i, A_i)$  for  $i = 1, 2$  such that

$$u_1(x, T) = g_1(x, T) \quad \text{if } x \in (B_1, C), \quad (4.41)$$

$$u_2(x, T) = g_2(x, T) \quad \text{if } x \in (C, B_2), \quad (4.42)$$

$$u_1(x, t) = m_1 \quad \text{if } x < \eta_1(t), \quad (4.43)$$

$$u_1(l_1(t)-, t) = u_1(l_1(t)+, t) = a_1, \quad (4.44)$$

$$u_2(x, t) = m_2 \quad \text{if } x > \eta_2(t), \quad (4.45)$$

$$u_2(l_2(t)-, t) = u_2(l_2(t)+, t) = a_2, \quad (4.46)$$

and

$$u_1(x, 0) = \begin{cases} m_1 & \text{if } x < D_1, \\ u_0^1(x) & \text{if } D_1 < x < A_1, \\ a_1 & \text{if } x > A_1. \end{cases} \quad (4.47)$$

$$u_2(x, 0) = \begin{cases} m_2 & \text{if } x > D_2, \\ u_0^2(x) & \text{if } A_2 < x < D_2, \\ a_2 & \text{if } x < A_2. \end{cases} \quad (4.48)$$

From (4.39), (4.40), (4.44), (4.46) and from RH conditions, we can glue  $u_1, u_2, u_3$  to a solution  $u$  of (1.2) with initial data  $\bar{u}_0$  given by

$$u(x, t) = \begin{cases} u_1(x, t) & \text{if } x < l_1(t), \\ u_3(x, t) & \text{if } l_1(t) < x < l_2(t), \\ u_2(x, t) & \text{if } x > l_2(t), \end{cases} \quad (4.49)$$

and initial condition  $\bar{u}_0$  is given by

$$\bar{u}_0(x) = \begin{cases} m_1 & \text{if } x < D_1, \\ u_0^1(x) & \text{if } D_1 < x < A_1, \\ \lambda & \text{if } A_1 < x < B_1, \\ u_0(x) & \text{if } B_1 < x < B_2, \\ \mu & \text{if } B_2 < x < A_2, \\ u_0^2(x) & \text{if } A_2 < x < D_2, \\ m_2 & \text{if } x > D_2. \end{cases} \quad (4.50)$$

From (4.41), (4.42)  $u$  satisfies

$$u(x, T) = \begin{cases} g_1(x) & \text{if } B_1 < x < C, \\ g_2(x) & \text{if } C < x < B_2, \end{cases} \quad (4.51)$$

and  $(u, \bar{u}_0)$  is the required solution. This proves (a).

(b). Given  $\delta > 0$  choose  $A_1 < B_1 < B_2 < A_2$  such that  $\max(l_1(B_1), l_2(B_2)) = \delta$  and  $u_3$  be the solution of (1.2) as in (4.39). From (1.40),(1.41) and from Lemma 4.1, there exist solution  $u_1$  of (1.2) in  $(B_1, \infty) \times (\delta, T)$  and boundary data  $\tilde{b}_1, u_2$  of (1.2) in  $(-\infty, B_2) \times (\delta, T)$  and boundary data  $\tilde{b}_2$  such that

$$\begin{aligned} u_1(x, T) &= g_1(x) \quad \text{if } x \in (B_1, C), \\ u_2(x, T) &= g_2(x) \quad \text{if } x \in (C, B_2), \end{aligned}$$

and for  $\delta < t < T$ ,

$$\begin{aligned} u_1(B_1, t) &= \tilde{b}_1(t), \quad u_1(l_1(t)-, t) = a_1, \\ u_2(B_2, t) &= \tilde{b}_2(t), \quad u_2(l_2(t)+, t) = a_2. \end{aligned}$$

Then from RH condition glue  $u_1, u_2, u_3$  in  $\Omega = (B_1, B_2) \times (0, T)$  by

$$u(x, t) = \begin{cases} u_1(x, t) & \text{if } 0 < t < \delta, B_1 < l_1(x) < t, \\ u_2(x, t) & \text{if } 0 < t < \delta, t < l_1(x) < B_2, \\ u_3(x, t) & \text{otherwise.} \end{cases}$$

Then  $u$  is a solution of (1.2) satisfying the boundary conditions  $(b_1, b_2)$  given by

$$\begin{aligned} b_1(t) &= \begin{cases} \tilde{b}_1(t) & \text{if } \delta < t < T, \\ u_3(B_1, t) & \text{if } 0 < t < \delta, \end{cases} \\ b_2(t) &= \begin{cases} \tilde{b}_2(t) & \text{if } \delta < t < T, \\ u_3(B_2, t) & \text{if } 0 < t < \delta. \end{cases} \end{aligned}$$

Then  $(u, b_1, b_2)$  is the solution for problem (1.3). This proves the Lemma.

## Proof of Lemma (4.1) and (4.2) :

**Initial Value problem partitions:** (See Figure 14) Let  $0 \leq \delta < T$ ,  $I = (A_1, A_2)$ ,  $J = (C_1, C_2)$ . Let  $P = \{y_0, y_1 \dots y_n, x_0, x_1 \dots x_n\}$  is called a partition of  $(I, J)$  if

$$A_1 = y_0 < y_1 < \dots < y_n = A_2, \quad C_1 = x_0 \leq x_1 \leq \dots \leq x_n = C_2.$$

Let  $P(I, J) = \{P : P \text{ is a partition of } (I, J)\}$ . For a partition  $P$  denote  $a_i(P), s_i(P), b_i(P), a_i(t, P), s_i(t, P), b_i(t, P)$  by

$$\begin{aligned} f'(a_i(P)) &= \frac{x_i - y_i}{T - \delta}, \\ f'(b_i(P)) &= \frac{x_i - y_{i+1}}{T - \delta}, \\ s_i(P) &= \frac{f(a_i(P)) - f(b_i(P))}{a_i(P) - b_i(P)}, \\ a_i(t, P) &= x_i + f'(a_i(P))(t - T), \\ b_i(t, P) &= x_i + f'(b_i(P))(t - T), \\ s_i(t, P) &= x_i + s_i(P)(t - T). \end{aligned}$$

Clearly  $a_i(\delta, P) = y_i$ ,  $b_i(\delta, P) = y_{i+1}$ .

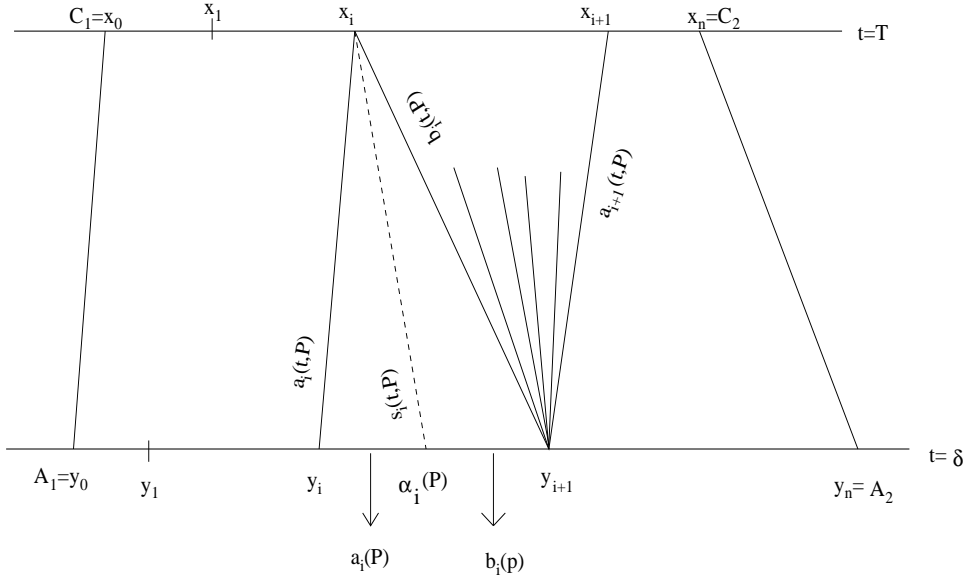


Figure 14:

**LEMMA 4.3** Let  $\alpha_i(P) = s_i(\delta, P)$ , then for  $\delta \leq t \leq T$ ,

$$b_i(P) < a_i(p), \quad b_i(P) \leq a_{i+1}(P), \quad (4.59)$$

$$y_i < \alpha_i(P) < y_{i+1}, \quad (4.60)$$

$$a_i(t, P) < s_i(t, P) < b_i(t, P) \quad \text{for } \delta < t < T. \quad (4.61)$$

**Proof.** Since  $y_i < y_{i+1}$ , hence

$$f'(a_i(P)) = \frac{x_i - y_i}{T - \delta} > \frac{x_i - y_{i+1}}{T - \delta} = f'(b_i(P)),$$

therefore  $a_i(P) > b_i(P)$ . By convexity of  $f$

$$f'(a_i(p)) > \frac{f(a_i(P)) - f(b_i(P))}{a_i(P) - b_i(P)} > f'(b_i(P)),$$

$$\frac{x_i - y_i}{T - \delta} > \frac{x_i - \alpha_i(P)}{T - \delta} > \frac{x_i - y_{i+1}}{t - \delta},$$

and hence  $y_i < \alpha_i(P) < y_{i+1}$ . Since  $x_i \leq x_{i+1}$  and hence  $f'(b_i(P)) = \frac{x_i - y_{i+1}}{T - \delta} \leq \frac{x_{i+1} - y_{i+1}}{T - \delta} = f'(a_{i+1}(P))$ . This implies  $b_i(P) \leq a_{i+1}(P)$ . This proves (4.59) to (4.61) and hence the Lemma.

