

VI EIEC, Chiclana, Spain

An *hp* Fourier Finite Element (FFE) Framework with Electromagnetics and Multiphysics Applications

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Basque Center for Applied Mathematics (BCAM)
Promoting Technological Advances Through Mathematics

OVERVIEW

1. Motivation: Waveguide Design and Oil-Industry Applications.

2. Method:

- Fourier finite element (FFE) method.
- Parallel implementation.
- Multi-physics framework.

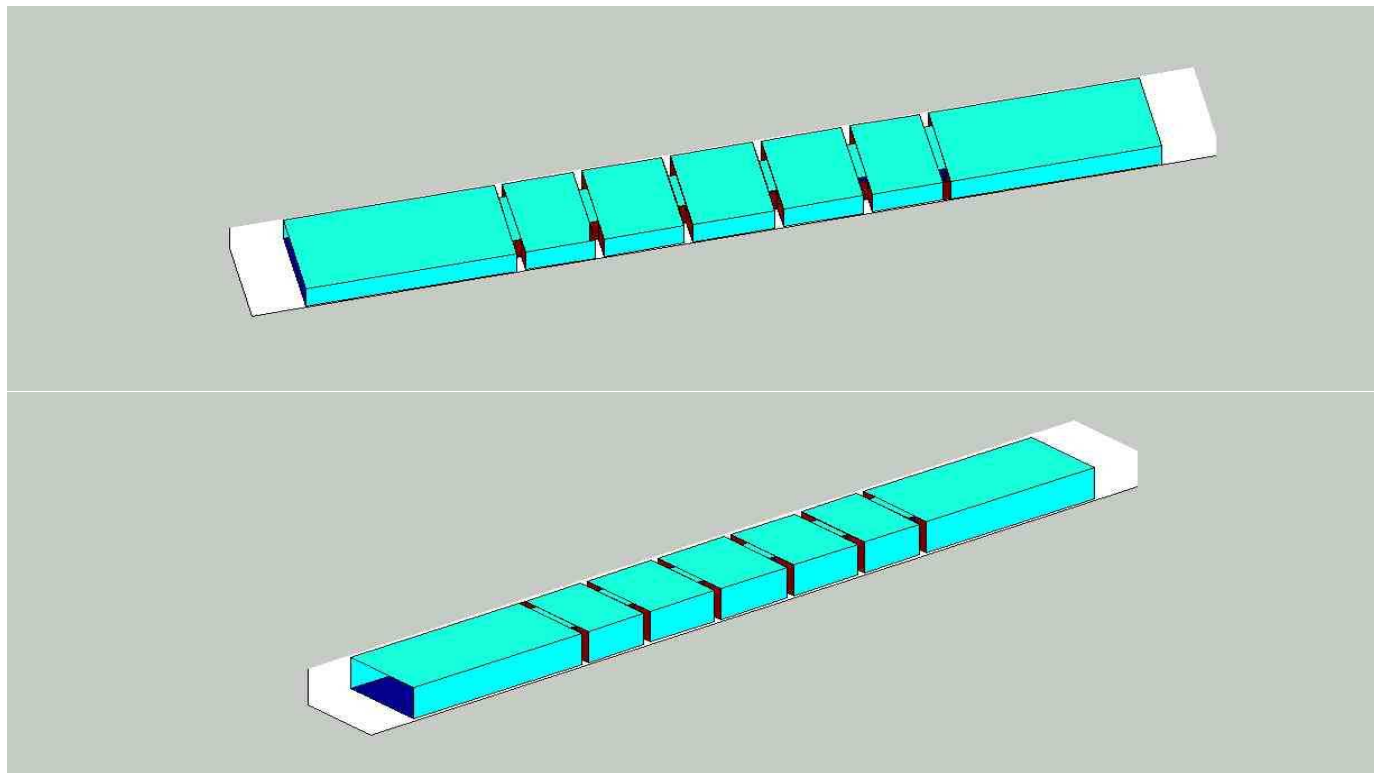
3. Numerical Simulations:

- 2D resistivity logging measurements.
- Marine controlled source electromagnetic (CSEM) measurements.
- 3D resistivity logging measurements.

4. Conclusions and Future Work.

MOTIVATION (WAVEGUIDES)

Waveguide Design



Goal: Determine electric field intensity at the ports.

MOTIVATION (OIL-INDUSTRY)

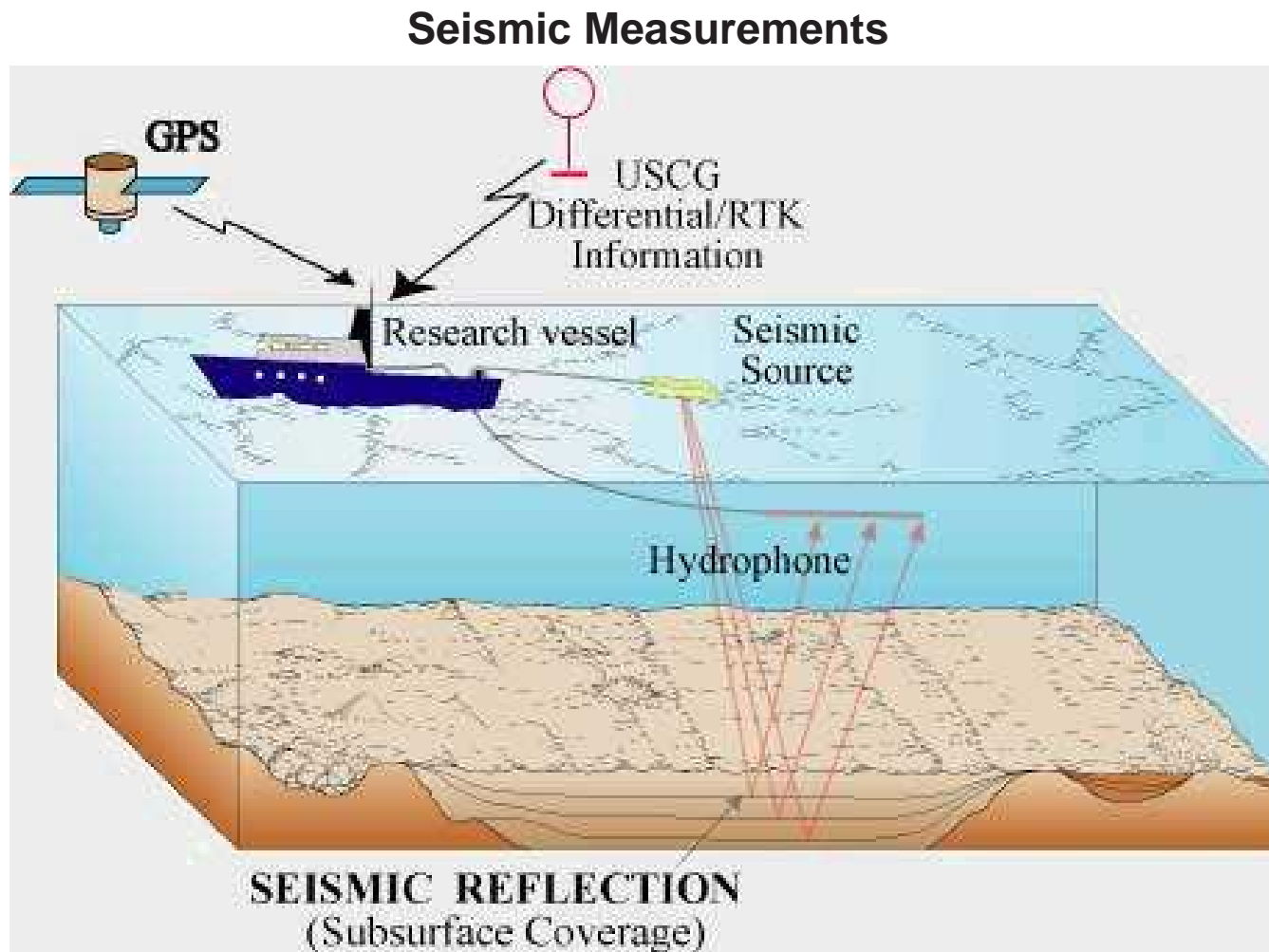


Figure from the USGS Science Center for Coastal and Marine Geology

MOTIVATION (OIL-INDUSTRY)

Marine Controlled-Source Electromagnetics (CSEM)

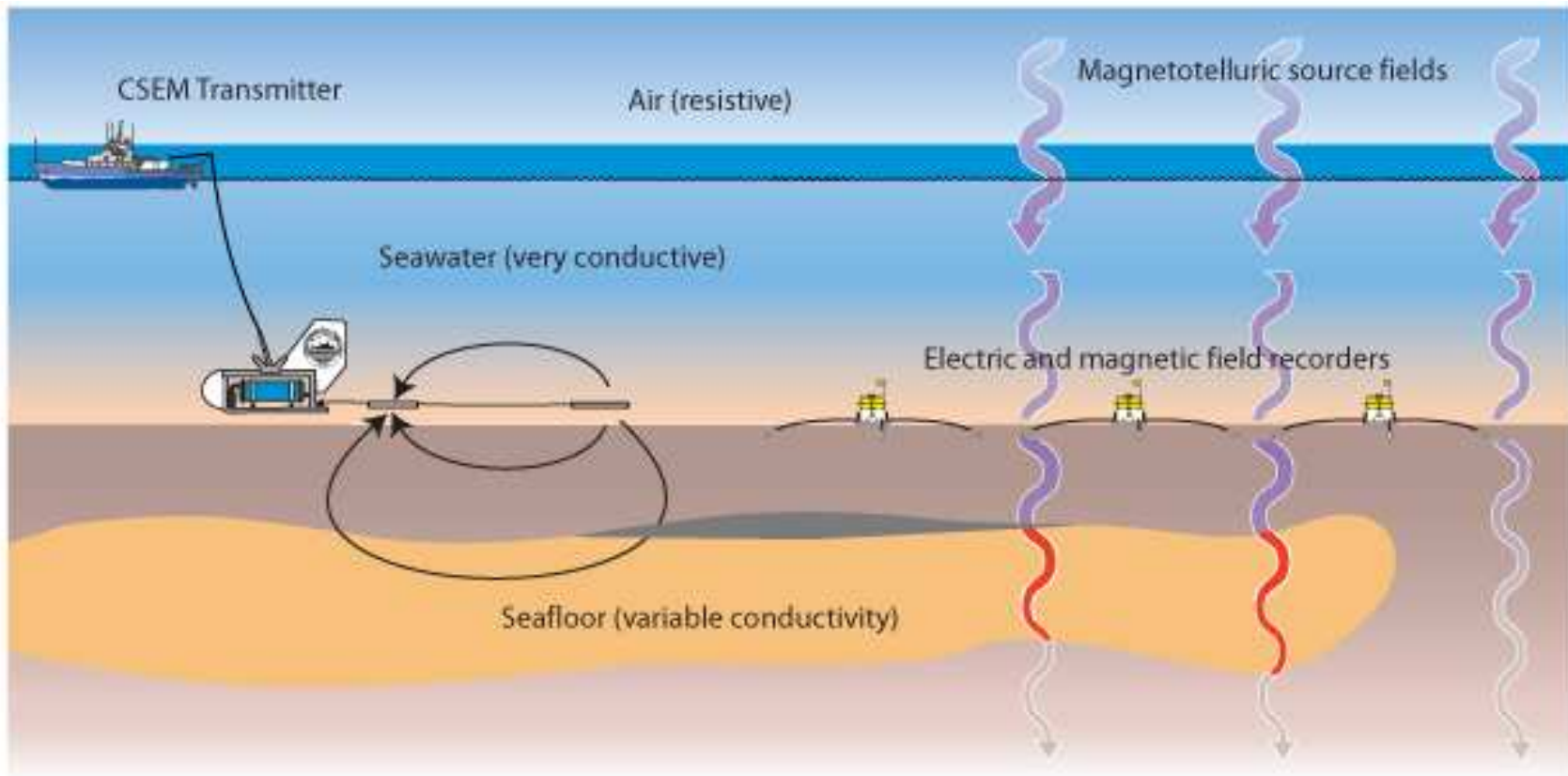
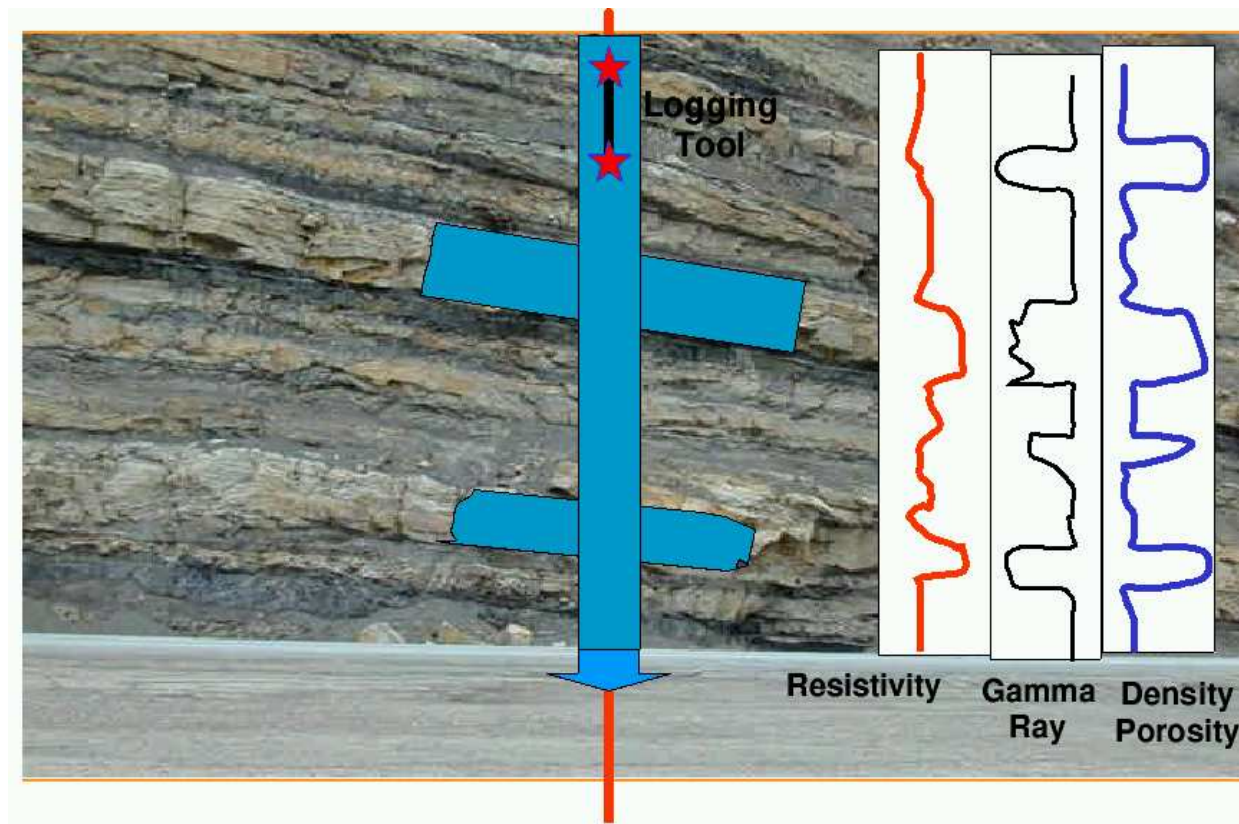


