

Summer Project. Part II.

**Limitations of a fully automatic *hp*-adaptive
procedure for the Finite Element (FE) method.**

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Jun 12, 2003

Baker-Atlas

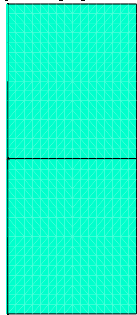
OVERVIEW

1. Overview.
2. Answer to questions.
3. Model problem.
4. Limitations of the fully automatic *hp*-adaptive procedure.
5. Conclusions and Future Work.

2. MODELING OF GEOMETRICAL DETAILS THROUGH HIGHER ORDER METHODS

Geometrical modeling of a circle

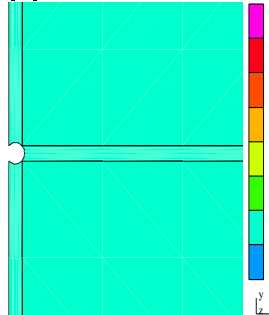
2014g00: A Fully automatic hp-adaptive Finite Element code



Zoom=1

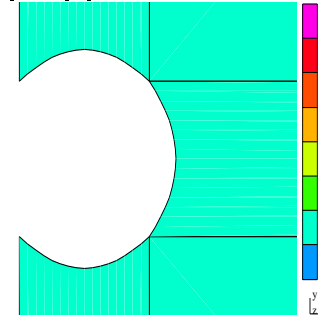


2014g00: A Fully automatic hp-adaptive Finite Element code



Zoom=10

2014g00: A Fully automatic hp-adaptive Finite Element code

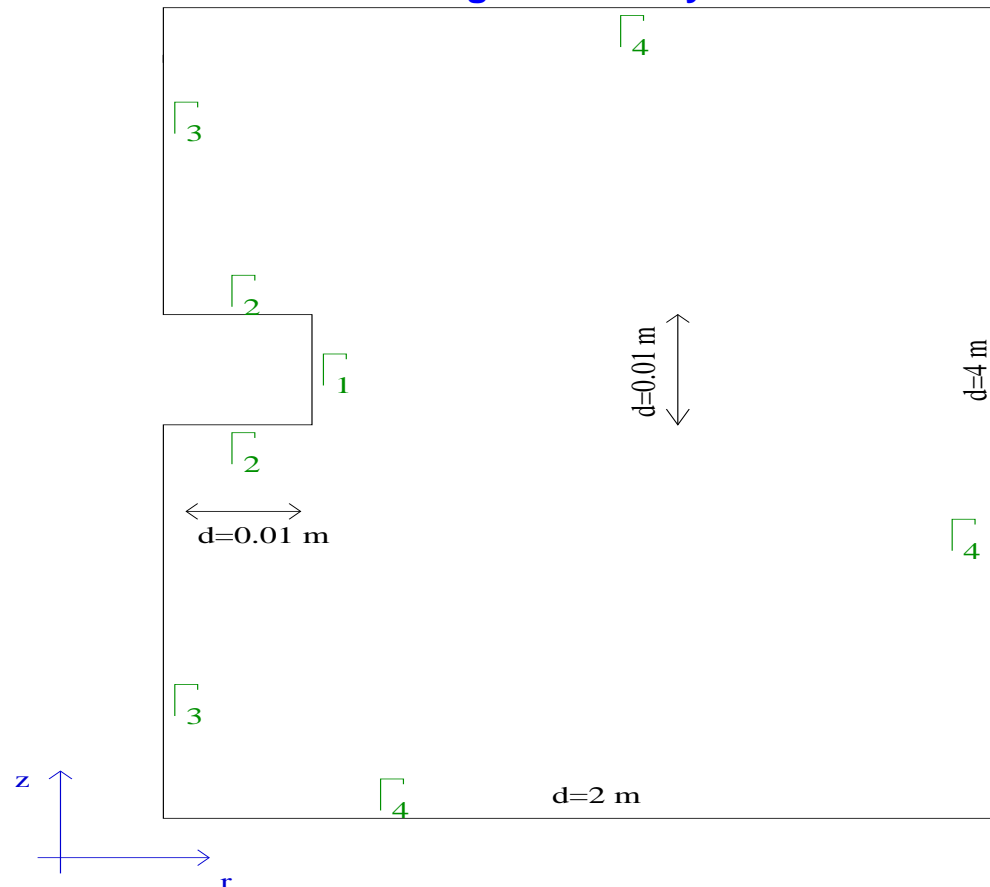


Zoom=100

Only five elements needed to model a small circle embedded into a large domain!!!