Let  $\Omega_i(P) = \{(x, t) : \delta < t < T, a_i(t, P) < x < a_{i+1}(t, P)\}$ . In view of Lemma 4.5, let  $u_i(x, t, P)$  be a solution of (1.2) in  $\Omega_i(P)$  defined by

$$u_i(x, t, P) = \begin{cases} a_i(P) & \text{if } a_i(t, P) < x < s_i(t, P), \\ b_i(P) & \text{if } s_i(t, P) < x < b_i(t, P), \\ (f')^{-1}\left(\frac{x-y_{i+1}}{t-\delta}\right) & \text{if } b_i(t, P) \leq x < a_{i+1}(t, P). \end{cases} \quad (4.62)$$

Hence  $u_i(a_{i+1}(t, P)-, t, P) = a_{i+1}(P) = u_{i+1}(a_{i+1}(t, P)+, t, P)$ . Therefore define the solution  $u(x, t, P)$  of (1.2) in  $\mathbb{R} \times (\delta, T)$  by

$$u(x, t, P) = \begin{cases} u_i(x, t, P) & \text{if } (x, t) \in \Omega_i(P), \\ a_0(P) & \text{if } x < a_0(t, P), \\ a_n(P) & \text{if } x > a_n(t, P), \end{cases} \quad (4.63)$$

satisfying the initial condition

$$u(x, \delta, P) = \begin{cases} u_0(x, P) & \text{if } x \in (A_1, A_2), \\ a_0(P) & \text{if } x < A_1, \\ a_n(P) & \text{if } x > A_2, \end{cases} \quad (4.64)$$

where  $u_0$  is given by

$$u_0(x, P) = \begin{cases} a_i(P) & \text{if } y_i < x < \alpha_i(P), \\ b_i(P) & \text{if } \alpha_i(P) < x < y_{i+1}. \end{cases} \quad (4.65)$$

Furthermore at  $t = T, x \in (C_1, C_2)$ ,  $u$  satisfies

$$f'(u(x, T, P)) = \sum_{i=0}^{n-1} \chi_{[x_i, x_{i+1})}(x) \left( \frac{x - y_{i+1}}{T - \delta} \right). \quad (4.66)$$

Next we calculate the  $L^\infty$  and TV bounds of  $u_0$ . First observe that  $f'(a_0(P)) = \frac{C_1 - A_1}{T - \delta}$  and  $f'(a_n(P)) = \frac{C_2 - A_2}{T - \delta}$ , hence  $a_0(P), a_n(P)$ , are independent of  $P$  and denote

$$a_0 = a_0(P), a_n = a_n(P),$$

$$a_0(t) = a_0(t, P), a_n(t) = a_n(t, P).$$

Let  $M = \frac{\max(C_2, A_2) - \min(C_1, A_1)}{T - \delta}$ , then  $|f'(a_i(P))| \leq \left| \frac{x_i - y_i}{T - \delta} \right| \leq M$ ,  $|f'(b_i(P))| \leq M$  and hence

$$|f'(u_0(x, p))| \leq M \quad (4.67)$$

$$\begin{aligned} TV(f'(u_0(\cdot, P))) &= \sum_{i=0}^n |f'(a_i(P)) - f'(b_i(P))| \\ &= + \sum_{i=0}^{n-1} |f'(b_i(P)) - f'(a_{i+1}(P))| \\ &= \sum_{i=0}^n \left| \frac{x_i - y_i}{T - \delta} - \frac{x_i - y_{i+1}}{T - \delta} \right| + \sum_{i=0}^{n-1} \left| \frac{x_i - y_{i+1}}{T - \delta} - \frac{x_{i+1} - y_{i+1}}{T - \delta} \right| \\ &= \frac{1}{T - \delta} (A_2 - A_1) + \frac{1}{T - \delta} (C_2 - C_1). \end{aligned} \quad (4.68)$$

Since  $|f'(\theta)| \rightarrow \infty$  as  $|\theta| \rightarrow \infty$  and hence we have

**LEMMA 4.4** *There exist a constant  $M_1$  independent of  $P$  such that*

$$\|u_0(\cdot, P)\|_\infty + TV(f'(u_0(\cdot, P))) \leq M_1. \quad (4.69)$$

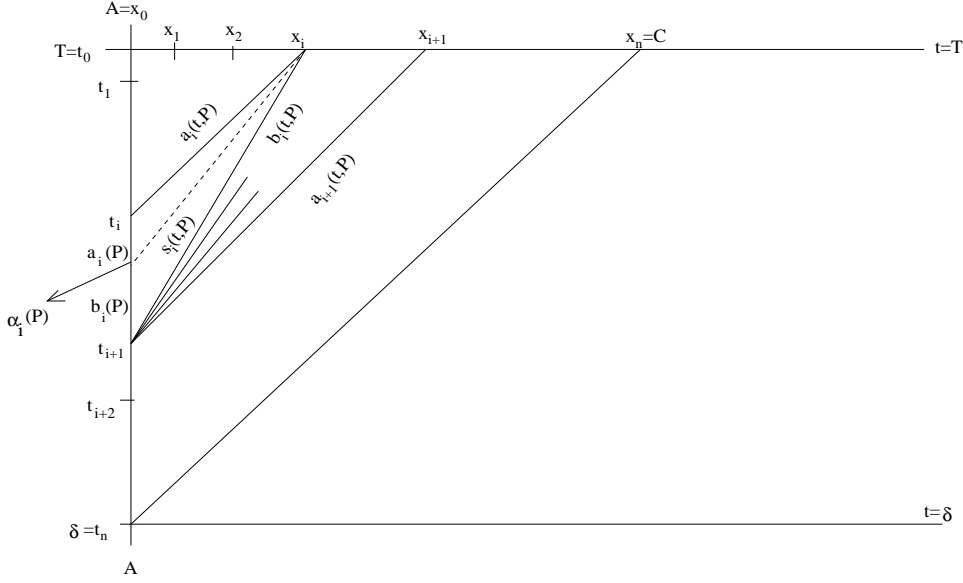


Figure 15:

**Boundary value partition:** (See Figure 15) Let  $0 \leq \delta < T$ ,  $A < C$ ,  $I = (A, C)$ ,  $J = (\delta, T)$ . Let  $P = \{t_0, t_1 \dots t_n, x_0, x_1 \dots x_n\}$  is called a boundary value partition if

$$T = t_0 > t_1 > t_2 \dots > t_n = \delta, \quad A = x_0 \leq x_1 \leq x_2 < \dots \leq x_n = C.$$

$$\text{Let } P(I, J) = \{P : P \text{ is a boundary value partition of } I, J\}. \quad (4.70)$$

For a  $P \in P(I, J)$  denote  $a_i(P), s_i(P), b_i(P), a_i(t, P), s_i(t, P), b_i(t, P)$  by

$$\begin{aligned} f'(a_i(P)) &= \frac{x_i - A}{T - t_i}, \\ f'(b_i(P)) &= \frac{x_i - A}{T - t_{i+1}}, \\ s_i(P) &= \frac{f(a_i(P)) - f(b_i(P))}{a_i(P) - b_i(P)}, \\ a_i(t, P) &= x_i + f'(a_i(P))(t - T), \\ b_i(t, P) &= x_i + f'(b_i(P))(t - T), \\ s_i(t, P) &= x_i + s_i(P)(t - T), \end{aligned}$$

Clearly  $a_i(t_i, P) = t_i$ ,  $b_i(t_{i+1}, P) = t_{i+1}$ .