Figure from the UCSD Institute of Oceanography

MOTIVATION (OIL-INDUSTRY)

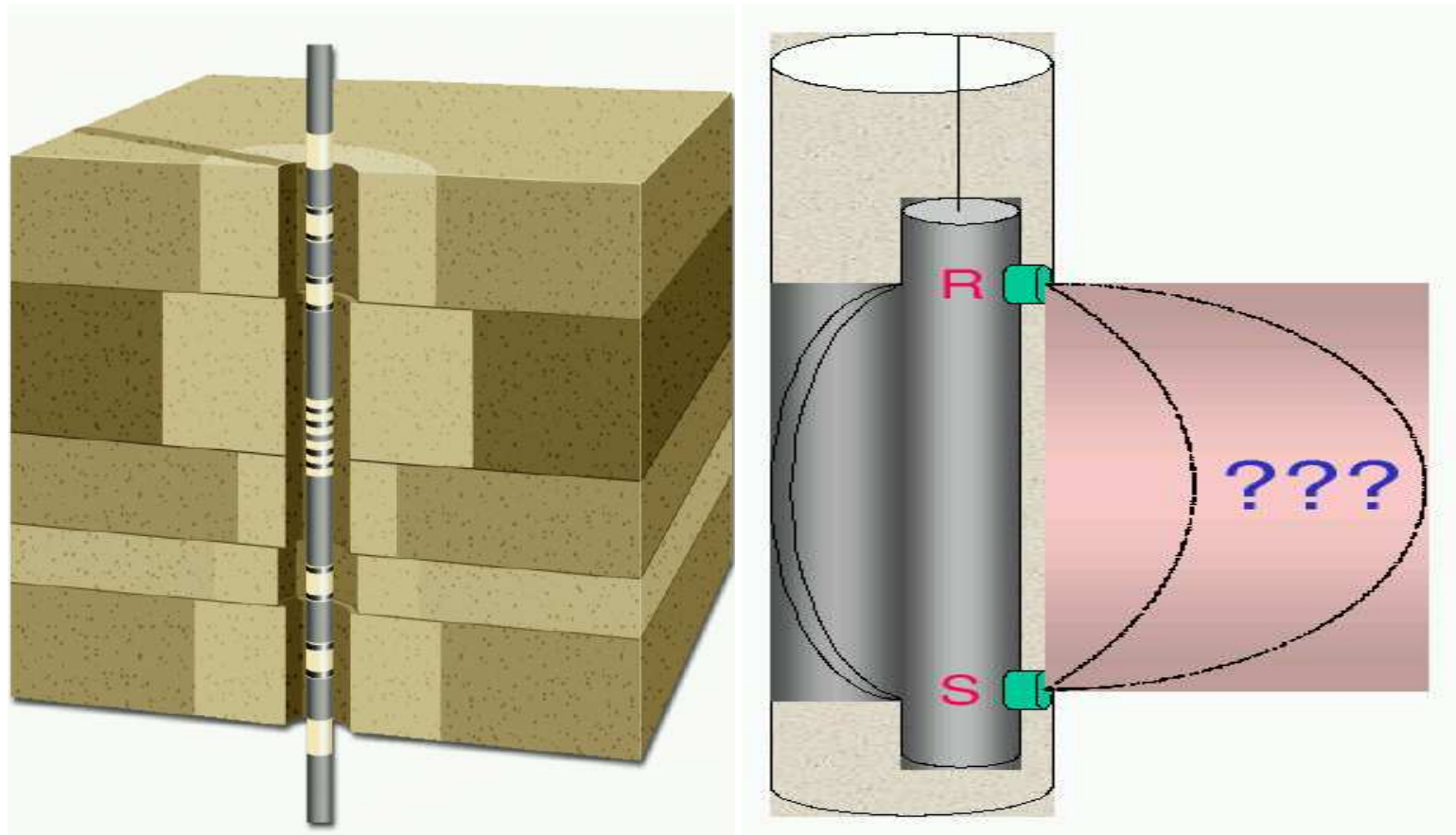
Multiphysics Logging Measurements



OBJECTIVES: To determine payzones (**porosity**), amount of oil/gas (**saturation**), and ability to extract oil/gas (**permeability**).

MOTIVATION (OIL-INDUSTRY)

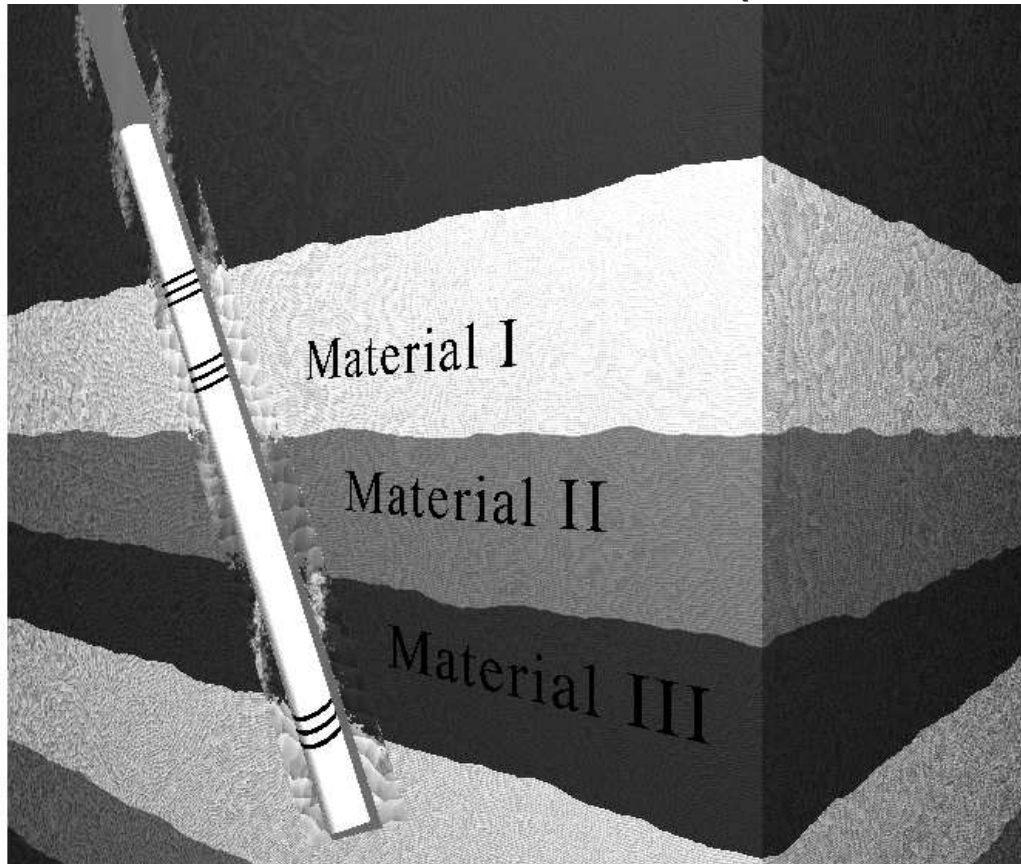
Main Objective: To Solve a Multiphysics Inverse Problem



Given multi-frequency electromagnetic, acoustic, and nuclear measurements, **the objective is to determine porosity, saturation, and permeability distributions in the reservoir.**

FOURIER FINITE ELEMENT METHOD

Deviated Wells (Forward Problem)

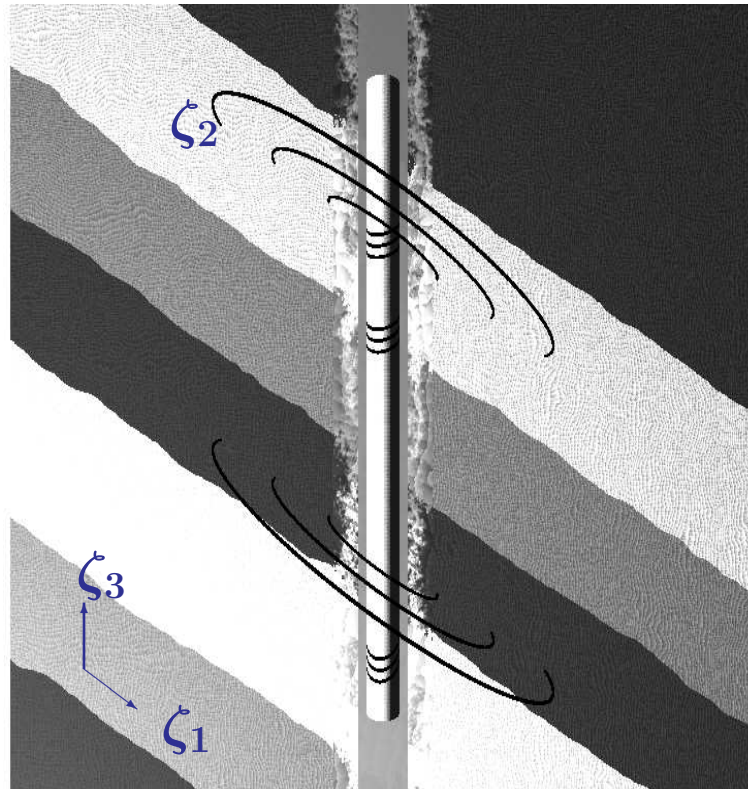


Dip Angle
Invasion
Anisotropy
Triaxial Induction
Eccentricity
Laterolog
Through-Casing
Induction-LWD
Induction-Wireline
Inverse Problems
Multi-Physics

Objective: Find solution at the receiver antennas.

FOURIER FINITE ELEMENT METHOD

Non-Orthogonal System of Coordinates



Material coefficients are constant with respect to the quasi-azimuthal direction ζ_2

Fourier Series Expansion in ζ_2

DC Problems: $-\nabla \sigma \nabla u = f$

$$u(\zeta_1, \zeta_2, \zeta_3) = \sum_{l=-\infty}^{l=\infty} u_l(\zeta_1, \zeta_3) e^{jl\zeta_2}$$

$$\sigma(\zeta_1, \zeta_2, \zeta_3) = \sum_{m=-\infty}^{m=\infty} \sigma_m(\zeta_1, \zeta_3) e^{jm\zeta_2}$$

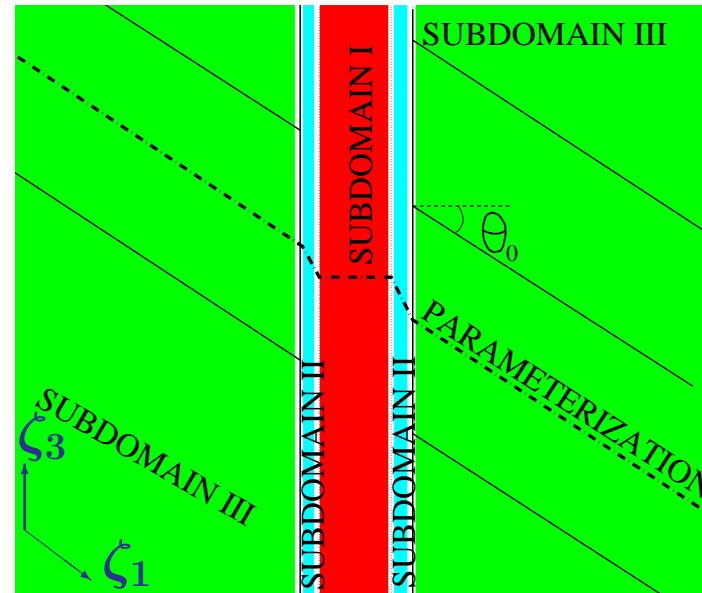
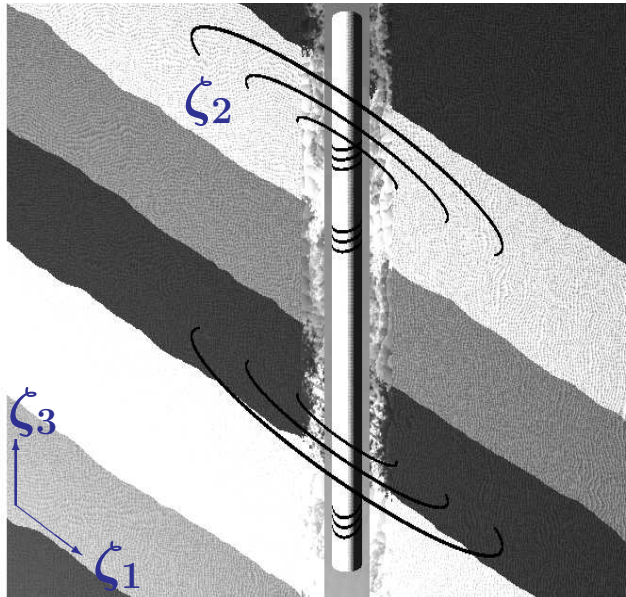
$$f(\zeta_1, \zeta_2, \zeta_3) = \sum_{n=-\infty}^{n=\infty} f_n(\zeta_1, \zeta_3) e^{jn\zeta_2}$$

Fourier modes $e^{jl\zeta_2}$ are orthogonal high-order basis functions that are (almost) invariant with respect to the gradient operator.

FOURIER FINITE ELEMENT METHOD

Cartesian system of coordinates: $\mathbf{x} = (x_1, x_2, x_3)$.

New non-orthogonal system of coordinates: $\zeta = (\zeta_1, \zeta_2, \zeta_3)$.



Subdomain I

;

Subdomain II

;

Subdomain III

$$\begin{cases} x_1 = \zeta_1 \cos \zeta_2 \\ x_2 = \zeta_1 \sin \zeta_2 \\ x_3 = \zeta_3 \end{cases}$$

$$\begin{cases} x_1 = \zeta_1 \cos \zeta_2 \\ x_2 = \zeta_1 \sin \zeta_2 \\ x_3 = \zeta_3 + \tan \theta_0 \frac{\zeta_1 - \rho_1}{\rho_2 - \rho_1} \rho_2 \end{cases}$$

$$\begin{cases} x_1 = \zeta_1 \cos \zeta_2 \\ x_2 = \zeta_1 \sin \zeta_2 \\ x_3 = \zeta_3 + \tan \theta_0 \zeta_1 \end{cases}$$

FOURIER FINITE ELEMENT METHOD

Final Variational Formulation

We define the Jacobian matrix $\mathcal{J} = \frac{\partial(x_1, x_2, x_3)}{\partial(\zeta_1, \zeta_2, \zeta_3)}$ and its determinant $|\mathcal{J}| = \det(\mathcal{J})$.