2. MODEL PROBLEM

Modeling of a battery



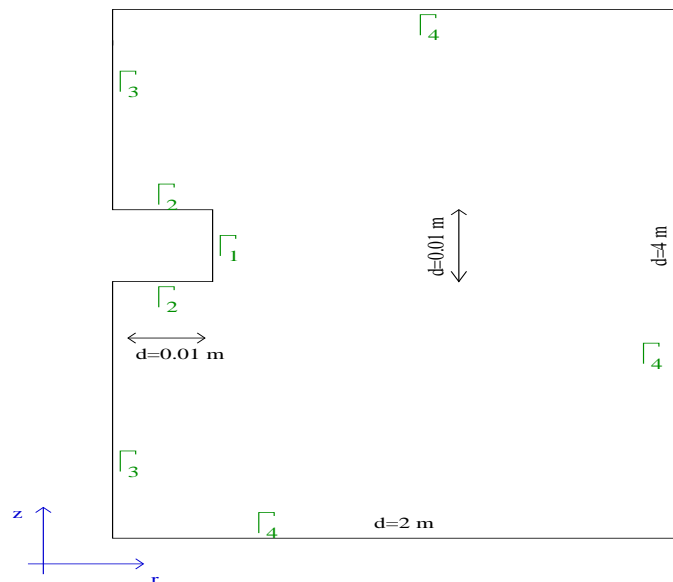
Goal: Determine EM field far from the battery (receiver antennas).

2. MODEL PROBLEM

Time Harmonic Maxwell's Equations

$$\nabla \times \mathbf{E} = -j\mu\omega\mathbf{H}$$

$$\nabla \times \mathbf{H} = j\omega\epsilon\mathbf{E} + \sigma\mathbf{E}$$



Reduced Wave Equation:

$$\nabla \times \left(\frac{1}{\mu} \nabla \times \mathbf{E} \right) - (\omega^2\epsilon - j\omega\sigma)\mathbf{E} = -j\omega\mathbf{J}^{imp}$$

Boundary Conditions (BC):

Dirichlet BC at a PEC surface:

$$\mathbf{n} \times \mathbf{E} = 0 \text{ on } \Gamma_2 \cup \Gamma_4$$

Neumann BC's:

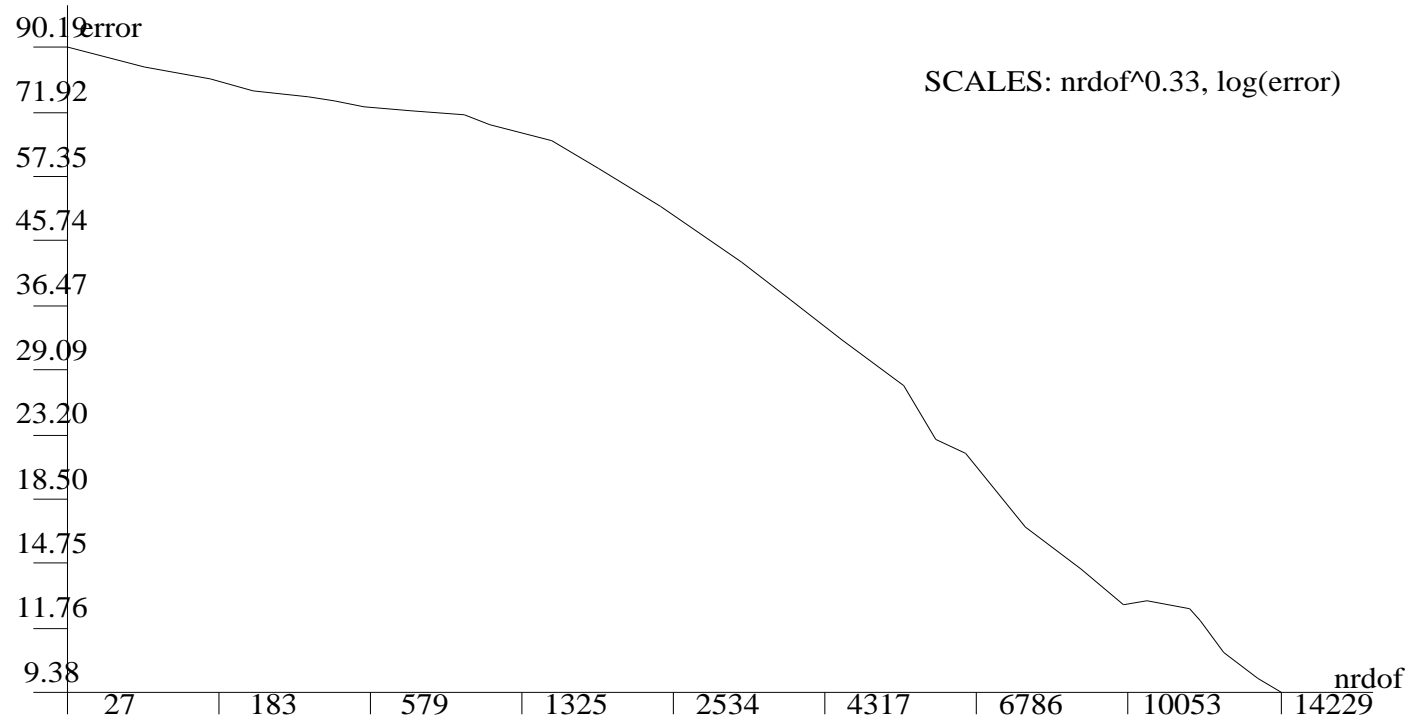
$$\mathbf{n} \times \frac{1}{\mu} \nabla \times \mathbf{E} = -j\omega \text{ on } \Gamma_1$$