**LEMMA 4.5** Define  $\alpha_i(P)$  such that  $s_i(\alpha_i(P), P) = A$ . Then for  $t \leq T$

$$a_i(P) > b_i(P), \quad a_{i+1}(P) \geq b_i(P), \quad (4.71)$$

$$t_i > \alpha_i(P) > t_{i+1}, \quad a_i(t, P) \leq s_i(t, P) \leq b_i(t, P), \quad (4.72)$$

**Proof.** Since  $t_i > t_{i+1}$ ,  $x_i \leq x_{i+1}$ , hence

$$\frac{x_i - A}{T - t_i} > \frac{x_i - A}{T - t_{i+1}}, \quad \frac{x_i - A}{T - t_{i+1}} \leq \frac{x_{i+1} - A}{T - t_{i+1}}.$$

This implies (4.71). From strict convexity of  $f$  and (4.71), we have

$$f'(a_i(P)) > \frac{f(a_i(P)) - f(b_i(P))}{a_i(P) - b_i(P)} > f'(b_i(P)),$$

hence  $t_i > \alpha_i(P) > t_{i+1}$  and for all  $t < T$ ,  $a_i(t, P) \leq s_i(t, P) \leq b_i(t, P)$ . This proves the Lemma.

Let  $\Omega_i(P) = \{(x, t) : a_i(t, P) < x < a_{i+1}(t, P), t_{i+1} < t < T\}$ . In view of Lemma 4.5, let  $u_i(x, t, P)$  be a solution of (1.2) in  $\Omega_i(P)$  defined by

$$u_i(x, t, P) = \begin{cases} a_i(P) & \text{if } a_i(t, P) < x < s_i(t, P), \\ b_i(P) & \text{if } s_i(t, P) < x < b_i(t, P), \\ (f')^{-1}\left(\frac{x-A}{T-t_{i+1}}\right) & \text{if } b_i(t, P) < x < a_{i+1}(t, P). \end{cases} \quad (4.73)$$

Then

$$u_{i+1}(a_{i+1}(t, P)+, t, P) = a_{i+1}(P) = u_i(a_{i+1}(t, P)-, t, P). \quad (4.74)$$

Also  $a_n(P)$  and  $a_n(t, P)$  are independent of  $P$  and denote by  $a_n, a_n(t)$ . Then from (4.74) it follows that  $u_{n-1}(a_n(t)-, t, P) = a_n$ . Therefore define the solution  $u(x, t, P)$  of (1.2) in  $\Omega = (A, \infty) \times (\delta, T)$  by

$$u(x, t, P) = \begin{cases} u_i(x, t, P) & \text{if } (x, t) \in \Omega_i(P), \quad 0 < i \leq n-1, \\ a_n & \text{if } x > a_n(t), \quad \delta < t < T, \end{cases} \quad (4.75)$$

and  $u(x, t, P)$  takes the boundary value  $b(t, P)$  and initial value  $a_n$  given by

$$u(A, t, P) = b(t, P) = \begin{cases} \theta_f & \text{if } t_1 < t < T, \\ a_i(P) & \text{if } \alpha_i(P) < t < t_i, \\ b_i(P) & \text{if } t_{i+1} < t < \alpha_i(P). \end{cases} \quad (4.76)$$

$$u(x, \delta, P) = u_0(x, P) = a_n = (f)^{-1}\left(\frac{C-A}{T-\delta}\right) \quad \text{if } x \in (A, \infty). \quad (4.77)$$

Further more at  $t = T$ , and  $x \in (A, C)$ ,  $u$  satisfies

$$f'(u(x, T, P)) = \sum_{i=1}^n \chi_{[x_i, x_{i+1})}(x) \left(\frac{x-A}{T-t_i}\right). \quad (4.78)$$

Next we calculate the  $L^\infty$  and TV bounds of the boundary value  $b(\cdot, P)$ .

$$\begin{aligned}
|f'(b(t, P))| &= \max_{1 \leq i \leq n} (|f'(a_i(P))|, |f'(b_i(P))|) \\
&= \max_{1 \leq i \leq n} \left( \left| \frac{x_i - A}{T - t_i} \right|, \left| \frac{x_i - A}{T - t_{i+1}} \right| \right) \\
&= \max_{1 \leq i \leq n} \left( \left| \frac{x_i - A}{T - t_i} \right| \right).
\end{aligned} \tag{4.79}$$

$$\begin{aligned}
TV(f'(b(\cdot, P))) &= \sum_{i=1}^{n-1} |f'(a_i(P)) - f'(b_i(P))| + \sum_{i=0}^{n-1} |f'(b_i(P)) - f'(a_{i+1}(P))| \\
&= \sum_{i=1}^{n-1} \left| \frac{x_i - A}{T - t_i} - \frac{x_i - A}{T - t_{i+1}} \right| + \sum_{i=1}^{n-1} \left| \frac{x_i - A}{T - t_{i+1}} - \frac{x_{i+1} - A}{T - t_{i+1}} \right| + \left| \frac{x_1 - A}{T - t_1} \right| \\
&= \sum_{i=1}^{n-1} \frac{(x_i - A)(t_i - t_{i+1})}{(T - t_i)(T - t_{i+1})} + \sum_{i=1}^{n-1} \frac{(x_{i+1} - x_i)}{(T - t_{i+1})} + \left| \frac{x_1 - A}{T - t_1} \right| \\
&\leq \left( \frac{T - \delta}{T - t_1} \right) \max_{1 \leq i \leq n} \left| \frac{x_i - A}{T - t_i} \right| + \left( \frac{C - A}{T - t_1} \right).
\end{aligned} \tag{4.80}$$

**Analysis of Discretization and Convergence:** Let  $\rho : [A, C] \rightarrow [\delta, T]$  be a non increasing right continuous function. Then it follows that  $\{x : \rho(x) \leq t\}$  is a closed interval for any  $t$ . Let  $0 < \epsilon < C - A$ , define

$$\rho_\epsilon(x) = \min\{\rho(x), \rho(A + \epsilon)\}.$$

Then  $\rho_\epsilon$  is a non-increasing right continuous function. Let  $m, n$  be non negative integers and let  $T = t_0 > t_1 = \rho(A + \epsilon) > t_2 > \dots > t_n = \delta$  be such that  $|t_i - t_{i+1}| \leq \frac{1}{m}$  for all  $i \geq 1$ . Let  $k \leq n - 1$  such that  $\{x : \rho_\epsilon(x) \leq t_{k+1}\} = \phi$ ,  $\{x : \rho(x) \leq t_k\} \neq \phi$  and define  $\{x_i\}$  by  $x_i = C$  if  $i \geq k + 1$  and for  $1 \leq i \leq k$ ,

$$\{x : \rho_\epsilon(x) > t_1\} = (x_i, C).$$

Denote  $P_{n,m,\epsilon}$  by  $P_{m,n,\epsilon} = \{t_0, t_1, \dots, t_n, x_0, x_1, \dots, x_n\}$  the partition depending on  $n, m$  and  $\epsilon$ . Associate to  $P_{m,n,\epsilon}$  define

$$\rho(x, P_{m,n,\epsilon}) = \sum_{i=1}^{n-1} t_i \chi_{[x_{i-1}, x_i)}(x) + t_n \chi_{[x_{n-1}, x_n)}(x). \tag{4.81}$$

Then it follows from definition,

$$\sup_n |\rho_\epsilon(x) - \rho(x)| \leq \sup_{A < x < \epsilon} |\rho(x) - \rho(A + \epsilon)| \tag{4.82}$$

$$\sup_n |\rho_\epsilon(x) - \rho(x, P_{m,n,\epsilon})| \leq \frac{1}{m}. \tag{4.83}$$

**Definition:** Let  $\epsilon_2 < \epsilon_1, n_2 \geq n_1$ . For  $i = 1, 2$ , let  $P_{m,n_i,\epsilon_i} = \{t_0, t_{1,i}, \dots, t_{n_i,i}, x_0, x_{1,i}, \dots, x_{n_i,i}\}$  be the partitions. Then we say  $P_{m,n_2,\epsilon_2}$  dominates  $P_{m,n_1,\epsilon_1}$  and is denoted by  $P_{m,n_2,\epsilon_2} \geq P_{m,n_1,\epsilon_1}$  if for  $1 \leq j \leq n_1$

$$\begin{aligned}
t_{j,1} &= t_{n_2 - n_1 + j, 2}, \\
x_{j,1} &= x_{n_2 - n_1 + j, 2}.
\end{aligned} \tag{4.84}$$