Variational formulation in the new system of coordinates:

$$\left\{ \begin{array}{l} \text{Find } u \in u_D + H_D^1(\Omega) \text{ such that:} \\ \left\langle \frac{\partial v}{\partial \zeta}, \tilde{\sigma} \frac{\partial u}{\partial \zeta} \right\rangle_{L^2(\Omega)} = \left\langle v, \tilde{f} \right\rangle_{L^2(\Omega)} \quad \forall v \in H_D^1(\Omega), \end{array} \right.$$

where:

$$\tilde{\sigma} := \mathcal{J}^{-1} \sigma \mathcal{J}^{-1T} |\mathcal{J}| \quad ; \quad \tilde{f} := f |\mathcal{J}| .$$

Same variational formulation with new materials and load data

FOURIER FINITE ELEMENT METHOD

Five Fourier modes are enough to represent EXACTLY the new material coefficients.

Direct Current:

$$\left\{ \begin{array}{l} \text{Find } u \in u_D + H_D^1(\Omega) \text{ such that:} \\ \sum_{n=k-2}^{n=k+2} \left\langle \left(\frac{\partial v}{\partial \zeta} \right)_k, \tilde{\sigma}_{k-n} \left(\frac{\partial u}{\partial \zeta} \right)_n \right\rangle_{L^2(\Omega_{2D})} = \left\langle v_k, \tilde{f}_k \right\rangle_{L^2(\Omega_{2D})} \quad \forall v_k \end{array} \right.$$

Alternate Current:

$$\left\{ \begin{array}{l} \text{Find } (\mathbf{E})_s \in H_{\Gamma_E}(\text{curl}; \Omega) \text{ such that:} \\ \sum_{n=s-2}^{n=s+2} \left\langle (\nabla^\zeta \times \mathbf{F})_s, (\tilde{\mu}^{-1})_{s-n} (\nabla^\zeta \times \mathbf{E})_l \right\rangle_{L^2(\Omega_{2D})} \\ - \left\langle \mathbf{F}_s, (\tilde{k}^2)_{s-n} \mathbf{E}_l \right\rangle_{L^2(\Omega_{2D})} = -j\omega \left\langle \mathbf{F}_s, (\tilde{\mathbf{J}}^{imp})_s \right\rangle_{L^2(\Omega_{2D})} \quad \forall \mathbf{F}_s \end{array} \right.$$

FOURIER FINITE ELEMENT METHOD

Example (7 Fourier Modes)

$$\sum_{n=k-2}^{n=k+2} \underbrace{\left\langle \left(\frac{\partial v}{\partial \zeta} \right)_k, \tilde{\sigma}_{k-n} \left(\frac{\partial u}{\partial \zeta} \right)_n \right\rangle_{L^2(\Omega_{2D})}}_{(k, k-n, n)} = \langle v_k, \tilde{f}_k \rangle_{L^2(\Omega_{2D})}$$

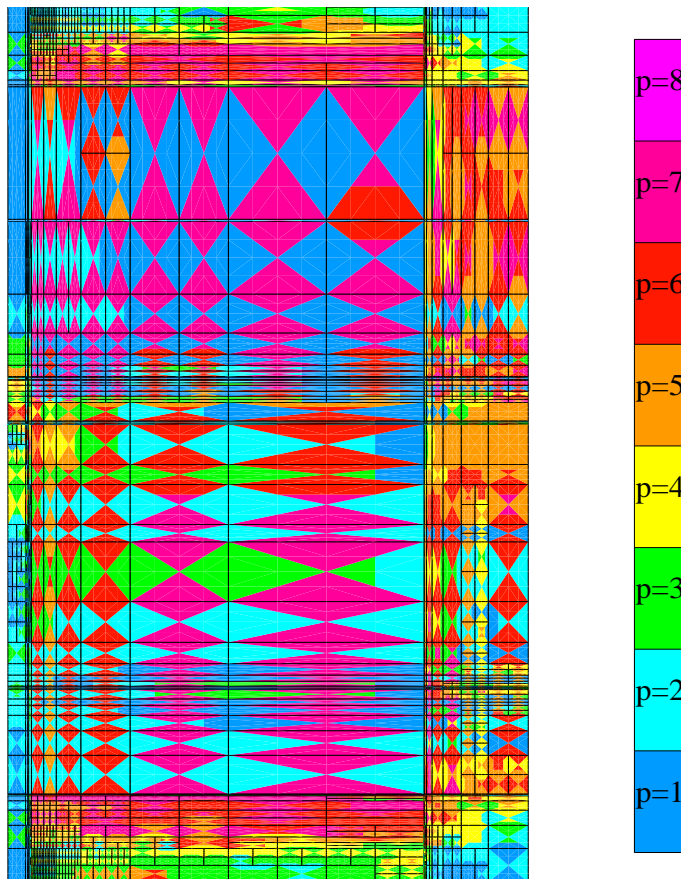
Stiffness Matrix:

$$\begin{pmatrix} (-3,0,-3) & (-3,-1,-2) & (-3,-2,-1) & 0 & 0 & 0 & 0 \\ (-2,1,-3) & (-2,0,-2) & (-2,-1,-1) & (-2,-2,0) & 0 & 0 & 0 \\ (-1,2,-3) & (-1,1,-2) & (-1,0,-1) & (-1,-1,0) & (-1,-2,1) & 0 & 0 \\ 0 & (0,2,-2) & (0,1,-1) & (0,0,0) & (0,-1,1) & (0,-2,2) & 0 \\ 0 & 0 & (1,2,-1) & (1,1,0) & (1,0,1) & (1,-1,2) & (1,-2,3) \\ 0 & 0 & 0 & (2,2,0) & (2,1,1) & (2,0,2) & (2,-1,3) \\ 0 & 0 & 0 & 0 & (3,2,1) & (3,1,2) & (3,0,3) \end{pmatrix}$$

FOURIER FINITE ELEMENT METHOD

A Self-Adaptive Goal-Oriented hp -FEM

Optimal 2D Grid
(Through Casing Resistivity Problem)



We vary locally the element size h and the polynomial order of approximation p throughout the grid.

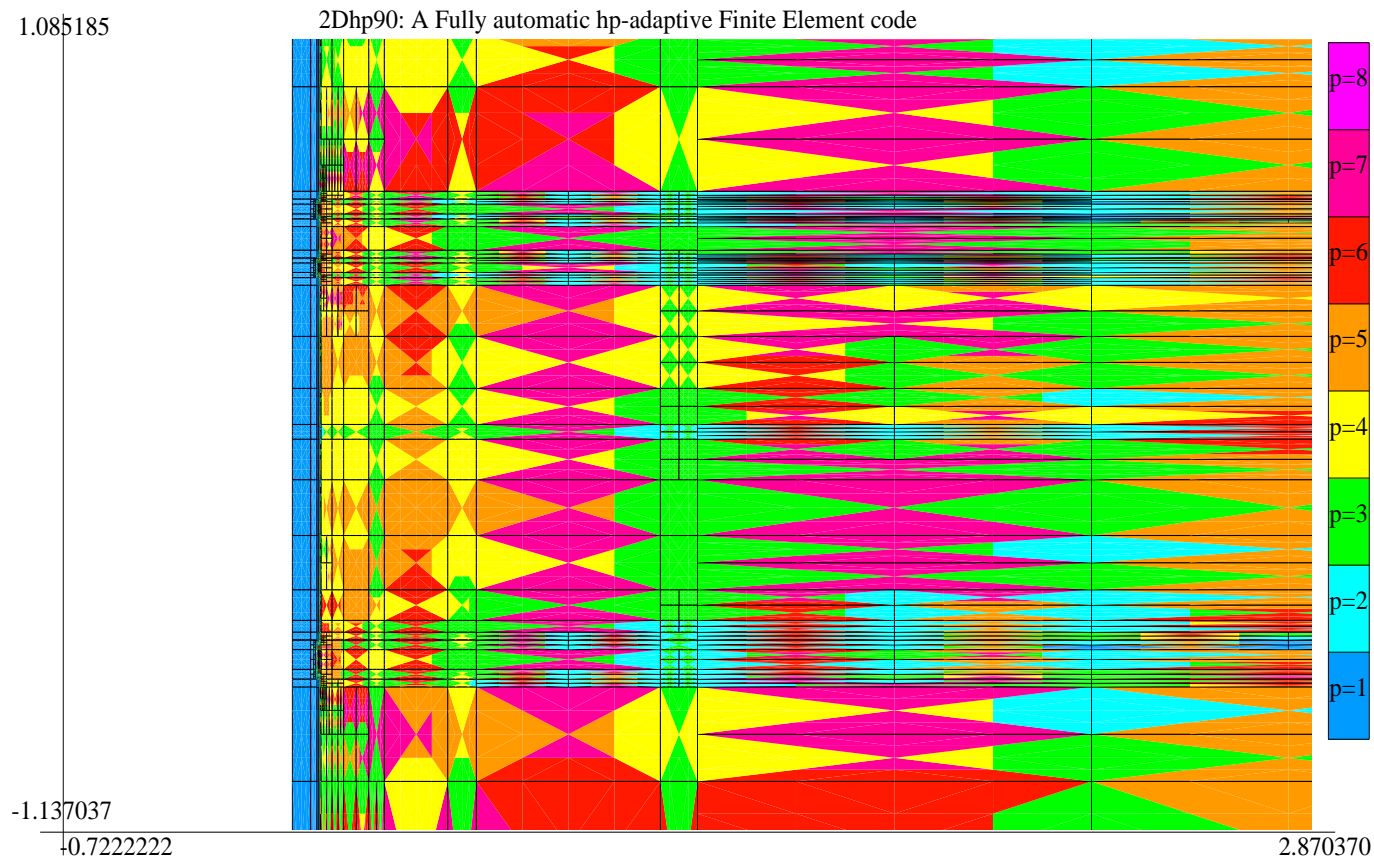
Optimal grids are **automatically generated** by the computer.

The self-adaptive goal-oriented hp -FEM provides **exponential convergence** rates in terms of the CPU time vs. the error in a user prescribed quantity of interest.

FOURIER FINITE ELEMENT METHOD

Axisymmetric Logging-While-Drilling (LWD) Simulation

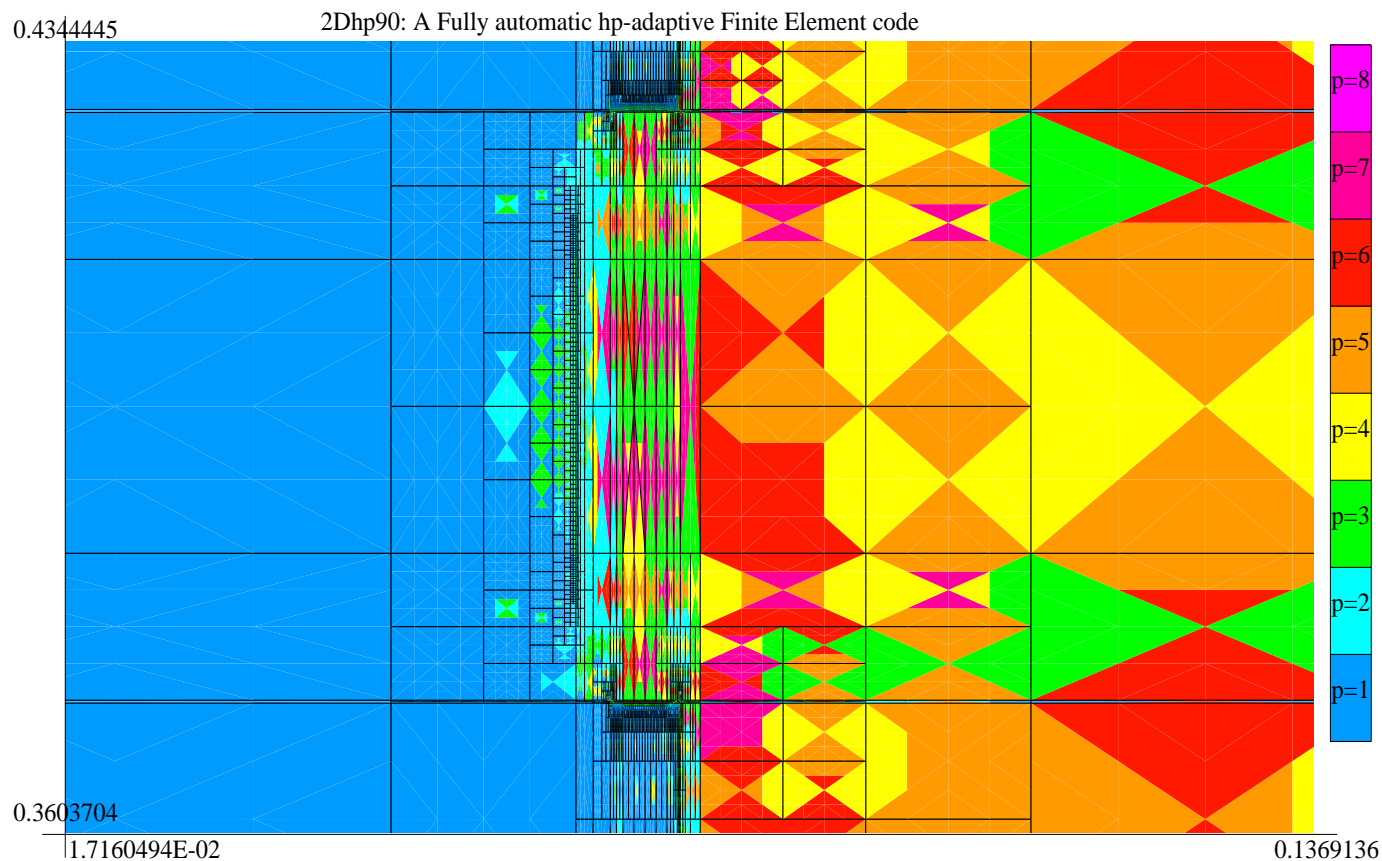
GOAL-ORIENTED HP-ADAPTIVITY (Quadrilateral Elements)



FOURIER FINITE ELEMENT METHOD

Axisymmetric Logging-While-Drilling (LWD) Simulation

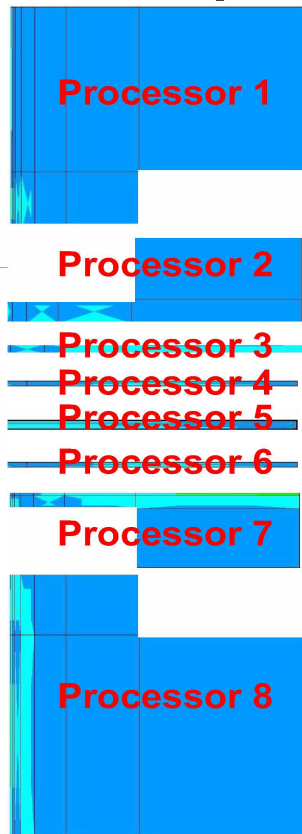
GOAL-ORIENTED HP-ADAPTIVITY (ZOOM TOWARDS FIRST RECEIVER ANTENNA)