$$\mathbf{n} \times \frac{1}{\mu} \nabla \times \mathbf{E} = 0 \text{ on } \Gamma_3$$

5. NUMERICAL RESULTS

Battery example: Convergence history

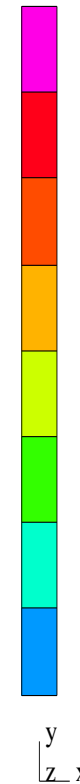
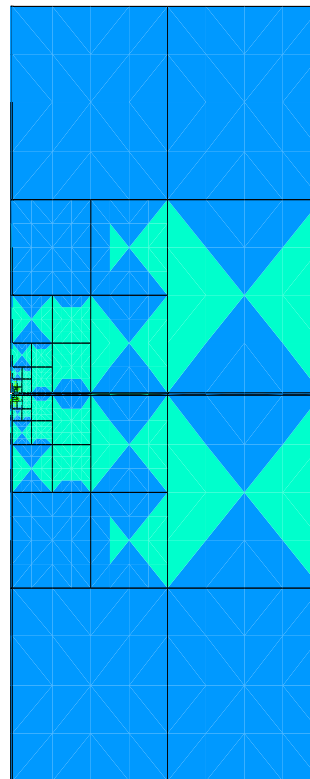
2Dhp90: A Fully automatic hp-adaptive Finite Element code



5. NUMERICAL RESULTS

Battery example: final *hp*-grid, Zoom = 1

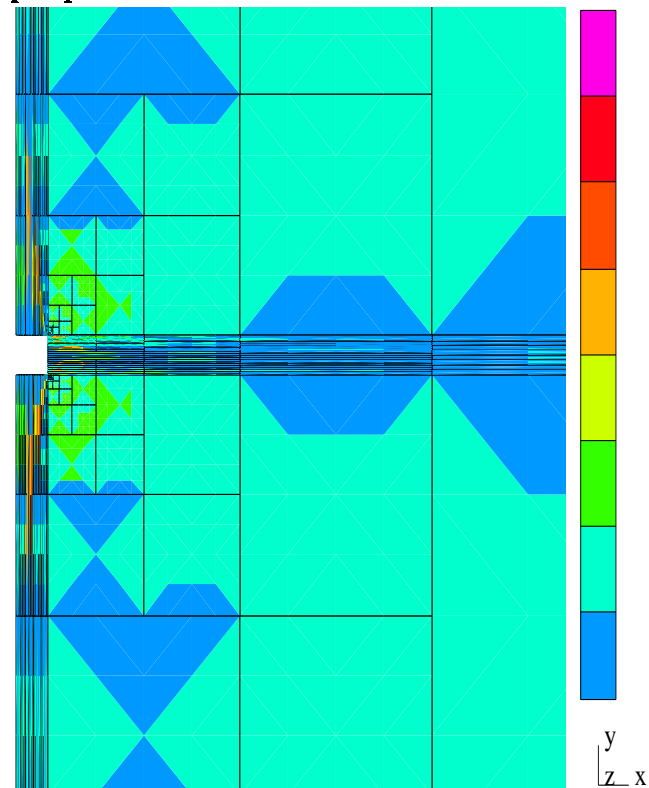
2Dhp90: A Fully automatic *hp*-adaptive Finite Element code