For a partition  $P_{m,n,\epsilon}$ , define  $\Omega(P_{m,n,\epsilon})$  by

$$\Omega(P_{m,n,\epsilon}) = \{(x, t) : a_1(t, P_{m,n,\epsilon}) < x, \delta < t < T\}. \quad (4.85)$$

**Properties of the domination:** Let  $\epsilon_2 < \epsilon_1, n_2 \geq n_1$  and let for  $i = 1, 2, u_i(x, t) = u(x, t, P_{m,n_i,\epsilon_i}), b_i(t) = b(t, P_{m,n_i,\epsilon_i})$  as in (4.75) and (4.76) respectively. Let  $P_{m,n_2,\epsilon_2} \geq P_{m,n_1,\epsilon_1}$  then from the construction it follows

$$\rho_{\epsilon_1}(x) = \rho_{\epsilon_2}(x) \quad \text{if } x \geq \epsilon_1 + A, \quad (4.86)$$

$$u_1(x, t) = u_2(x, t) \quad \text{if } (x, t) \in \Omega(P_{m,n,\epsilon_1}), \quad (4.87)$$

$$b_1(t) = b_2(t) \quad \text{if } \delta < t \leq \rho(A + \epsilon_1), \quad (4.88)$$

$$f'(u_i(x, T)) = \frac{x - A}{T - \rho(x, P_{m,n_i,\epsilon_i})}, \quad i = 1, 2. \quad (4.89)$$

$$\begin{aligned} \int_{\delta}^T |f'(b_1(t)) - f'(b_2(t))| dt &= \int_{\rho(\epsilon_1+A)}^{\rho(\epsilon_2+A)} |f'(b_2(t)) - f'(b_1(t))| dt \\ &\leq |\rho(A + \epsilon_1) - \rho(A + \epsilon_2)| \max_j \left\{ \left| \frac{x_{j,2} - A}{T - t_{j,2}} \right| \right\} \\ &= |\rho(A + \epsilon_1) - \rho(A + \epsilon_2)| \max_j \left\{ \left| \frac{x_{j,2} - A}{T - \rho_{\epsilon_2}(x_{j,2})} \right| \right\}. \end{aligned} \quad (4.90)$$

**Construction of dominations:** Let  $\epsilon_2 < \epsilon_1$  and  $P_{m,n_1,\epsilon_1} = \{t_0, t_{1,1}, \dots, t_{n_1,1}, x_0, x_{1,1}, \dots, x_{n_1,1}\}$ . Now choose  $\rho(\epsilon_2 + A) = t_{1,2} > t_{2,2} > \dots, t_{r_2,2} = t_{11} = \rho(\epsilon_1 + A)$  such that  $|t_{i,2} - t_{i+1,2}| \leq \frac{1}{m}$  for  $1 \leq i \leq r_2 - 1$ . Let  $n_2 = n_1 + n_2$  and define  $t_{i,2}$  for  $i \geq r_2$  by

$$t_{i,2} = t_{i-r_2+1,1},$$

and  $\{x_{i,2}\}$  be associated to  $\{t_{i,2}\}$ . Let  $n_2 = r_2 + n_1 - 1$  and  $P_{m,n_2,\epsilon_2} = \{t_0, t_{1,2}, \dots, t_{n_2,2}, x_0, x_{1,2}, \dots, x_{n_2,2}\}$ , then  $P_{m,n_2,\epsilon_2} \geq P_{m,n_1,\epsilon_1}$ .

Let  $0 < \epsilon_{i+1} < \epsilon_i < C - A, \lim_{i \rightarrow \infty} \epsilon_i = 0$ . Let  $m \geq 1$  and  $\{P_{m,n_1,\epsilon_1}\}_m$  be a partition corresponding to  $\rho_{\epsilon_1}$ . From the above construction, extend this partition to  $\{P_{m,n_2,\epsilon_2}\}_m$  to  $\rho_{\epsilon_2}$  such that  $P_{m,n_2,\epsilon_2} \geq P_{m,n_1,\epsilon_1}$ . By induction there exist partitions  $\{P_{m,n_j,\epsilon_j}\}_m$  of  $\rho_{\epsilon_j}$  such that

$$P_{m,n_j,\epsilon_j} \geq P_{m,n_{j-1},\epsilon_{j-1}}. \quad (4.91)$$

Denote  $P_{m,n_j,\epsilon_j} = \{t_0, t_{1,m,j}, \dots, t_{n_j,m,j}, x_0, x_{1,m,j}, \dots, x_{n_j,m,j}\}$ . Since  $\rho_{\epsilon_j} \leq \rho$  and hence

$$\left| \frac{x - A}{T - \rho_{\epsilon_j}(x)} \right| \leq \left| \frac{x - A}{T - \rho(x)} \right|,$$

and

$$\left| \frac{x_{k,m,j} - A}{T - t_{k,m,j}} \right| = \left| \frac{x_{k,m,j} - A}{T - \rho_{\epsilon_j}(x_{k,m,j})} \right| \leq \max_x \left| \frac{x - A}{T - \rho(x)} \right|. \quad (4.92)$$



Assume that  $\rho$  satisfies (4.6). Then from (4.92)

$$\max_{k \leq n_j} \left\{ \left| \frac{x_{k,m,j} - A}{T - t_{j,m,j}} \right| \right\} \leq \wedge. \quad (4.93)$$

For each  $m, j$ , let

$$\begin{aligned} u_{m,j}(x, t) &= u(x, t, P_{m,n_j,\epsilon_j}), \\ b_{m,j}(t) &= b(t, P_{m,n_j,\epsilon_j}), \end{aligned}$$

where  $u$  and  $b$  are given in (4.75) and (4.76) respectively. From (4.79), (4.80) and (4.93) we have for all  $m, j$

$$\left| f'(b_{m,j}(t)) \right| \leq \wedge. \quad (4.94)$$

$$TV(f'(b_{m,j})) \leq \left( \frac{T - \delta}{T - \rho(\epsilon_j)} \right) \wedge + \frac{C - A}{T - \rho(\epsilon_j + A)}. \quad (4.95)$$

Let  $j > k$ , then from (4.90)

$$\int_{\delta}^T \left| f'(b_{m,j}(t)) - f'(b_{m,k}(t)) \right| dt \leq \wedge |\rho(\epsilon_j + A) - \rho(\epsilon_k + A)|. \quad (4.96)$$

Under the above notations we have

**Proof of Lemma 4.1:** Let  $\rho$  satisfies (4.6), then for  $\rho(\epsilon_j + A) < T$  and from (4.94), (4.95), for each  $j$ ,  $\{f'(b_{m,j})\}_{m \in \mathbb{N}}$  is bounded in total variation norm. Therefore from super linearity of  $f$ ,  $\{b_{m,j}\}_{m \in \mathbb{N}}$  is uniformly bounded in  $L^\infty$  for all  $j, m$ . Hence from Helly's theorem and Cantors diagonalization, we can extract a subsequence still denoted by  $\{b_{m,j}\}$  such that for every  $j$ ,  $f'(b_{m,j}) \rightarrow f'(b_j)$  as  $m \rightarrow \infty$  in  $L^1$  and for *a.e.*  $t$ . Since  $(f')^{-1}$  exist and hence  $b_{m,j} \rightarrow b_j$  *a.e.*  $t$  and by dominated convergence theorem,  $b_{m,j} \rightarrow b_j$  in  $L^1$ . Let  $\rho_{m,j}(x) = \rho(x, P_{m,n_j,\epsilon_j})$ , then from (4.83)  $\rho_{m,j}(x) \rightarrow \rho_{\epsilon_j}(x)$  uniformly. Since  $f'(u_{m,j}(x, \delta)) = \frac{C-A}{T-\delta}$ , hence by  $L^1_{loc}$  contraction,  $u_{m,j}$  converges in  $L^1_{loc}$  and for *a.e.*  $(x, t)$  to a solution  $u_j$  of (1.2) with initial boundary condition

$$u_j(A, t) = b_j(t) \quad (4.97)$$

$$f'(u_j(x, \delta)) = \frac{C - A}{T - \delta}. \quad (4.98)$$

From (4.78) , (4.81) and (4.83), for *a.e.*  $x \in (A, C)$

$$f'(u_j(x, T)) = \frac{x - A}{T - \rho_{\epsilon_j}(x)}. \quad (4.99)$$

Letting  $m \rightarrow \infty$  in (4.96) to obtain

$$\int_{\delta}^T \left| f'(b_j(t)) - f'(b_k(t)) \right| dt \leq \wedge |\rho(A + \epsilon_j) - \rho(A + \epsilon_k)|. \quad (4.100)$$

Since  $\rho$  is right continuous and hence  $|\rho(A + \epsilon_j) - \rho(A + \epsilon_k)| \rightarrow 0$  as  $j, k \rightarrow \infty$ . Therefore from  $L_{loc}^1$  contractivity, there exist a subsequence still denoted by  $j$  such that  $u_j \rightarrow \tilde{u}_1$ , a solution of (1.2),  $b_j \rightarrow \tilde{b}_1$  in  $L_{loc}^1$  and *a.e.* Letting  $j \rightarrow \infty$  in (4.97) to (4.99), then  $(\tilde{u}_1, \tilde{b}_1)$  satisfies (4.6) to (4.9). From Rankine-Hugoniot condition across  $a_n(t, \delta)$ ,  $\tilde{u}_1$  satisfies (4.9). This proves (1). Similarly (2) follows and hence the Lemma.