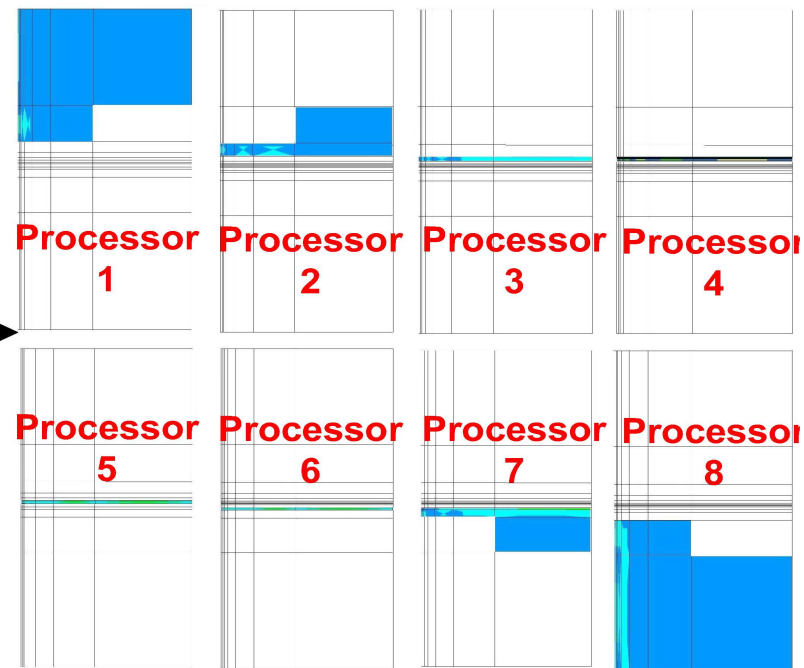
PARALLEL IMPLEMENTATION

We Use Shared Domain Decomposition

**Distributed
Domain
Decomposition**



**Shared
Domain Decomposition**



MULTIPHYSICS FRAMEWORK

We are generating new data structures based on:

The addition of **one new module/library** for solving inverse problems.

The use of **different number of equations** for each element/node.

- Enables to consider different physics for each element/node.
- Enables the use of different number of Fourier modes for each element/node.

The combination of **different types of elements** used for each physics:

- Continuous H^1 -elements (DC problems, elasticity, etc.)
- Nedelec (edge) $H(\text{curl})$ -elements (Electromagnetics).
- Raviart-Thomas (face) $H(\text{div})$ -elements (Fluid-dynamics)
- Discontinuous L^2 -elements.

MULTIPHYSICS FRAMEWORK

Final hp -grid and solution

Monopole source, open borehole setting:

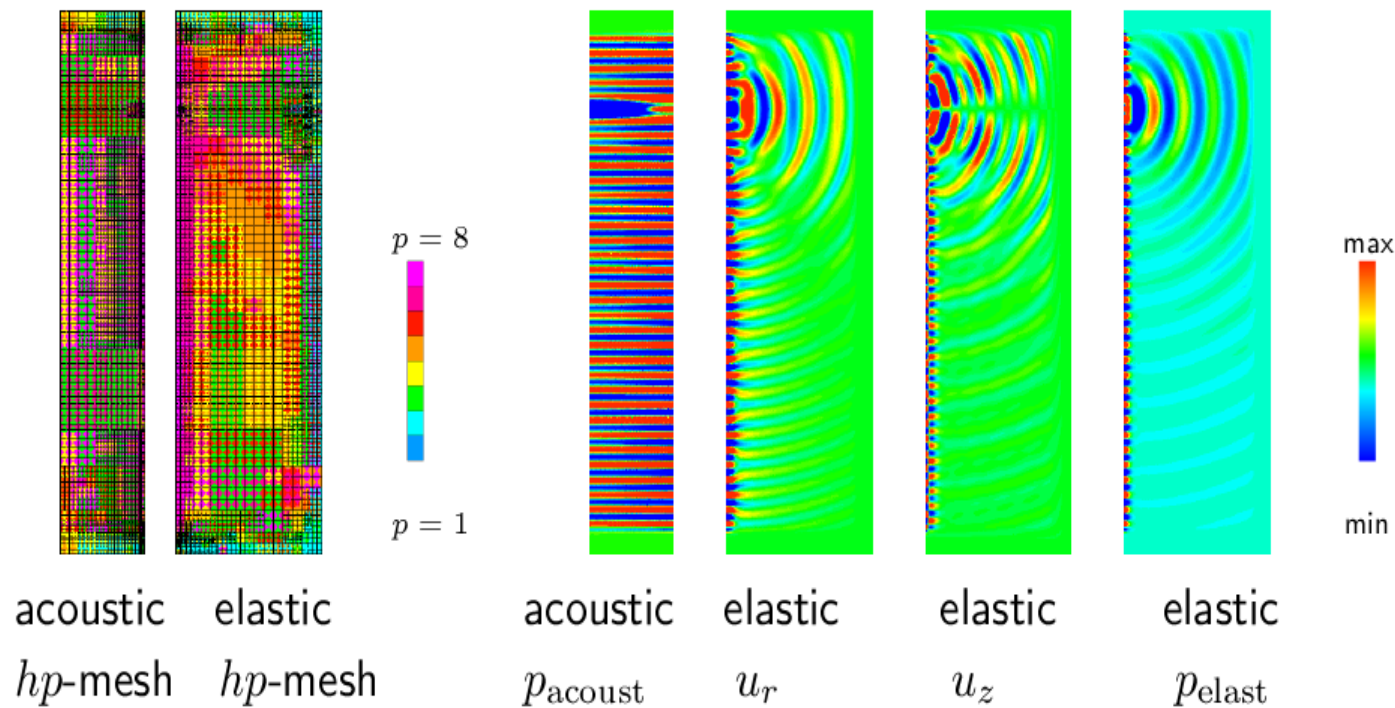
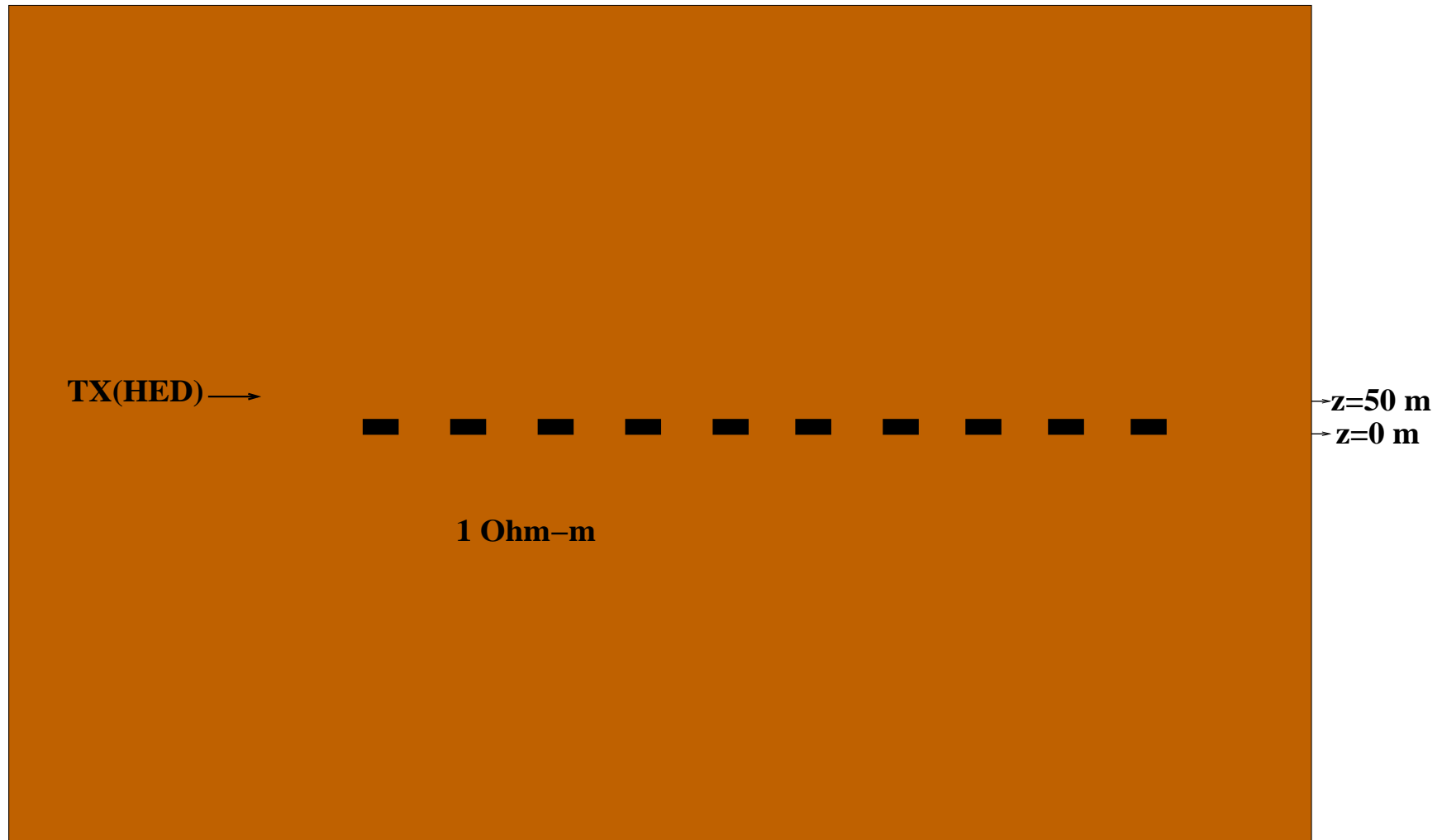


Figure: Frequency-domain solution at the center frequency of 8 kHz (acoustics subdomain scaled by a factor of 10 in radial direction; plotting ranges [0.1 min, 0.1 max])

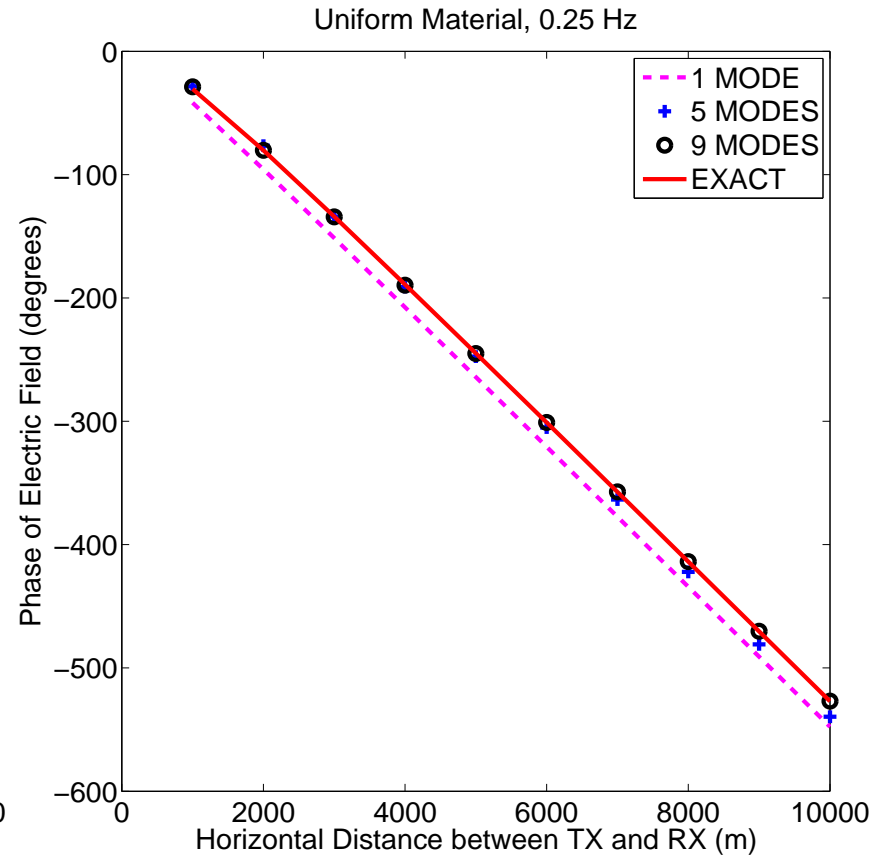
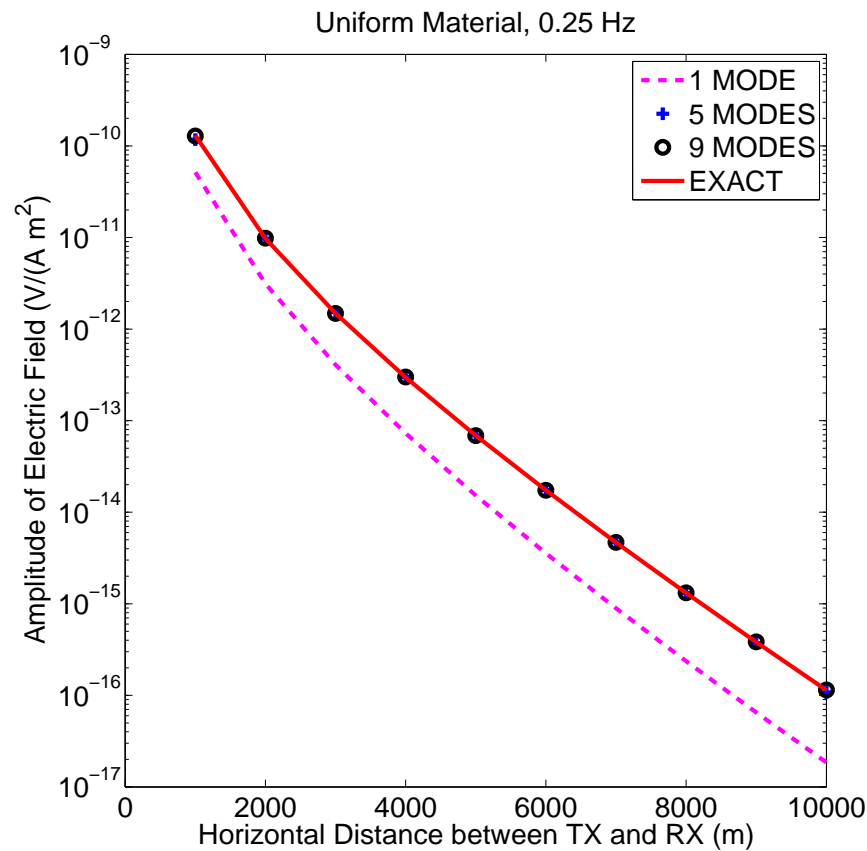
RESULTS: 2D MARINE CSEM