5. NUMERICAL RESULTS

Battery example: final *hp*-grid, Zoom = 10

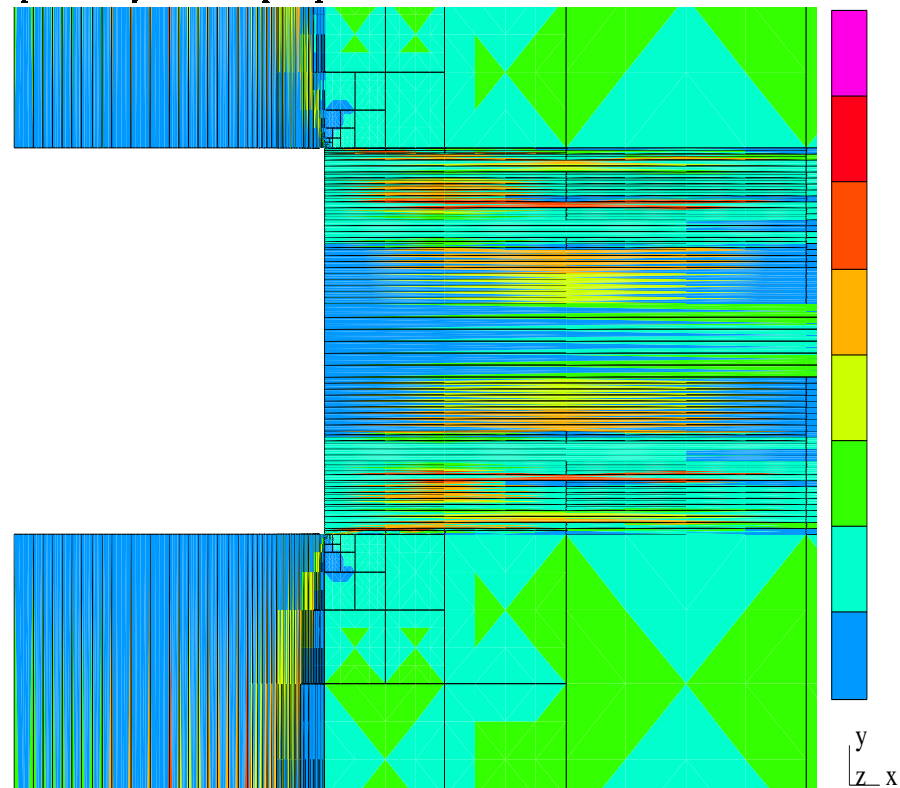
2Dhp90: A Fully automatic *hp*-adaptive Finite Element code



5. NUMERICAL RESULTS

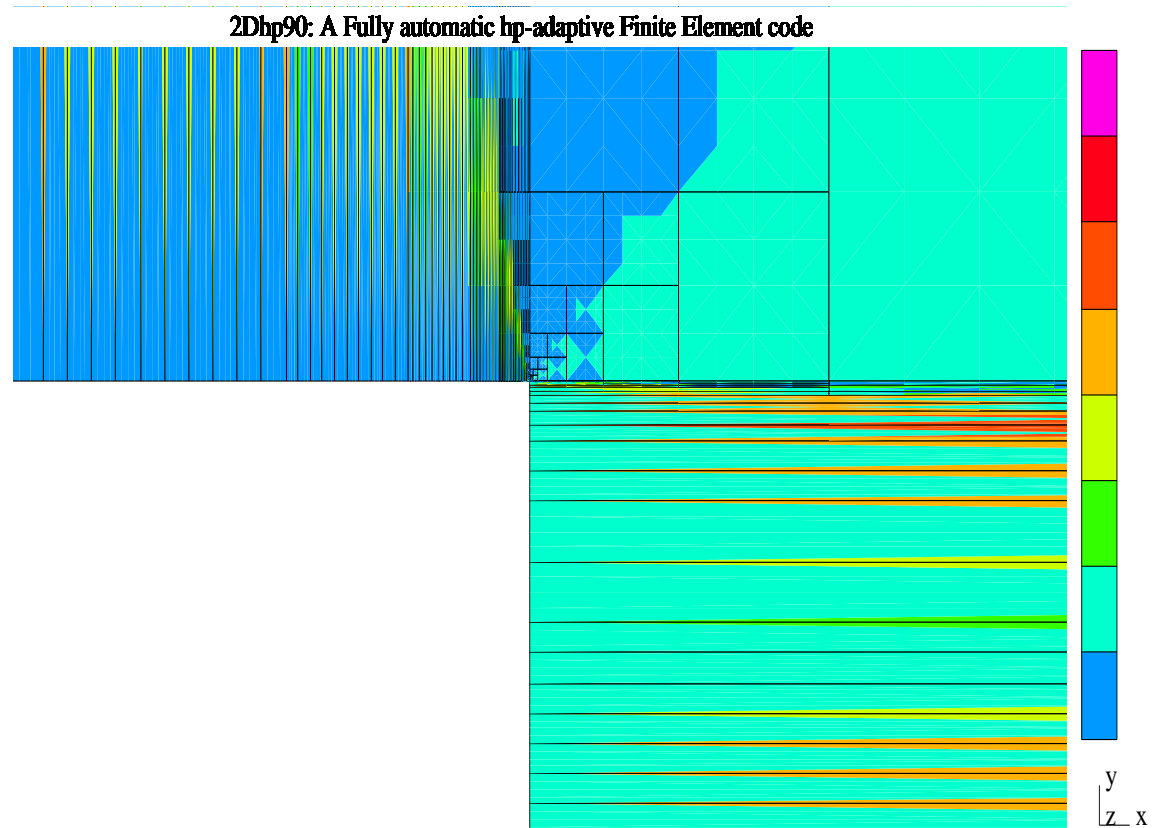
Battery example: final *hp*-grid, Zoom = 100