Proof of Lemma 4.2 is much simpler than that of Lemma 4.1 because of (4.67) and (4.68), TV bounds exist for discretization of  $\rho$ . Let  $\rho : [C_1, C_2] \rightarrow [A_1, A_2]$  be in  $IA([C_1, C_2])$ . First assume that  $\rho$  is a strictly increasing continuous function. Let  $n \geq 1$  and  $A_1 = y_0 < y_1 < \dots < y_n = A_2$  such that  $|y_i - y_{i+1}| \leq \frac{1}{n}$ . Let  $k$  be such that  $\{x : \rho(x) < y_{k-1}\} = \phi$  and  $\{x : \rho(x) < y_k\} \neq \phi$ . Define  $x_i = A_1$  if  $i \leq k - 1$  and for  $i \geq k$ ,

$$\{x : \rho(x) < y_i\} = [A_1, x_i).$$

Let  $P_n = \{y_0, y_1 \dots y_n, x_0, x_1 \dots x_n\}$  be the corresponding partition and define

$$\rho(x, P_n) = \sum_{i=0}^{n-2} y_i \chi_{[x_i, x_{i+1})}(x) + y_{n-1} \chi_{[x_{n-1}, C_2]}(x).$$

Clearly

$$|\rho(x) - \rho(x, P_n)| \leq \frac{1}{n},$$

and hence  $\rho(x, P_n) \rightarrow \rho(x)$  uniformly as  $n \rightarrow \infty$ .

**Proof of Lemma 4.2:** First assume that  $\rho$  is a strictly increasing continuous function. For  $n \geq 1$ , let  $P_n$  and  $\rho_n(x) = \rho(x, P_n)$  be constructed as above. Let  $u_n(x, t) = u(x, t, P_n)$  as in (4.63) a solution of (1.2) with initial data  $u_{0,n}(x) = u_0(x, \delta, P_n)$  as in (4.64). From (4.67),  $\{f'(u_{0,n})\}$  is bounded in  $BV_{loc}(\mathbb{R})$  and hence by Helly's theorem, there exist a subsequence still denoted by  $\{f'(u_{0,n})\}$  converges to  $f'(u_0)$  in  $L_{loc}^1$  and *a.e.* Since  $u_{0,n}$  is uniformly bounded and  $f'$  is strictly increasing function, therefore  $u_{0,n} \rightarrow u_0$  in  $L_{loc}^1$ . Hence from  $L_{loc}^1$  contractivity,  $u_n$  converges to  $\tilde{u}$  a solution of (1.2) *a.e.*  $(x, t) \in \mathbb{R} \times (\delta, T)$  with initial data  $f'(u_0)$ . Since  $f'(a_0(P)) = \frac{C_1 - A_1}{T - \delta}$ ,  $f'(a_n(P)) = \frac{C_2 - A_2}{T - \delta}$ , hence if  $\tilde{u}_0 = \tilde{u}_0|_{[A_1, A_2]}$ , then from Rankine-Hugoniot condition across  $a_0(t), a_n(t)$ ,  $(\tilde{u}, \tilde{u}_0)$  satisfies (4.17) to (4.19). At  $t = T$ ,

$$f'(u_n(x, T)) = \frac{x - \rho_n(x)}{T - \delta}, \quad \text{if } x \in [C_1, C_2],$$

and hence letting  $n \rightarrow \infty$ , for *a.e.*  $x \in (C_1, C_2)$ ,

$$f'(u(x, T)) = \frac{x - \rho(x)}{T - \delta}.$$

Then  $(\tilde{u}, \tilde{u}_0)$  is the required solution satisfying (4.16). Let  $\rho \in IA((C_1, C_2))$  and  $\rho_n$  be a strictly increasing continuous function with values in  $(A_1, A_2)$  and converging to  $\rho$  in  $L^1$  and *a.e.* Let  $(\tilde{u}_n, \tilde{u}_{n,0})$  be the corresponding solutions satisfying (4.16) to

(4.19). Hence from Helly's theorem, there exist a subsequence still denoted by  $\tilde{u}_{n,0}$  converging to  $\tilde{u}_0$  in  $L^1_{loc}$  and *a.e.* Therefore from  $L^1_{loc}$  contractivity, for a subsequence still denoted by  $\tilde{u}_n$  converging to  $\tilde{u}$  a.e to a solution of (1.2) satisfying (4.17) to (4.19). For *a.e.*  $x \in (C_1, C_2)$  we have

$$f'(\tilde{u}(x, t)) = \lim_{n \rightarrow \infty} f'(\tilde{u}_n(x, T)) = \lim_{n \rightarrow \infty} \frac{x - \rho_n(x)}{T - \delta} = \frac{x - \rho(x)}{T - \delta}.$$

This proves the Lemma.

## 5 Extensions:

### PROPOSITION 5.1 (Controllability of constant states):

1. In theorem (1.1),  $g(x) = m$  a constant if and only if  $m$  satisfies

$$\frac{C_2 - A_2}{T} \leq f'(m) \leq \frac{C_1 - A_1}{T}. \quad (5.1)$$

2. In theorem (1.2),  $g(x_0) = m$  a constant if and only  $m$  satisfies

$$f'(m) \geq \frac{C}{T - \delta}. \quad (5.2)$$

3. In theorem (1.3),  $g_1(x) = m_1, g_2(x) = m_2$  are constants. then  $g_1, g_2$  is controllable if and only if  $m_1, m_2$  satisfies

$$f'(m_1) \geq \frac{C - A_1}{T - \delta}, f'(m_2) \leq \frac{A_2 - C}{T - \delta}. \quad (5.3)$$

**Proof.** (1).  $g(x) = m$  if and only if  $\rho(x) = x - Tf'(m)$  for all  $x \in (C_1, C_2)$ . Hence from (1.35) we have  $A_1 \leq \rho(x) \leq A_2$  implies that  $\frac{x-A_2}{T} \leq f'(m) \leq \frac{x-A_1}{T}$  and hence (5.1) holds.

(2). From (1.36),  $g(x) = m$  if and only if  $\delta \leq \rho(x) \leq T$  and hence  $\delta \leq x - Tf'(m) \leq T$ . This implies (5.2). Similarly (5.3) follows from (1.38) and (1.39). This proves the theorem.

(3). Follows similarly.

### 5.1 Controllability on the boundary

As mentioned in the introduction problems (I) and (III) deal with the controllability at time  $t = T$ . What about the controllability at  $x = A_2$ . More precisely

**Problem (IV):** Let  $T > 0$  and  $A_1 < A_2$ . Given  $u_0 \in L^\infty(\mathbb{R})$ ,  $g \in L^\infty(0, T)$  find  $\bar{u}_0 \in L^\infty((A_1, A_2))$  and  $u$  a solution of (1.2) in  $\Omega = (-\infty, A_2) \times (0, T)$  such that

$$f'(u(A_2, t)) = g(t) \text{ if } 0 < t \leq T, \quad (5.4)$$

and

$$u(x, 0) = \begin{cases} u_0(x) & \text{if } x < A_1 \\ \bar{u}_0(x) & \text{if } A_1 < x < A_2. \end{cases} \quad (5.5)$$

Then we have the following

**Theorem 5.2** Let  $A_1 < B < A_2, \wedge > 0$  and  $\rho : [0, T] \rightarrow [B, A_2]$  be a non increasing left continuous function such that for all  $t \in [0, T]$ ,

$$\left| \frac{A_2 - \rho(t)}{t} \right| \leq \wedge, \quad (5.6)$$

and  $f'(g(t)) = \frac{A_2 - \rho(t)}{t}$ . Then there exist  $(u, \bar{u}_0)$  satisfying (5.4) and (5.5).