Model Problem I: UNIFORM FORMATION



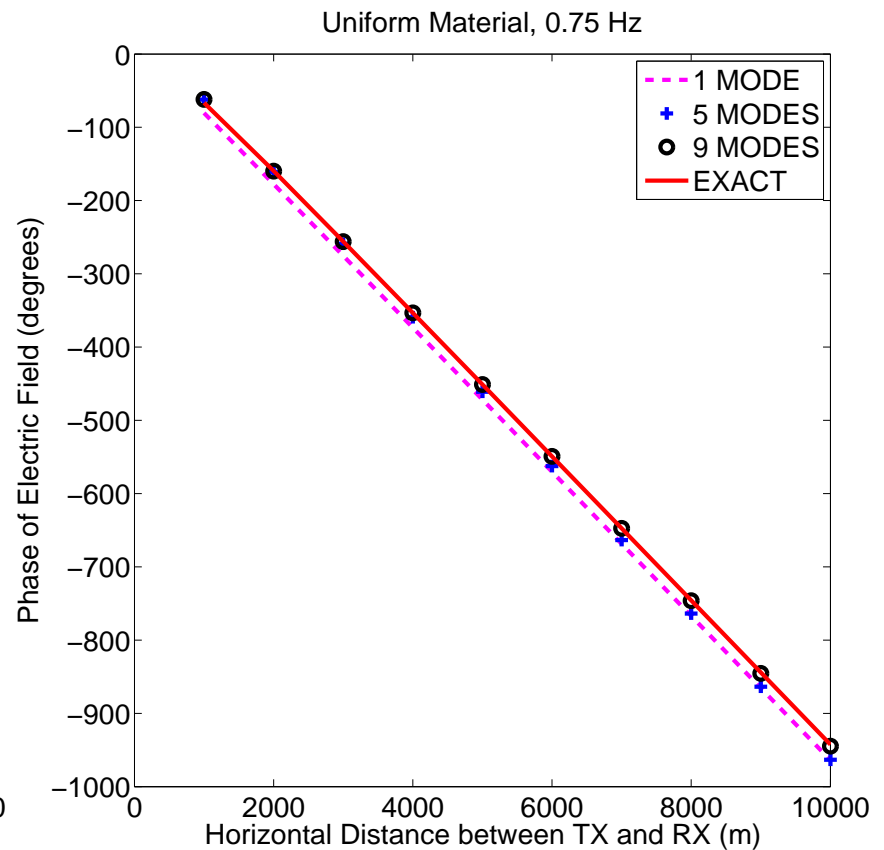
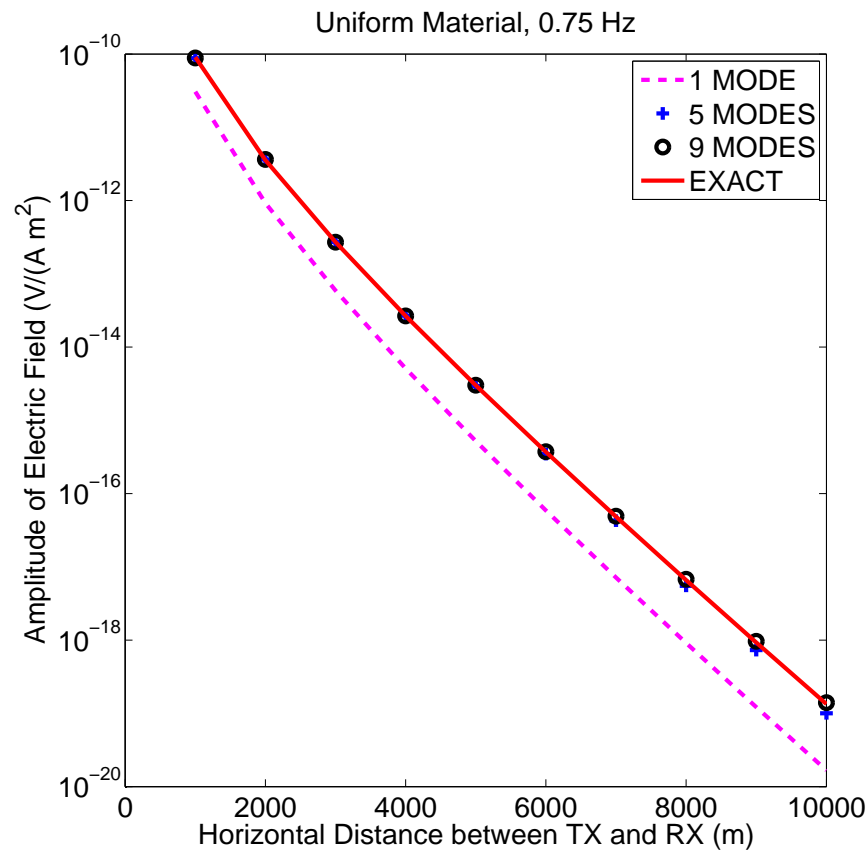
RESULTS: 2D MARINE CSEM

Model Problem I: UNIFORM FORMATION — 0.25 Hz —



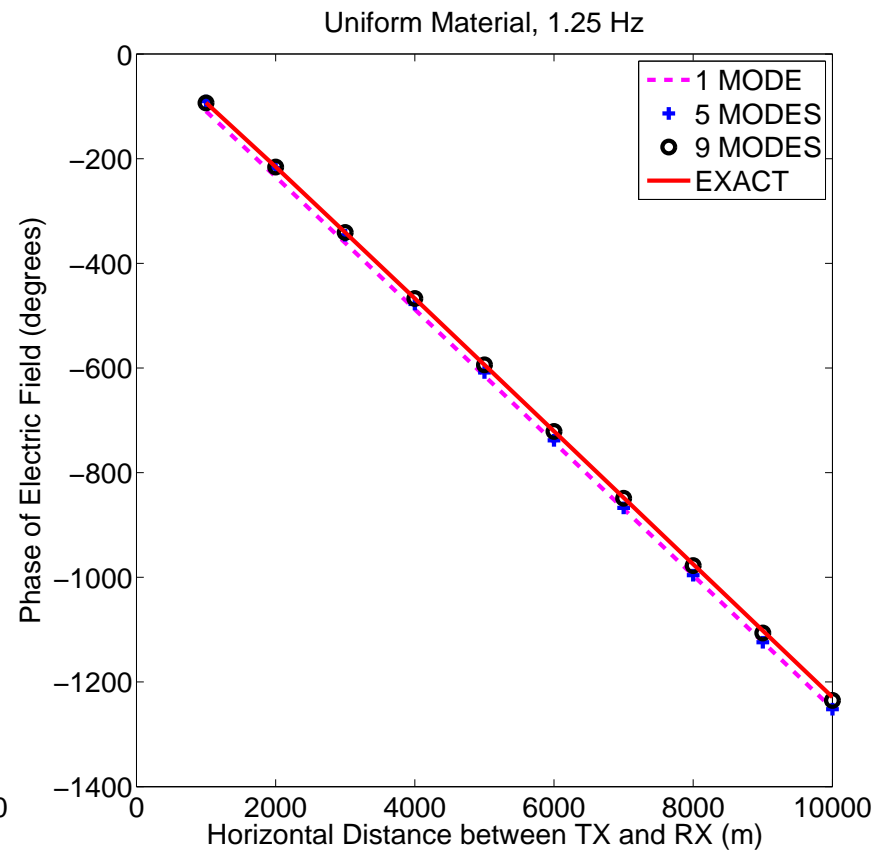
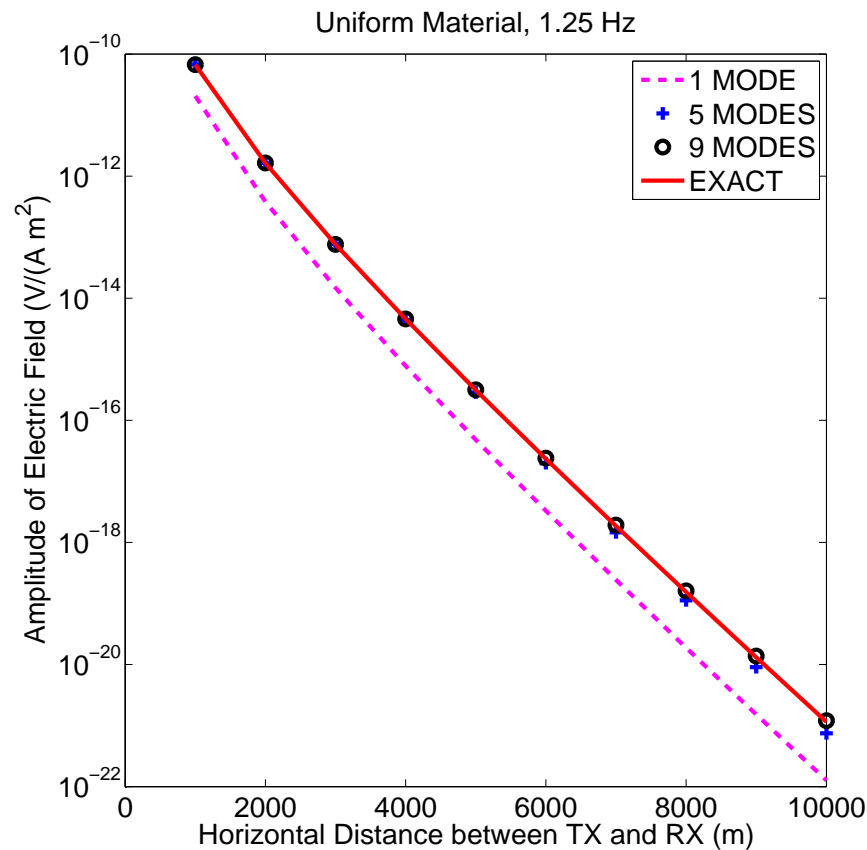
RESULTS: 2D MARINE CSEM