2Dhp90: A Fully automatic *hp*-adaptive Finite Element code



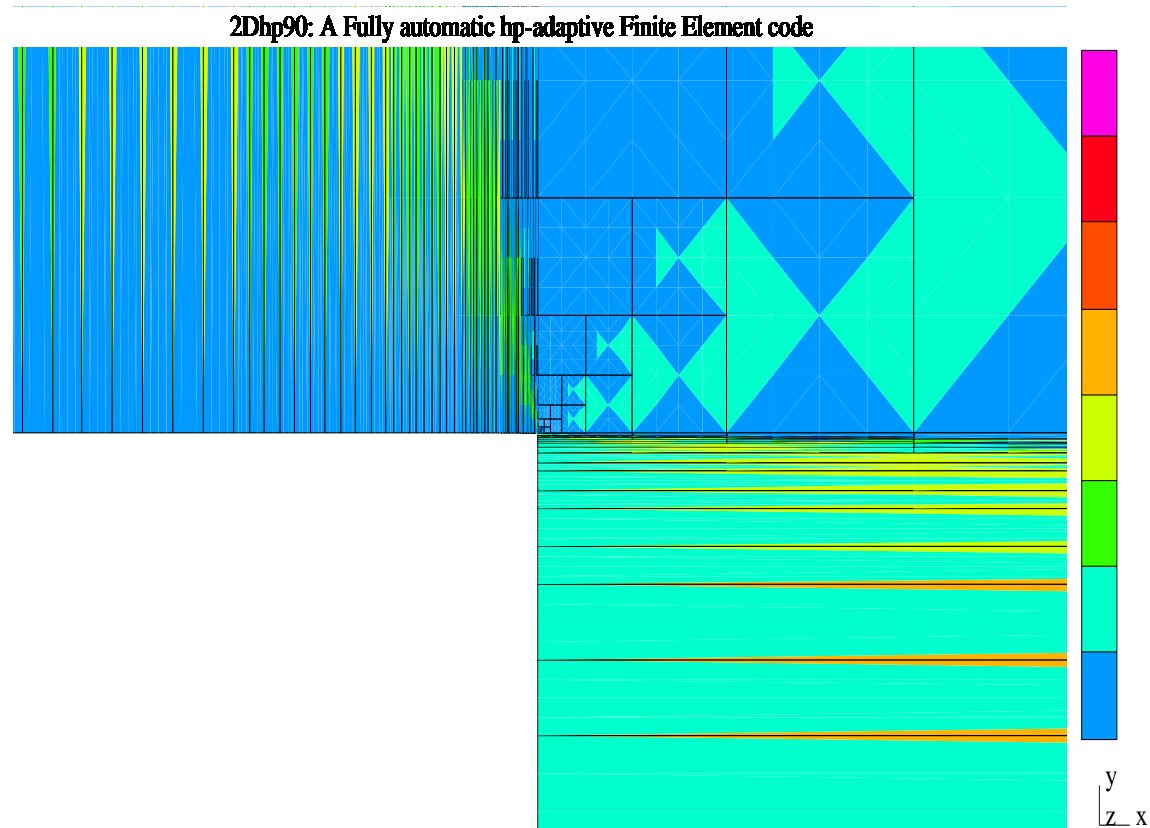
5. NUMERICAL RESULTS

Battery example: final *hp*-grid, Zoom = 1000



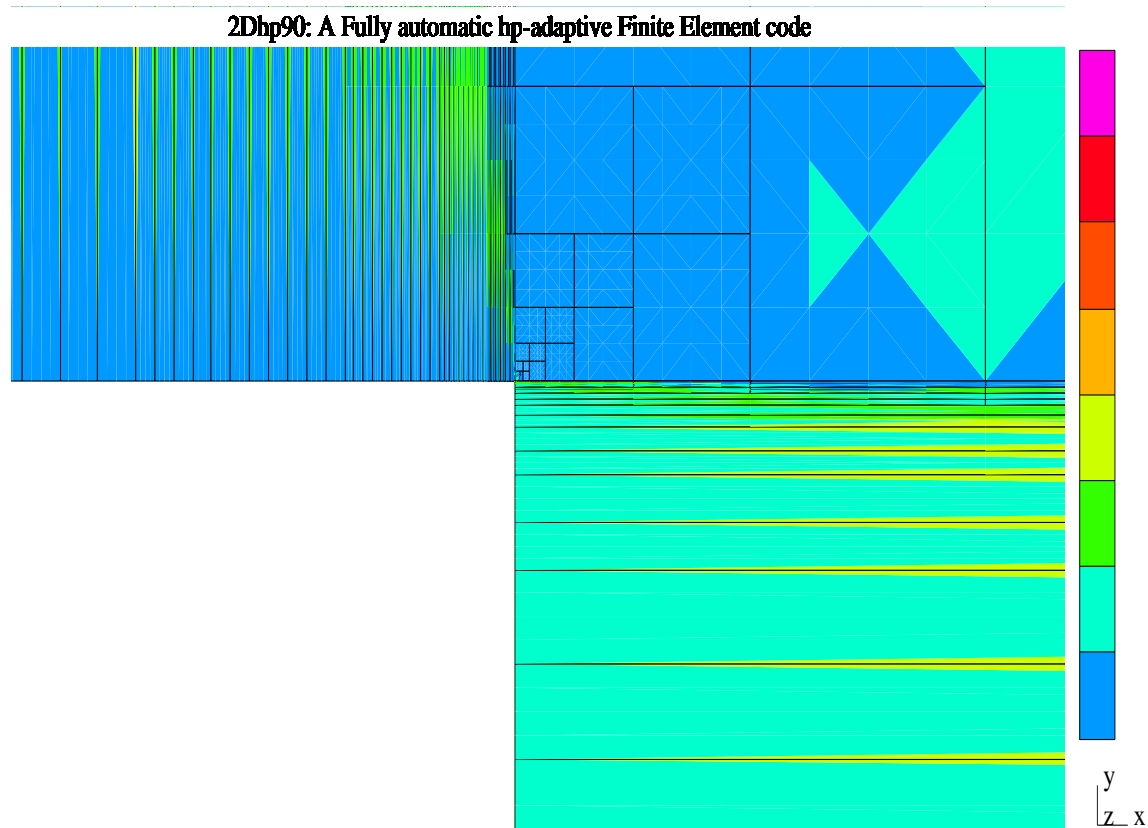
5. NUMERICAL RESULTS

Battery example: final *hp*-grid, Zoom = 10000



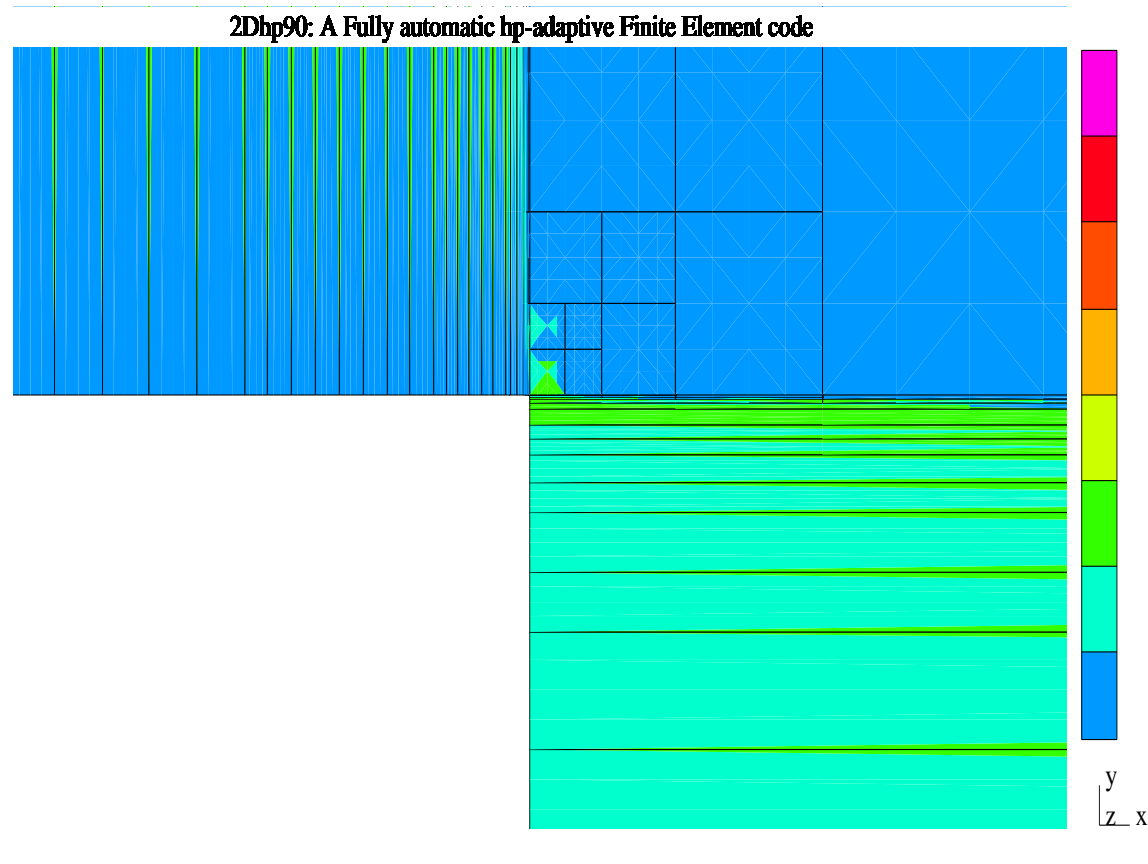
5. NUMERICAL RESULTS

Battery example: final *hp*-grid, Zoom = 100000