**Proof.** Proof follows on the same lines as in theorem (1.2) and hence only sketch the main idea of the proof.

**Step 1.** This step is analogous to Lemma 4.1. First assume that  $\rho$  is discrete. That is there exist a partition  $0 = t_n \leq t_{n-1} \leq \dots \leq t_0 = T$  and  $B = x_0 < x_1 < \dots < x_n = A_2$ . Define  $a_i$  and  $b_i$  by

$$\begin{aligned} f'(a_i) &= \frac{A_2 - x_i}{t_i}, f'(b_i) = \frac{A_2 - x_{i-1}}{t_i} \\ s_i(t) &= A_2 + (t - t_i) \frac{f(a_i) - f(b_i)}{a_i - b_i} \\ f'(a_i) &= \frac{A_2 - x_i}{t_i} > \frac{A_2 - x_{i-1}}{t_i} = f'(b_i). \end{aligned}$$

Then

$$f'(b_i) = \frac{A_2 - x_{i-1}}{t_i} < \frac{A_2 - x_{i-1}}{t_{i-1}} = f'(a_{i-1}).$$

Hence  $a_i > b_i, a_{i+1} > b_i$  and from convexity.  $f'(a_i) > \frac{f(a_i) - f(b_i)}{a_i - b_i} > f'(b_i)$ . Therefore

$$\begin{aligned} x_i = A_2 - t f'(a_i) &< A_2 - t \frac{f(a_i) - f(b_i)}{a_i - b_i} \\ &= s_i(0) < A_2 - t f'(b_i) \\ &= x_{i+1}. \end{aligned}$$

Hence for  $0 \leq t \leq T$ ,

$$l_i(t) \leq s_i(t) \leq m_i(t),$$

where  $l_i(t) = x_i + f'(a_i)t, m_i(t) = x_{i-1} + f'(b_i)t$ . Define  $\rho_n$  and  $g_n$  by

$$\begin{aligned} \rho_n(t) &= x_0 \chi_{[T, t_1]} + \sum_{i=1}^n x_i \chi_{(t_i, t_{i+1}]}(t) \\ f'(g_n(t)) &= \frac{A_2 - \rho_n(t)}{t}. \end{aligned}$$

Define  $u_n$  in  $\Omega = (-\infty, A_2) \times (0, T)$  by

$$f'(u_n(x, t)) = \begin{cases} a_n & \text{if } x \leq l_n(t), \\ a_i & \text{if } l_i(t) \leq x < s_i(t), \\ b_i & \text{if } s_i(t) < x \leq m_i(t), \\ (f')^{-1}\left(\frac{A_2 - x_i}{t}\right) & \text{if } m_i(t) \leq x \leq l_{i-1}(t), \end{cases}$$

then  $u_n$  is a solution of (1.2) in  $\Omega$  satisfying

$$\begin{aligned} f'(u_n(x, t)) &= a_n \quad \text{if } x \leq l_n(t) = B + t\left(\frac{A_2 - B}{T}\right) \\ f'(u_n(A_2, t)) &= \frac{x - \rho_n(t)}{t}. \end{aligned}$$

Let  $\bar{u}_{n,0}(x) = u_n(x, 0)$  for  $B \leq x \leq A_2$ , then as in the proof of Lemma (4.1) and from (5.6), for a subsequence  $u_n \rightarrow \tilde{u}$  in  $L^1_{loc}(\Omega)$ ,  $u_n(\cdot, 0) \rightarrow \tilde{u}_0$  in  $L^1((B, A_2))$ ,  $\rho_n \rightarrow \rho$  a. e. such that  $u$  satisfies (1.2) and for a.e.  $t$ ,

$$f'(\tilde{u}(A_2, t)) = \frac{A_2 - \rho(t)}{t} \quad \text{if } t \in (0, T), \quad (5.7)$$

$$\tilde{u}(x, 0) = \tilde{u}_0(x) \quad \text{if } x \in (B, A_2), \quad (5.8)$$

$$f'(\tilde{u}(x, t)) = \frac{A_2 - B}{T} \quad \text{if } x \leq l_0(t). \quad (5.9)$$

**Step 2.** From Lemma (2.10) there exist a  $\mu$  and a solution  $u_1$  of (1.2) in  $\Omega$  satisfying

$$f'(u_1(x, t)) = a_0 \quad \text{if } x > l_0(t), \quad 0 \leq t < T \quad (5.10)$$

$$u_1(x, 0) = \begin{cases} a_0 & \text{if } x > B, \\ \mu & \text{if } A_1 < x < B, \\ u_0(x) & \text{if } x < A_1. \end{cases}$$

Now define  $(u, \bar{u}_0)$  in  $\Omega$  by

$$\begin{aligned} u(x, t) &= \begin{cases} \tilde{u}(x, t) & \text{if } x > l_1(t), \\ u_1(x, t) & \text{if } x < l_0(t), \end{cases} \\ \bar{u}_0(x) &= \begin{cases} u_0(x) & \text{if } x < A_1, \\ \mu & \text{if } A_1 < x < B, \\ \tilde{u}_0(x) & \text{if } x \in (B, A_2). \end{cases} \end{aligned}$$

Then  $(u, \bar{u}_0)$  is the required solution to problem (IV).

## 5.2 Controllability of initial and boundary values:

All three problems deals with finding either initial data or purely boundary data. In fact one can combine both and is as follows.

**Problem V:** Let  $u_0 \in L^\infty, T > 0, 0 < C_1 < C_2, 0 < A$ , Let  $\rho_1 : [0, C_1] \rightarrow [0, T], \rho_2 : [C_1, C_2] \rightarrow [0, A]$  be such that

- (i)  $\rho_1$  is a non increasing right continuous function.
- (ii)  $\rho_2$  is a non decreasing function.

Define  $g_1$  and  $g_2$  by

$$f'(g_1(x)) = \frac{x}{T - \rho_1(x)} \quad \text{if } x \in [0, C_1]$$

$$f'(g_2(x)) = \frac{x - \rho_2(x)}{T} \quad \text{if } x \in [C_1, C_2].$$

Then the problem is to find  $b \in L^\infty(0, T)$  and  $\bar{u}_0 \in L^\infty(0, A)$  such that a solution  $u$  of (1.2) in  $\mathbb{R} \times (0, T)$  satisfying the following initial boundary data

$$u(0, t) = b(t) \quad \text{if } 0 < t < T. \quad (5.11)$$

$$u(x, 0) = \begin{cases} \bar{u}_0(x) & \text{if } x \in (0, A), \\ u_0(x) & \text{if } x \in (A, 0), \end{cases} \quad (5.12)$$

and

$$f'(u(x, t)) = \begin{cases} g_1(x) & \text{if } x \in (0, C_1), \\ g_2(x) & \text{if } x \in (C_1, C_2). \end{cases} \quad (5.13)$$

**Theorem 5.3** *Let  $\lambda > 0, 0 < A_1 < A$  be given. Let  $\rho_1$  and  $\rho_2, g_1$  and  $g_2$  be as above and satisfying*

$$0 \leq \rho_2(x) \leq A_1, \quad \left| \frac{x}{T - \rho_1(x)} \right| \leq \wedge \quad (5.14)$$

*then problem (V) admits a solution.*

**Idea of the proof.** First get a free region by choosing  $\lambda$  large such that the solution  $u_\lambda$  of (1.2) in  $\mathbb{R} \times (0, \infty)$  satisfying for  $0 < t < T$ ,

$$u_\lambda(x, t) = a_1 = \frac{C_2 - A_1}{T}, \quad \text{if } x < A_1 + tf'(a_1) = l_1(t),$$

$$u_\lambda(x, 0) = \begin{cases} a_1 & \text{if } x < A_1, \\ \lambda & \text{if } A_1 < x < A, \\ u_0(x) & \text{if } x > A. \end{cases}$$

Existence of  $u_\lambda$  is guaranteed from Lemma 2.9. Let  $f'(a_0) = \frac{C_1}{T}$  and for  $0 < t < T$  define the free region  $F_1$  and  $F_2$  by

$$F_1 = \{(x, t) : 0 < x < l_0(t) = tf'(a_0)\}, F_2 = \{(x, t) : l_0(t) < x < l_1(t) = A_1 + tf'(a_1)\}.$$