Model Problem I: UNIFORM FORMATION — 0.75 Hz —



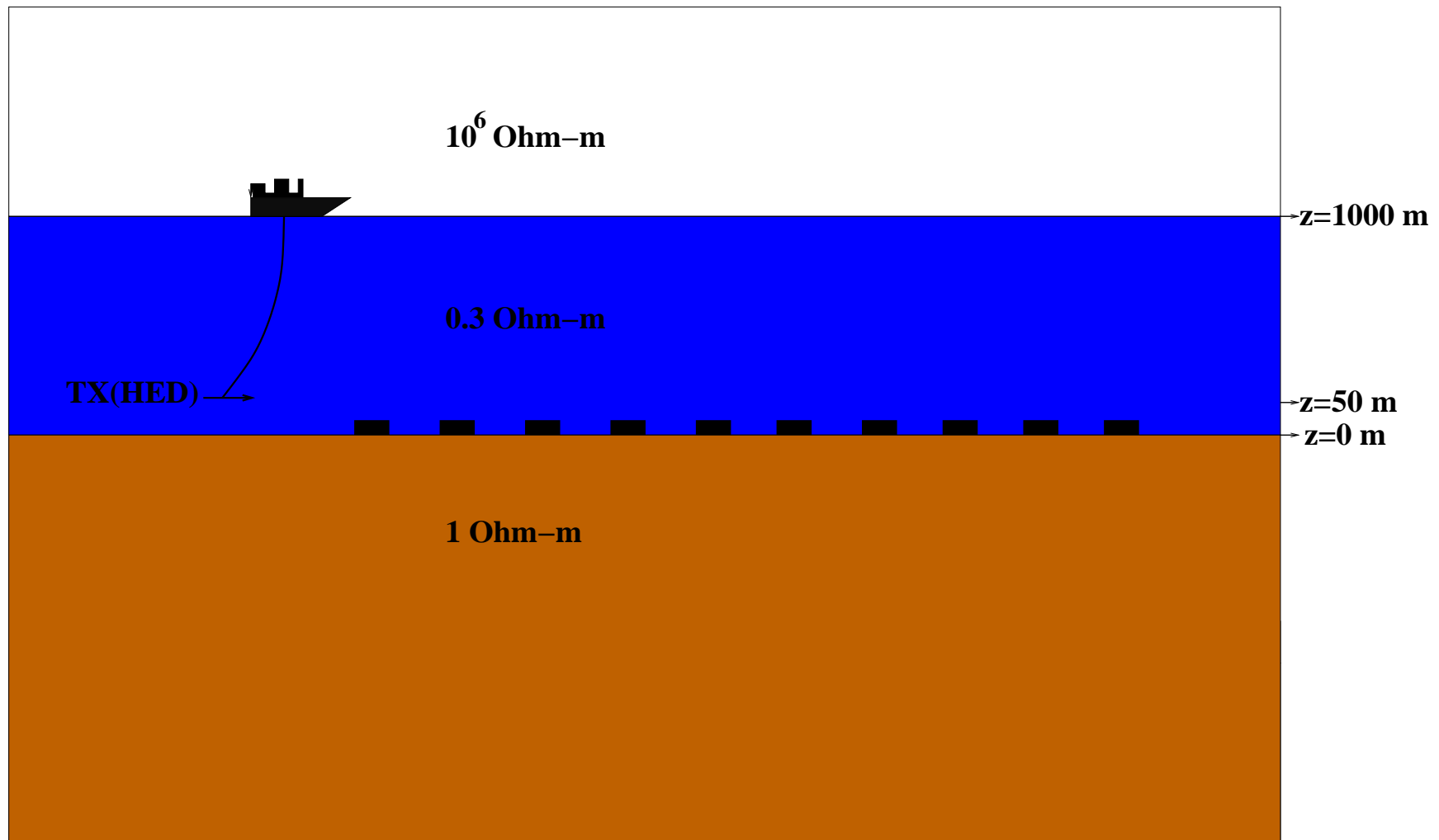
RESULTS: 2D MARINE CSEM

Model Problem I: UNIFORM FORMATION — 1.25 Hz —



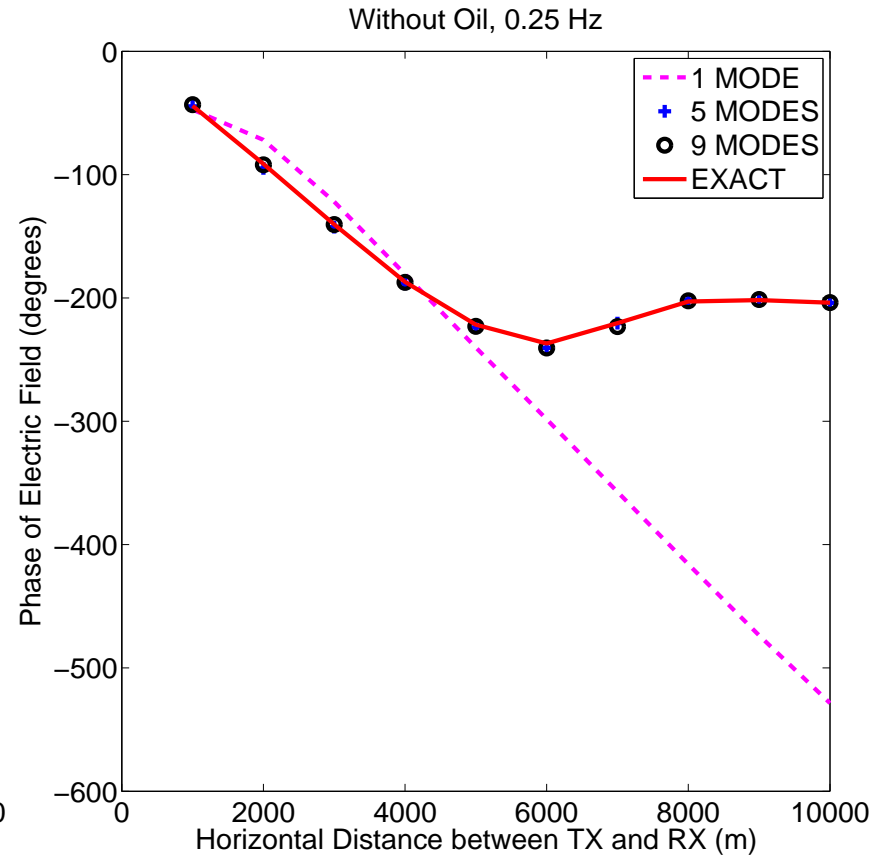
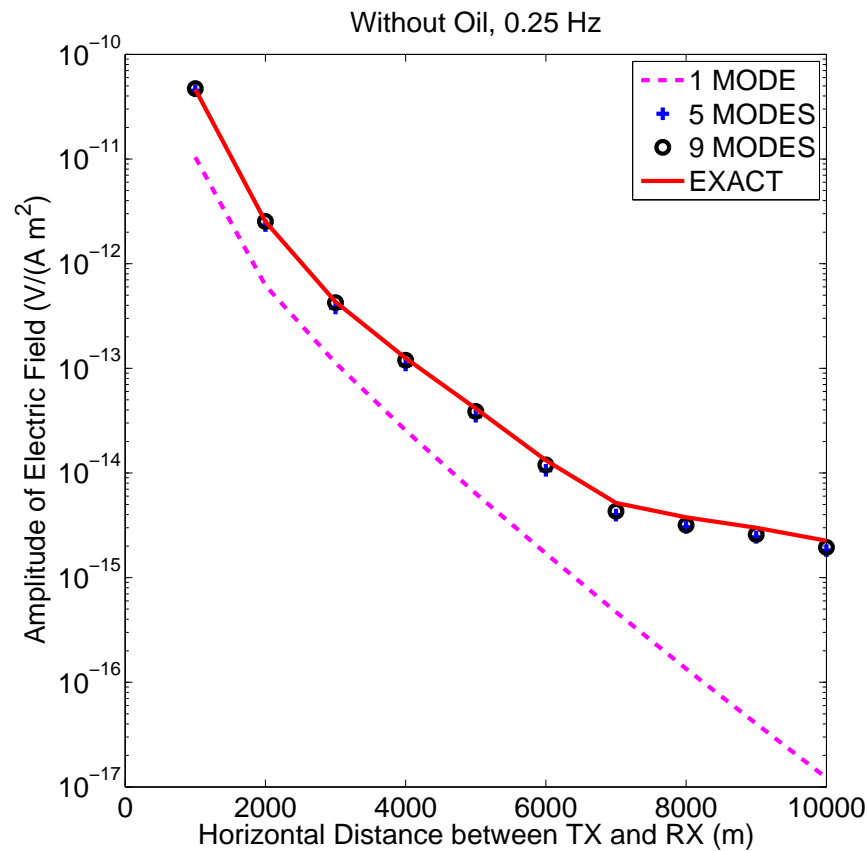
RESULTS: 2D MARINE CSEM

Model Problem II: CSEM SCENARIO WITHOUT OIL



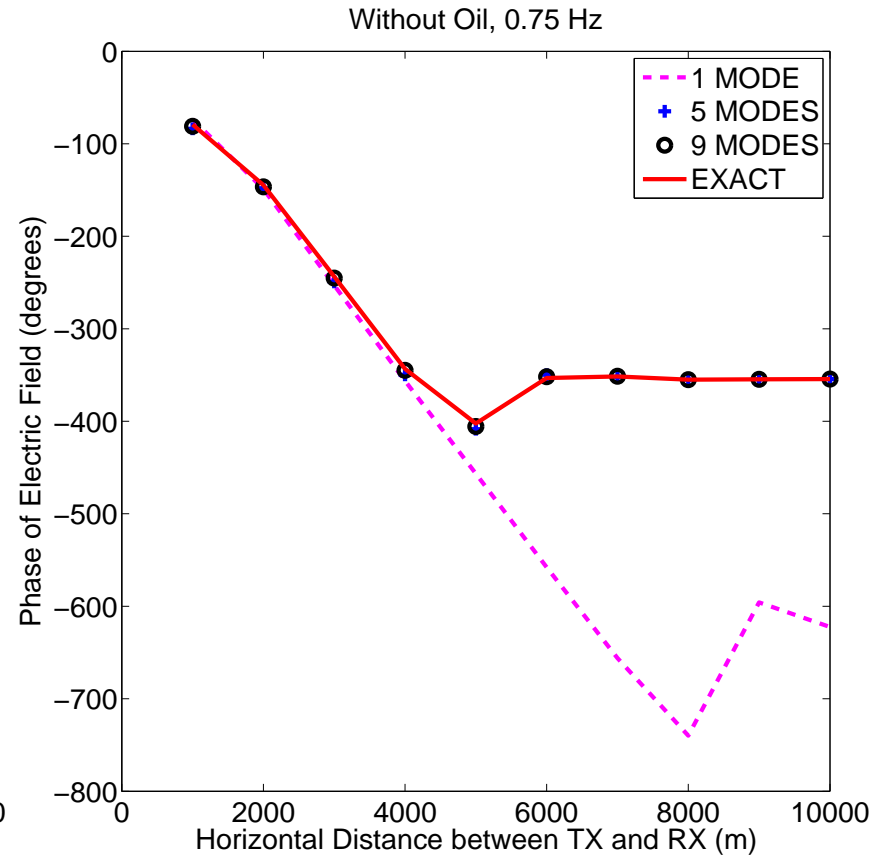
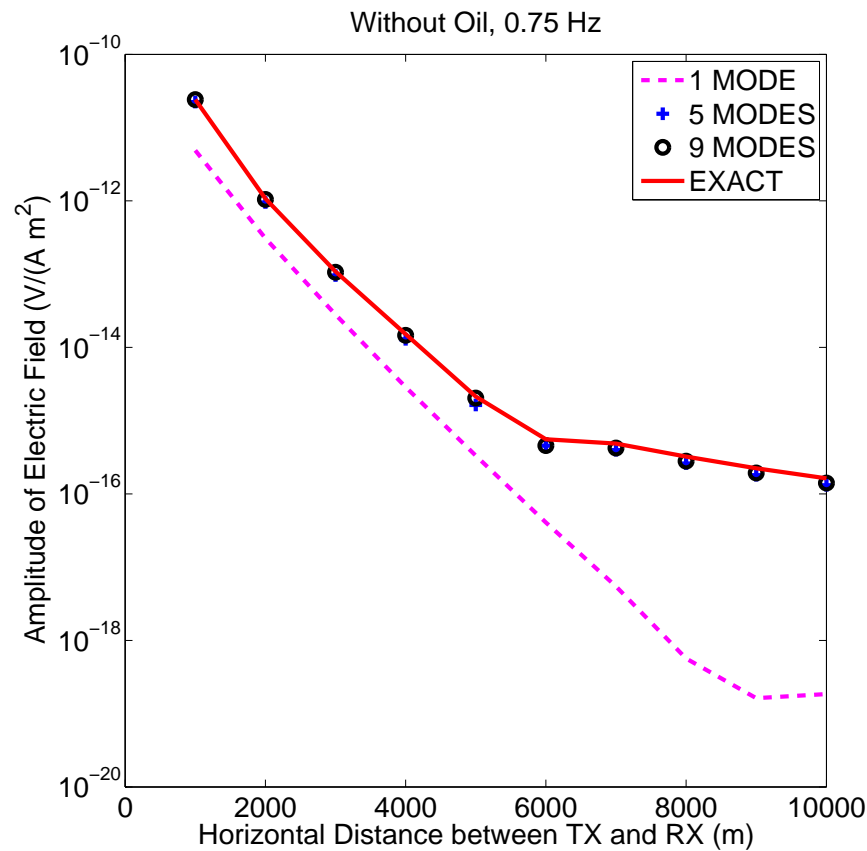
RESULTS: 2D MARINE CSEM

Model Problem II: WITHOUT OIL — 0.25 Hz —



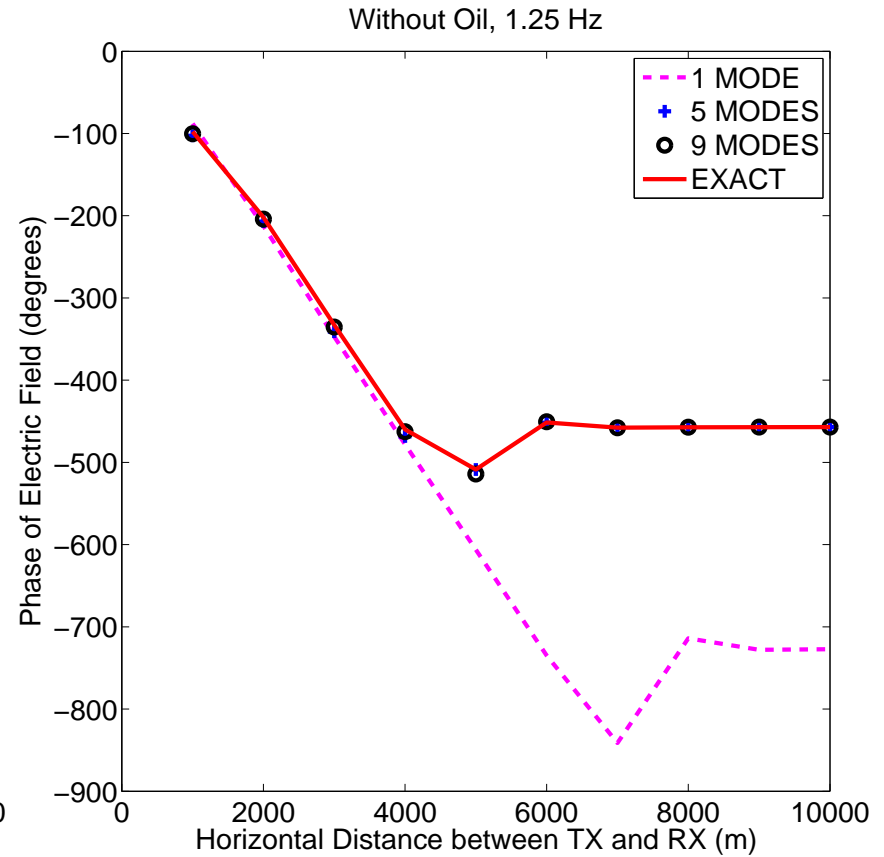
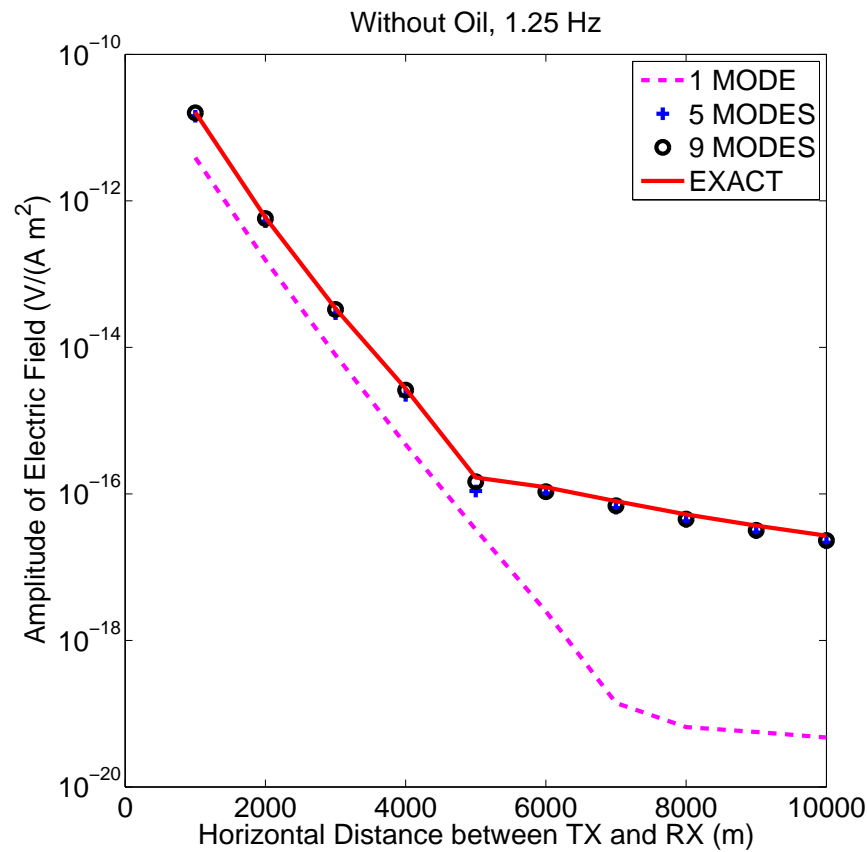
RESULTS: 2D MARINE CSEM