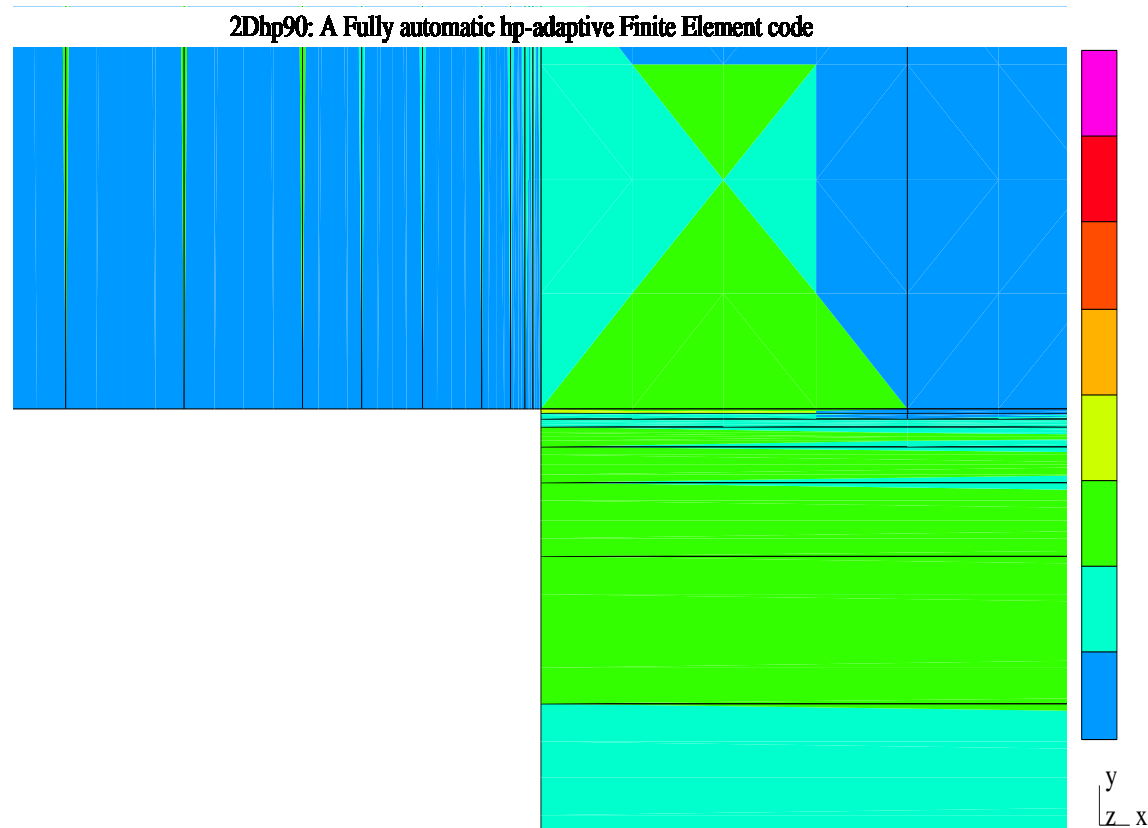
5. NUMERICAL RESULTS

Battery example: final *hp*-grid, Zoom = 100000



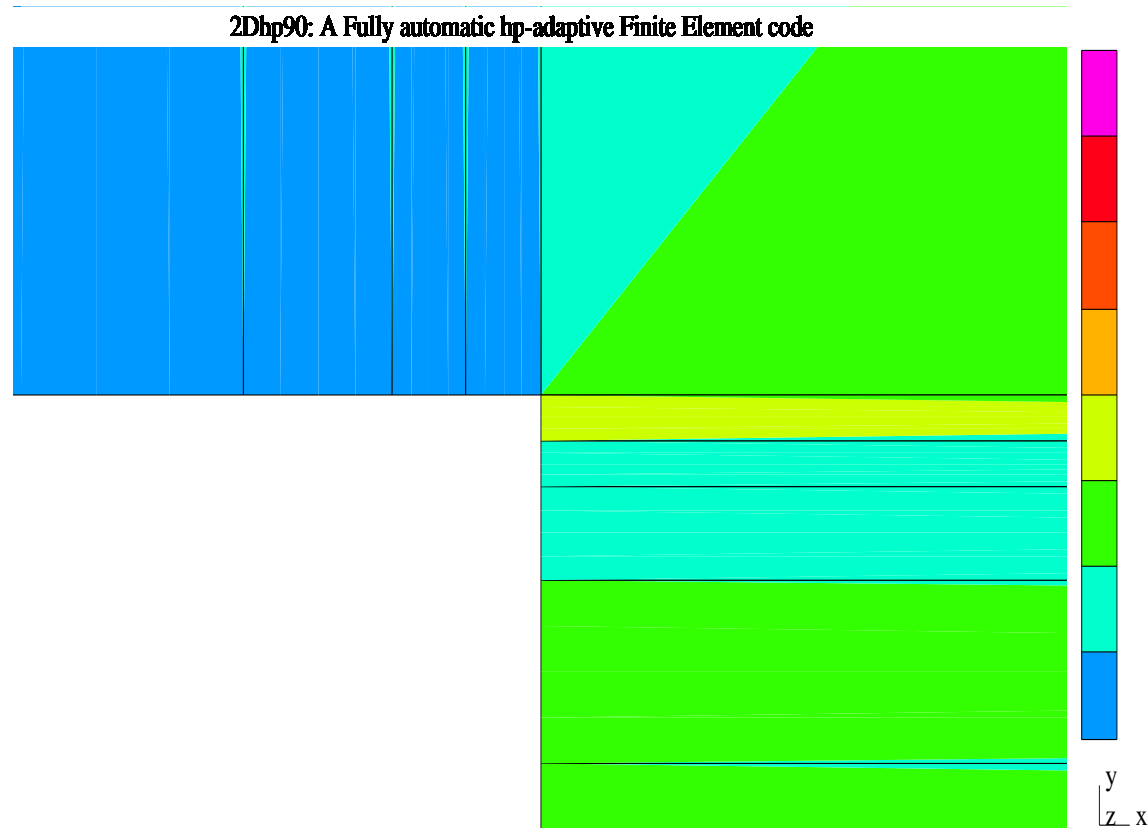
5. NUMERICAL RESULTS

Battery example: final *hp*-grid, Zoom = 1000000



5. NUMERICAL RESULTS

Battery example: final *hp*-grid, Zoom = 10000000



5. NUMERICAL RESULTS

Why the optimal grid is so bad?

Optimization is based on minimization of the ENERGY NORM of the error, given by:

$$\| error \| = \int | error | + \int | \nabla \times error |$$

Interpretation of results:

- The grid is optimal for the selected refinement criteria,
- but our **refinement criteria is inadequate** for our purposes.

6. SUMMARY AND FUTURE WORK

SUMMARY:

- The *hp*-finite element method allows for introducing geometrical details.
- The *hp*-adaptive algorithm is robust.
- Minimization of the error in **energy norm is NOT an adequate criteria** for solving many EM problems.

FUTURE WORK:

- Study the potential of a fully automatic goal-oriented *hp*-adaptive strategy for Petroleum Engineering EM applications.
- Improve performance of the adaptive strategy by creating a two grid solver.