Since  $0 \leq \rho_1(x) \leq T$  for  $x \in (0, C_1)$  and satisfying (5.14), therefore from Lemma (4.1), there exist a solution  $u_1$  of (1.2) in  $F_1$  and  $b \in L^\infty(0, T)$  such that

$$\begin{aligned} u_1(0, t) &= b(t) \\ u_1(x, T) &= g_1(x) \quad \text{if } x \in (0, C_1) \\ u_1(l_0(t)-, t) &= a_0. \end{aligned}$$

From (5.14) and Lemma (4.2), there exist a solution  $u_2$  of (1.2) in  $F_2$  and  $\tilde{u}_0 \in L^\infty(0, A_1)$  such that

$$\begin{aligned} u_2(x, T) &= g_2(x) \quad \text{if } x \in (C_1, C_2) \\ u_2(x, 0) &= \tilde{u}_0(x) \quad \text{if } x \in (0, A_1) \\ u_2(l_0(t)+, t) &= a_0, \quad u_2(l_1(t)-, t) = a_1. \end{aligned}$$

From RH conditions, glue  $u_1, u_2, u_\lambda$  to a single solution  $u$  of (1.2) in  $(0, \infty) \times (0, T)$  by

$$u(x, t) = \begin{cases} u_1(x, t) & \text{if } (x, t) \in F_1, \\ u_2(x, t) & \text{if } (x, t) \in F_2, \\ u_\lambda(x, t) & \text{if } x > l_1(t), \end{cases}$$

and

$$u(x, 0) = \begin{cases} \tilde{u}_0(x) & \text{if } x \in (0, A_1), \\ \lambda & \text{if } x \in (A_1, A), \\ u_0(x) & \text{if } x \in (A, \infty). \end{cases}$$

Then  $(u, u(x, 0), b)$  is the required solution to problem (V) The same method allows to generalize problem III also.

## 6 Optimal Control:

Let  $T > 0, k$  a measurable function such that  $f'(k) \in L^2(\mathbb{R})$  and  $u$  be a solution of (1.2) with initial data  $u_0$ . Consider the optimal control problem

$$m = \inf_{u_0} J(u_0) = \inf_{u_0} \int_{\mathbb{R}} |f'(u(x, T)) - f'(k(x))|^2 dx. \quad (6.1)$$

For the Burger's equation ( $f(u) = \frac{u^2}{2}, f'(u) = u$ ), this problem was studied by Castro-Palcious-Zuazua [6]. Under the assumption that  $k$  and  $u_0$  have compact support. They prove an existence of a minimizer and derived an algorithm to capture this minimizer. The main difficulty is that the functional is not differentiable .

In this paper we reduce the problem to a simple projection problem on a convex set and then use the standard numerical method to capture the unique minimizer. Then from Lemma (4.2) we can construct a minimizer to (6.1).

**Reduction to a simpler problem:** Let  $k \in L^2_{loc}(\mathbb{R})$  and  $I = (C_1, C_2)$  such that

$$k(x) = \theta_f \quad \text{if } x \notin I. \quad (6.2)$$

Define the admissible class  $A$  of functions by

$$A = \{u_0 \in L^\infty(\mathbb{R}) : u_0(x) = \theta_f \quad \text{outside a compact set } \}.$$

Since  $f'(k(x)) = f'(\theta_f) = 0$  for  $x \notin I$ , hence  $J$  is well defined on  $A$  and the optimal control problem is to find  $\tilde{u}_0$  such that

$$J(\tilde{u}_0) = \inf_{u_0 \in A} J(u_0). \quad (6.3)$$

For a given  $u_0 \in A$ , let  $u$  be the solution of (1.2) with initial data  $u_0$ . Then from Lax-Olienik explicit representation (2.12), there exist a non decreasing function  $\rho$  in  $x$  such that for *a.e.x*

$$f'(u(x, t)) = \frac{x - \rho(x)}{T}. \quad (6.4)$$

From the finite domain of dependence,  $u(x, T) = \theta_f$  outside a compact set and hence  $f'(u(x, t)) = 0$  for  $x$  outside a compact set. Therefore for outside a compact set  $\rho(x) = x$ . Let

$$B = \left\{ \rho \in L_{loc}^\infty(\mathbb{R}) : \begin{array}{l} (i) \rho \text{ is a non decreasing function} \\ (ii) \rho(x) = x \text{ outside a compact set} \end{array} \right\} \quad (6.5)$$

then the problem (6.3) reduces to find a  $\tilde{\rho} \in B$  such that

$$J(\tilde{\rho}) = m = \inf_{\rho \in B} \int_{\mathbb{R}} \left| \frac{x - \rho(x)}{T} - f'(k(x)) \right|^2 dx. \quad (6.6)$$

From the definition of  $k$  and  $B$ ,  $J$  is well defined. Let  $N > 0$  and define

$$B_N = \{ \rho \in B; \rho(x) = x \text{ for } |x| > N \}. \quad (6.7)$$

Then  $B = \cup_{N=1}^\infty B_N$ . For  $\rho \in B_N$ , define  $\tilde{\rho} \in B$  as follows:

$$\tilde{\rho}(x) = \begin{cases} x & \text{if } x \leq \min(C_1, \rho(C_1)) \text{ or } x > \max(C_2, \rho(C_2)), \\ \rho(C_1) & \text{if } \rho(C_1) < x \leq C_1, \\ \rho(x) & \text{if } C_1 < x \leq C_2, \\ \rho(C_2) & \text{if } C_2 < x \leq \rho(C_2), \end{cases} \quad (6.8)$$

and  $0 < x - \tilde{\rho}(C_1) \leq x - \rho(x)$  if  $\rho(C_1) < x \leq C_1$  and  $0 \leq \rho(C_2) - x \leq \rho(x) - x$  if  $C_2 < x < \rho(C_2)$ . Since  $f'(k(x)) = 0$  if  $x \notin (\min(C_1, J(C_1)), \max(C_2, J(C_2)))$  and hence

$$\begin{aligned} J(\tilde{\rho}) &= \int_{\min(C_1, J(C_1))}^{\max(C_2, J(C_2))} \left| \frac{x - \tilde{\rho}(x)}{T} - f'(k(x)) \right|^2 dx \leq \int_{\mathbb{R}} \left| \frac{x - \rho(x)}{T} - f'(k(x)) \right|^2 dx \\ &= J(\rho). \end{aligned} \quad (6.9)$$

Therefore from (6.9), if

$$\tilde{B} = \{ \rho \in B; \rho = \tilde{\rho} \}$$

then

$$m = \inf_{\rho \in \tilde{B}} J(\rho). \quad (6.10)$$



**LEMMA 6.1** *Let  $\rho_n \in \tilde{B}$  be a minimizing sequence of (6.10). Then  $\{\rho_n(C_1), \rho_n(C_2)\}$  are bounded.*

**Proof.** Let  $\rho_0(x) = x \in \tilde{B}$  and suppose  $\rho_k(C_1) \rightarrow -\infty$  as  $k \rightarrow \infty$ , then

$$\begin{aligned} \|f'(k)\|_2^2 &= \int_{C_1}^{C_2} |f'(k)|^2 dx = J(\rho_0) \geq \int_{\rho_k(C_1)}^{C_1} \left| \frac{x - \rho_k(x)}{T} - f'(k(x)) \right|^2 dx \\ &= \int_{\rho_k(C_1)}^{C_1} \left| \frac{x - \rho_k(C_1)}{T} \right|^2 dx = \frac{1}{2T^2} |C_1 - \rho_k(C_1)|^3 \\ &\rightarrow \infty \text{ as } k \rightarrow \infty, \end{aligned} \tag{6.11}$$

which gives a contradiction. Similarly  $\rho_n(C_2)$  is bounded from above. This proves the Lemma.

**Theorem 6.2** There exist a unique minimizer  $\rho$  to (6.10) satisfying

$$C_1 - (2T^2 \|f(k)\|_2^2)^{1/3} \leq \rho(C_1) \leq \rho(C_2) \leq C_2 + (2T^2 \|f(k)\|_2^2)^{1/3}. \tag{6.12}$$

**Proof.** In view of Lemma 6.1, there exist  $N > 0$  such that for  $\tilde{B}_N = \tilde{B} \cap B_N$

$$m = \inf_{\rho \in \tilde{B}_N} J(\rho).$$

Now  $\tilde{B}_N$  is a closed convex set in  $L^2((-N, N))$  and hence there exist a unique minimizer  $\bar{\rho} \in \tilde{B}_N$ . Now (6.12) follows from (6.11). This proves the theorem.