Model Problem II: WITHOUT OIL — 0.75 Hz —



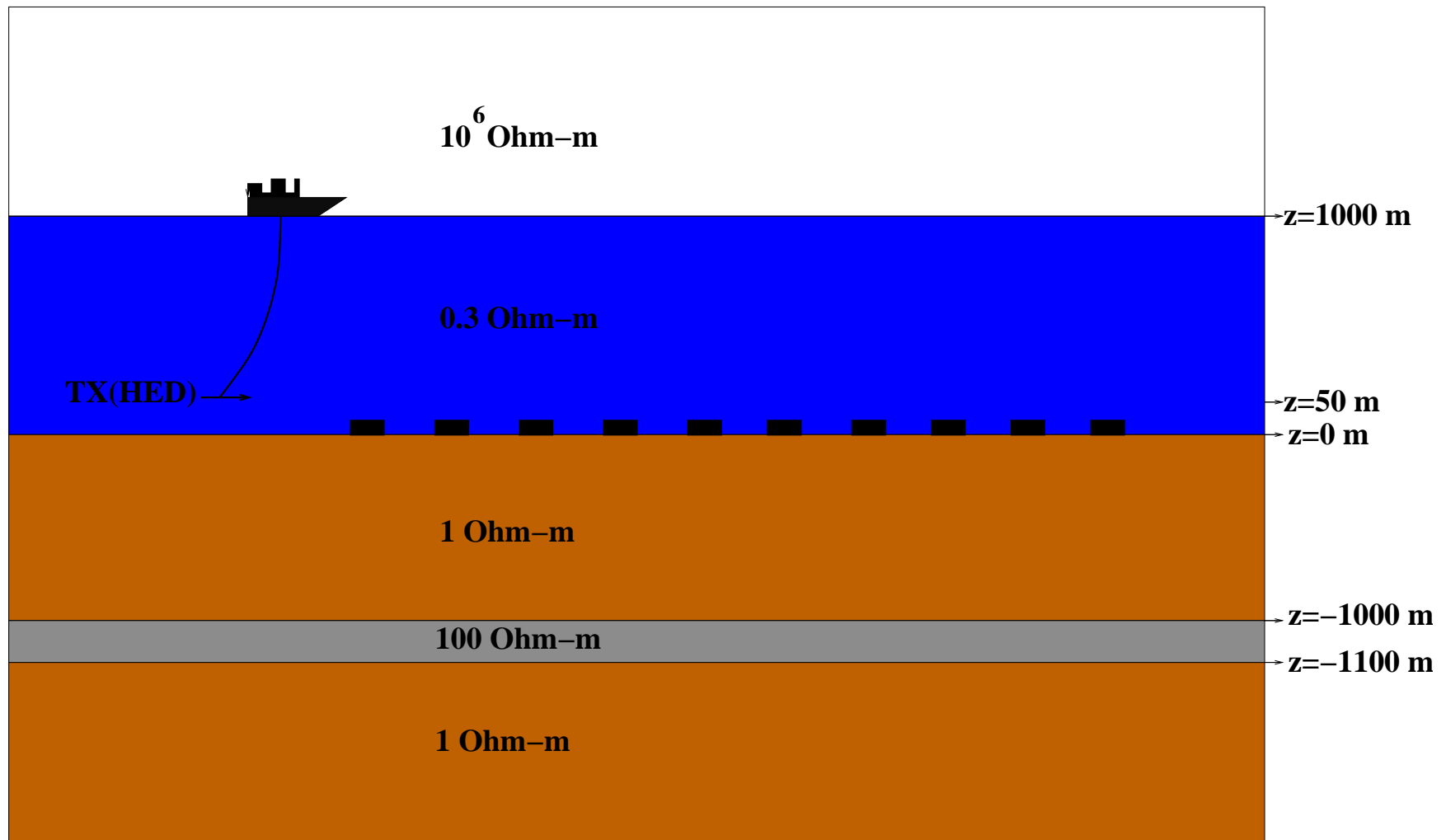
RESULTS: 2D MARINE CSEM

Model Problem II: WITHOUT OIL — 1.25 Hz —



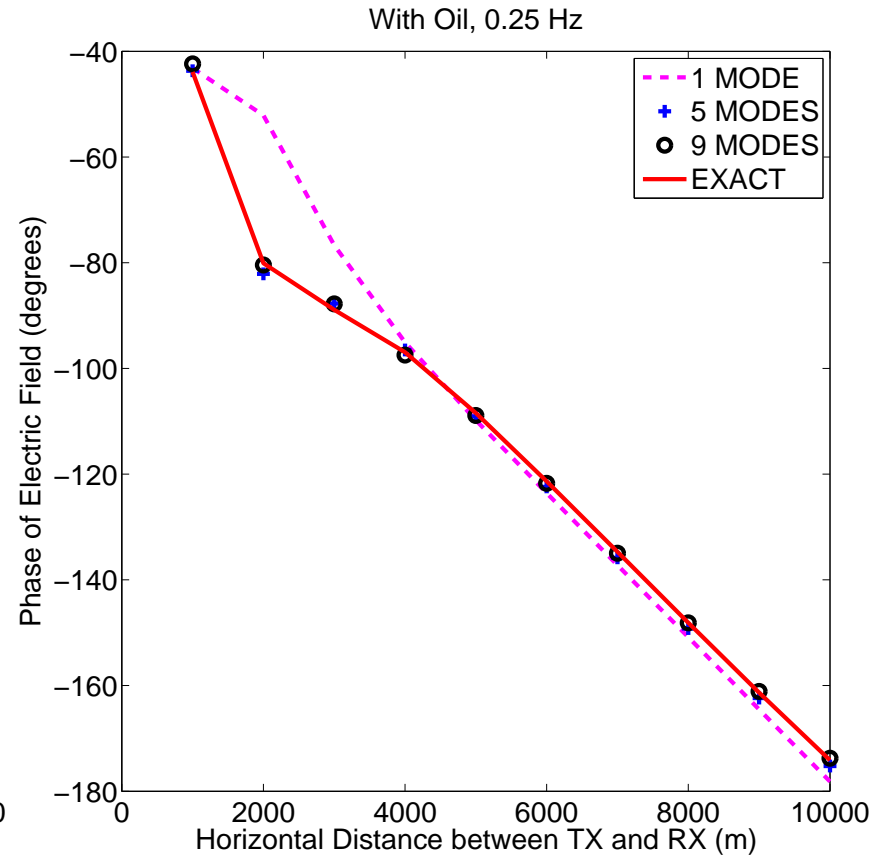
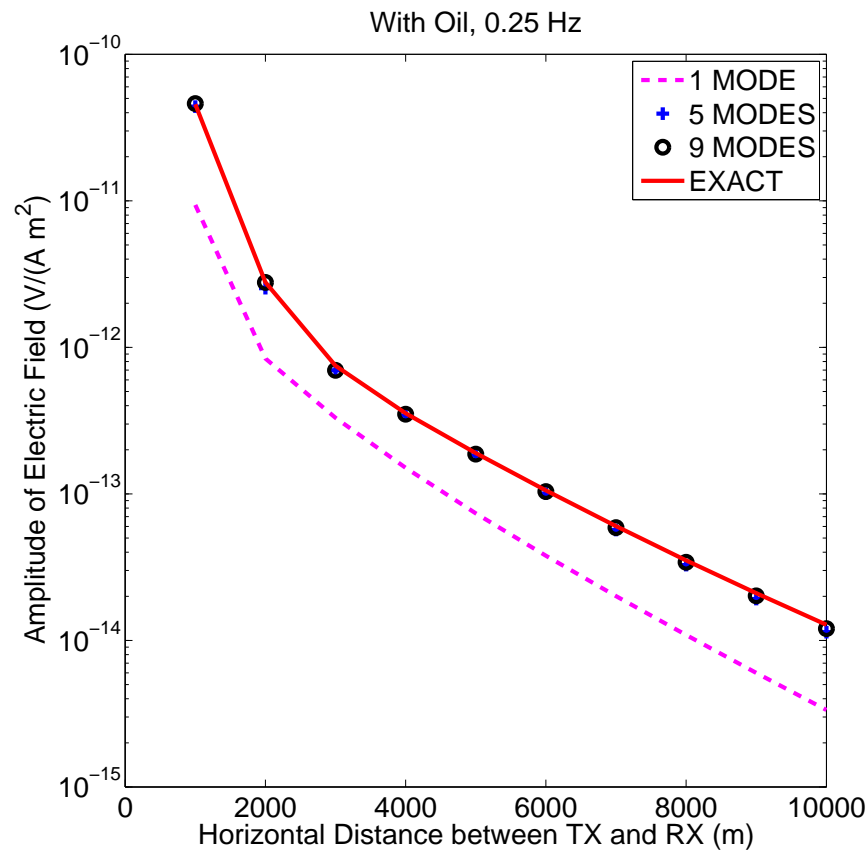
RESULTS: 2D MARINE CSEM

Model Problem III: CSEM SCENARIO WITH OIL



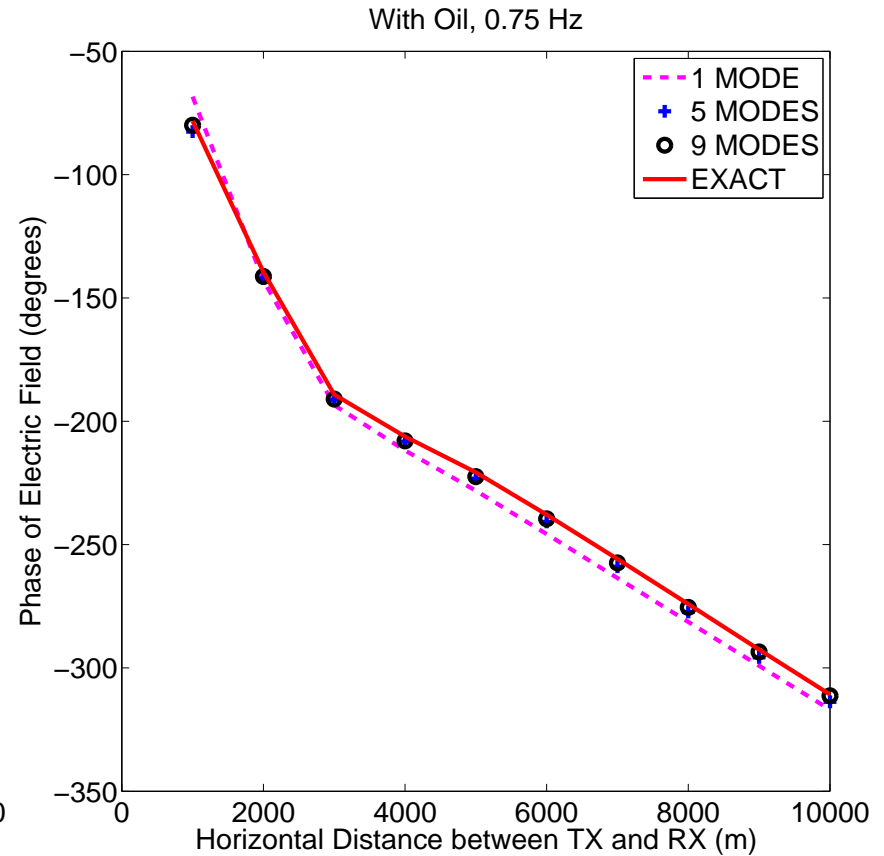
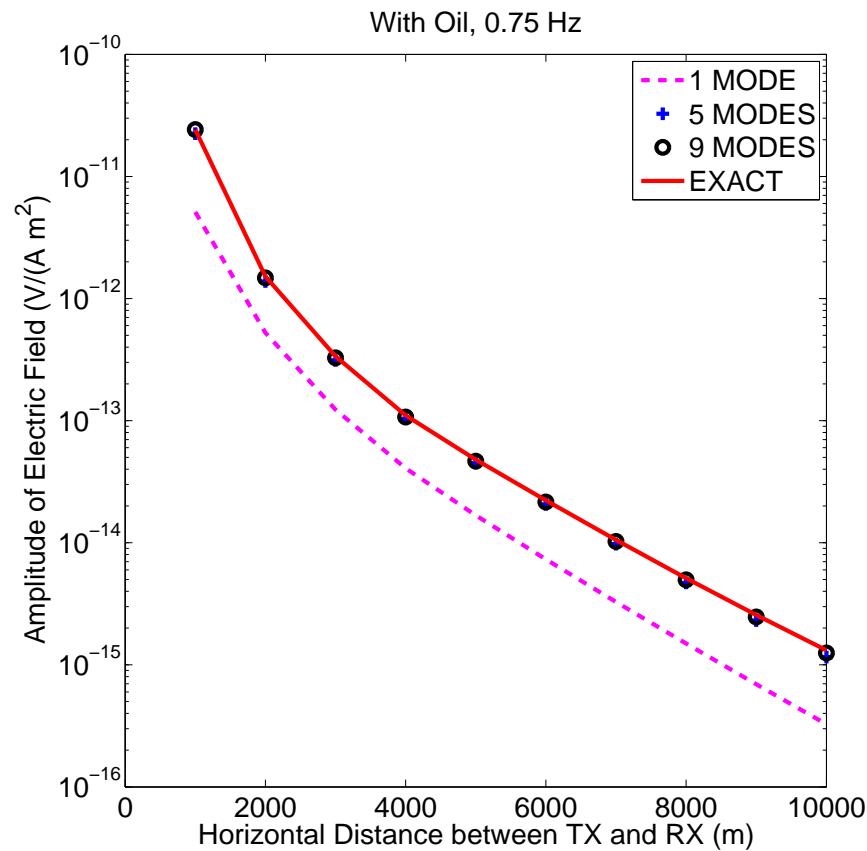
RESULTS: 2D MARINE CSEM