### Construction of Optimal control:

Let

$$A_1 = C_1 - (2T^2 \|f(k)\|_2^2)^{1/3}, \quad A_2 = C_2 + (2T^2 \|f(k)\|_2^2)^{1/3},$$

and  $J = (A_1, A_2)$ . then  $\bar{\rho} \in IA(J)$  (see 1.32) with values in  $J$ . Hence from Lemma (4.2), there exist  $\tilde{u}_0 \in L^\infty(J)$  and a solution  $u_1(x, t)$  of (1.2) in  $\Omega = J \times (0, T)$  satisfying

$$\begin{aligned} f'(u_1(x, T)) &= \frac{x - \bar{\rho}(x)}{T} \\ u_1(0, T) &= \tilde{u}_0 \\ f'(u_1(A_1, t)) &= f'(u_1(A_2, t)) = 0. \end{aligned}$$

Now define  $\bar{u}_0$  and  $\bar{u}$  by

$$\bar{u}_0(x) = \begin{cases} \tilde{u}_0(x) & \text{if } x \in J, \\ \theta_f & \text{if } x \notin J. \end{cases}$$

$$\bar{u}(x, t) = \begin{cases} u_1(x, t) & \text{if } (x, t) \in \Omega, \\ \theta_f & \text{if } (x, t) \notin \Omega, \end{cases}$$

then  $\bar{u}_0$  is a solution to optimal control problem (6.1)

Numerically it is fairly easy to obtain  $\bar{\rho}$  since the minimization is a simple convex minimization problem. Once  $\bar{\rho}$  is obtained, then using Lemma (4.2), approximate  $\bar{u}_0$  can be constructed.

**Remark 6.3** *In the optimal Control Problem: condition on  $k$  can be relaxed and is as follows. We can assume that for  $x \notin (C_1, C_2)$*

$$k(x) = \begin{cases} \alpha_1 & \text{if } x < C_1, \\ \alpha_2 & \text{if } x > C_2. \end{cases}$$

Then the class  $B$  is defined as follows. Let  $\rho \in L_{loc}^\infty(\mathbb{R})$  be such that

(i).  $\rho$  is non decreasing function

(ii). There exist  $A_1 < A_2$  such that

$$\rho(x) = \begin{cases} x - \alpha_1 T & \text{if } x < A_1, \\ x - \alpha_2 T & \text{if } x > A_2. \end{cases}$$

Let

$$B = \{\rho; \rho \text{ satisfying (i) and (ii)}\}.$$

Then by the similar arguments one can show that there exist a unique  $\tilde{\rho} \in B$  such that

$$J(\tilde{\rho}) = \inf_{\rho \in B} J(\rho). \quad (6.13)$$

In view of the controllability of initial and boundary value problems, we can extend the optimal controllability for the boundary value problem. To illustrate this, let us consider one sided initial boundary value problem. Let  $0 < T, 0 < C$ , and  $k \in L_{loc}^2(\mathbb{R})$  such that  $k(x) = \theta_f$  for  $x$  large. Let  $u_0 \in L^\infty, b \in L^\infty(0, T)$  and  $u$  be the solution of (1.2) in  $\Omega = (0, \infty) \times (0, T)$  with

$$u(t, 0) = b(t) \quad 0 < t < T,$$

$$u(x, 0) = u_0(x) \quad x > 0,$$

$$J(u_0, b) = \int_{\mathbb{R}} |f'(u(x, T)) - f'(k(x))|^2 dx.$$

In order to make integral finite assume  $u_0(x) = \theta_f$  for  $x$  large. Hence define

$$A = \{(u_0, b) \in L^\infty(\mathbb{R}) \times L^\infty(0, T); u_0(x) = \theta_f, \text{ for large } x\}.$$

Then optimal control problem is to find  $(\tilde{u}_0, \tilde{b})$  such that

$$J(\tilde{u}_0, \tilde{b}) = \inf_{(u_0, b) \in A} J(u_0, b). \quad (6.14)$$

From Joseph-Gowda [16] and Lax - Olienik [10] formulas for any  $(u_0, b) \in A$ . there exist  $0 \leq C_1 \leq C$  and  $\rho_1 : [0, C_1] \rightarrow [0, T]$  a non increasing function and  $\rho_2 : [C_1, C] \rightarrow \mathbb{R}$  a non decreasing function such that

(i).  $\rho_2(x) = x$  for  $x$  large and

$$f'(u(x, T)) = \frac{x - \rho_2(x)}{T} \quad \text{if } x \in (C_1, C).$$

(ii).  $f'(u(x, t)) = \frac{x}{T - \rho_1(x)}$ ,  $0 < x < C_1$  and

$$\left| \frac{x}{T - \rho(x)} \right| \leq \Lambda,$$

where  $\Lambda$  is a constant depending on the Lipschitz constant of  $f$  on  $[-\|b\|_\infty, \|b\|_\infty]$ .

Therefore

$$\begin{aligned} J(u_0, b) &= \int_0^{C_1} \left| \frac{x}{T - \rho_1(x)} - f'(k(x)) \right|^2 dx + \int_{C_1}^C \left| \frac{x - \rho_2(x)}{T} - f'(k(x)) \right|^2 dx \\ &= J_1(\rho_1, C_1) + J_2(\rho_2, C_1) \\ &= J(\rho_1, \rho_2, C_1) \end{aligned}$$

$$m = \inf_{u_0, b} J(u_0, b) = \inf_{\rho_1, \rho_2, C_1} \{J_1(\rho_1, C_1) + J_2(\rho_2, C_1)\}.$$

Let  $(\rho_{1,k}, \rho_{2,k}, C_{1,k})$  be a minimizing sequence. As in the previous case, it follows that there exists  $A > 0$ , such that  $\rho_{2,k}(x) = x$  for all  $k$  and  $x \geq A$ . Hence  $\{\rho_{i_k}\}$  are uniformly bounded monotone functions, therefore from Helly's theorem there exist a subsequence still denoted by  $\{\rho_{1,k}, \rho_{2,k}, C_{1,k}\}$  converges  $(\tilde{\rho}_1, \tilde{\rho}_2, \tilde{C})$  for all  $x \in [0, C]$ . Hence by Fataou's Lemma  $(\tilde{\rho}_1, \tilde{\rho}_2, \tilde{C})$  is an optimal solution and from Lemma 4.1 , 4.2 we can construct the solution  $(\tilde{u}_0, \tilde{b})$ .

If  $\tilde{C}$  is known, then  $\tilde{\rho}_1$  and  $\tilde{\rho}_2$  can be obtained from the  $L^2$  - projection as follows: Let  $\eta_1(x) = \frac{x}{T - \rho_1(x)}$  then  $\frac{x}{\eta_1} \leq T$ ,  $\frac{\eta_1(x)}{x}$  is a non increasing right continuous function. Let  $\eta : [0, C] \rightarrow \mathbb{R}$  be function such that

1.  $\frac{\eta(x)}{x}$  is non increasing right, continuous function in  $[0, \tilde{C}]$  and  $\frac{x}{\eta(x)} \leq T$  in  $[0, \tilde{C}]$ .
2.  $\eta|_{(\tilde{C}, C)}$  is non decreasing function.

Let

$$K_N = \{\eta; \eta \text{ satisfying (1) , (2) and } 0 \leq \eta \leq N\}.$$

Then  $K_N$  is a closed convex set in  $L^2((0, C))$  and let  $\tilde{\eta}_k \in K_N$  such that

$$J(\tilde{\eta}) = \inf_{\eta \in K_N} J(\eta) = \inf \left\{ \int_0^{\tilde{C}} |\eta(x) - f'(k(x))|^2 dx + \int_{\tilde{C}}^C \left| \frac{x - \eta(x)}{T} - f'(k(x)) \right|^2 dx \right\}.$$

Then for large  $\eta$ , if we define

$$\begin{aligned} \tilde{\rho}_1(x) &= T - \frac{x}{\tilde{\eta}(x)} \quad \text{for } x \in (0, \tilde{C}) \\ \tilde{\rho}_2(x) &= \tilde{\eta}(x) \quad \text{for } x \in (\tilde{C}, C) \end{aligned}$$

then  $(\tilde{\rho}_1, \tilde{\rho}_2, \tilde{C})$  is the optimal solution.

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