Model Problem III: WITH OIL — 0.25 Hz —



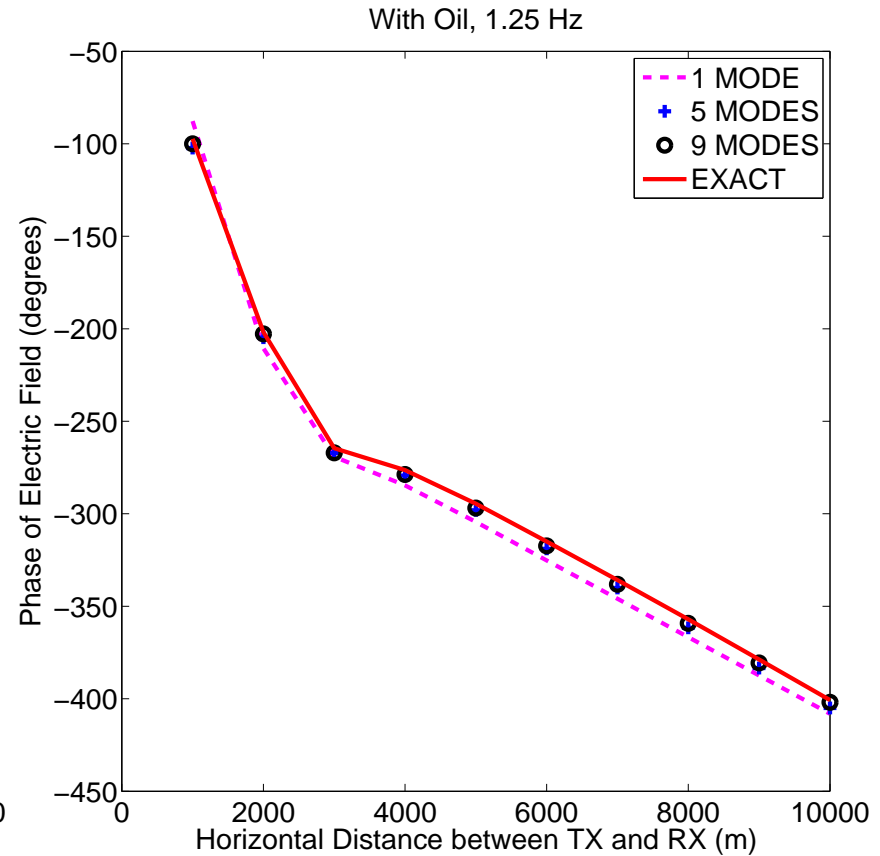
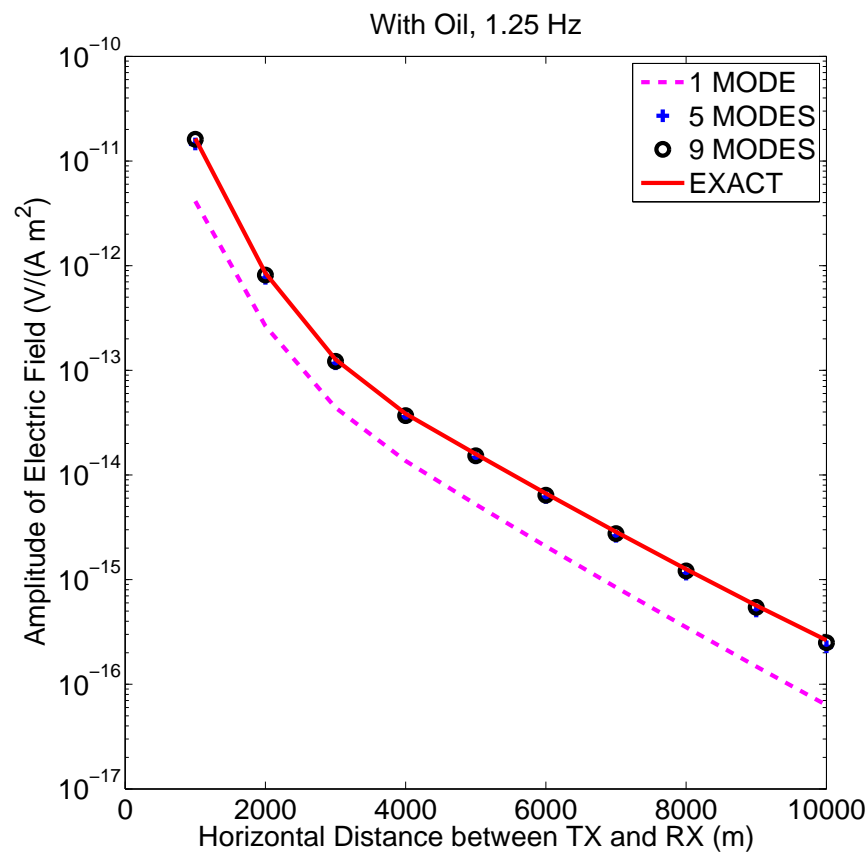
RESULTS: 2D MARINE CSEM

Model Problem III: WITH OIL — 0.75 Hz —



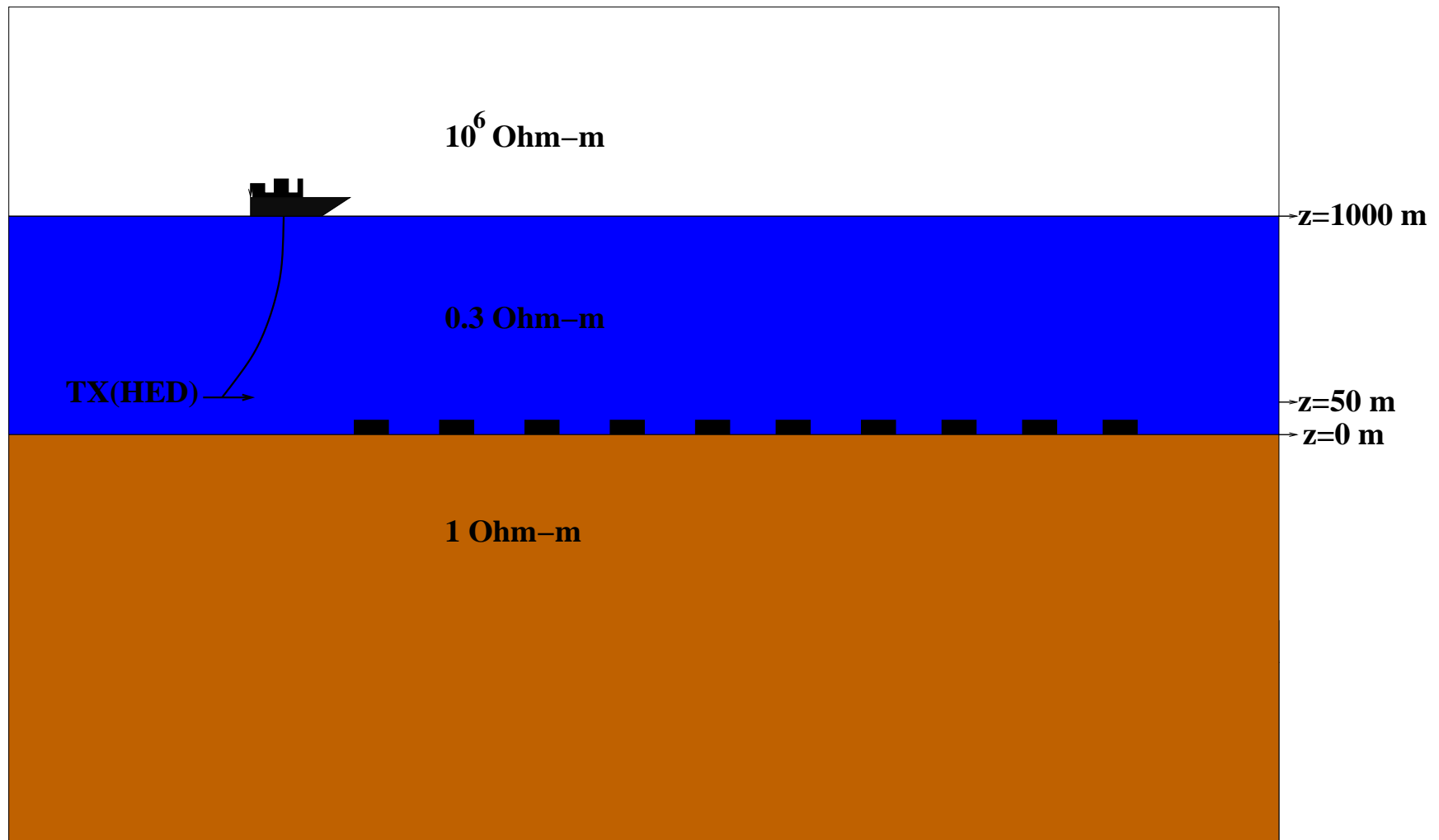
RESULTS: 2D MARINE CSEM

Model Problem III: WITH OIL — 1.25 Hz —



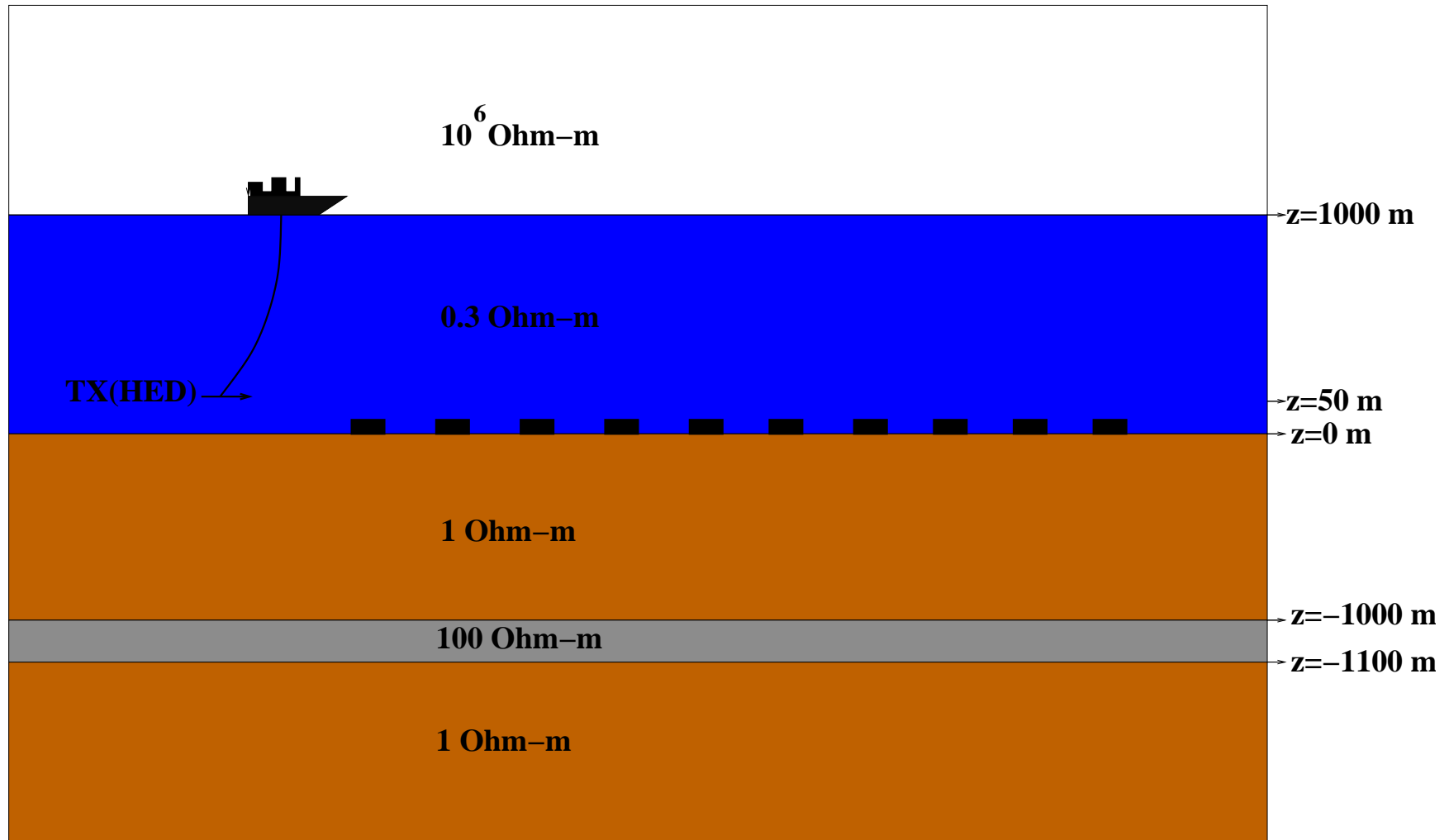
RESULTS: 2D MARINE CSEM

NO OIL



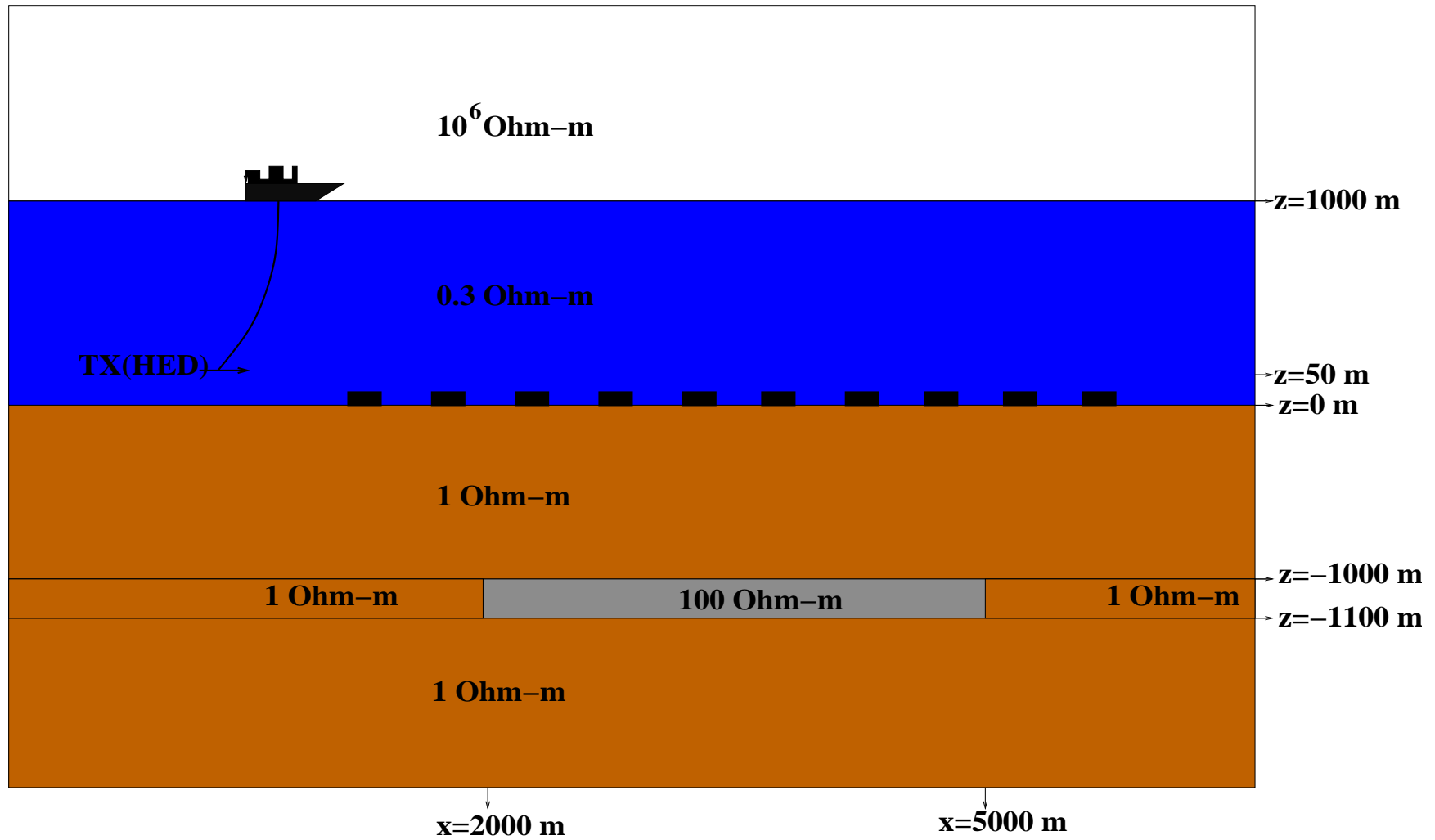
RESULTS: 2D MARINE CSEM

INFINITE LAYER OF OIL



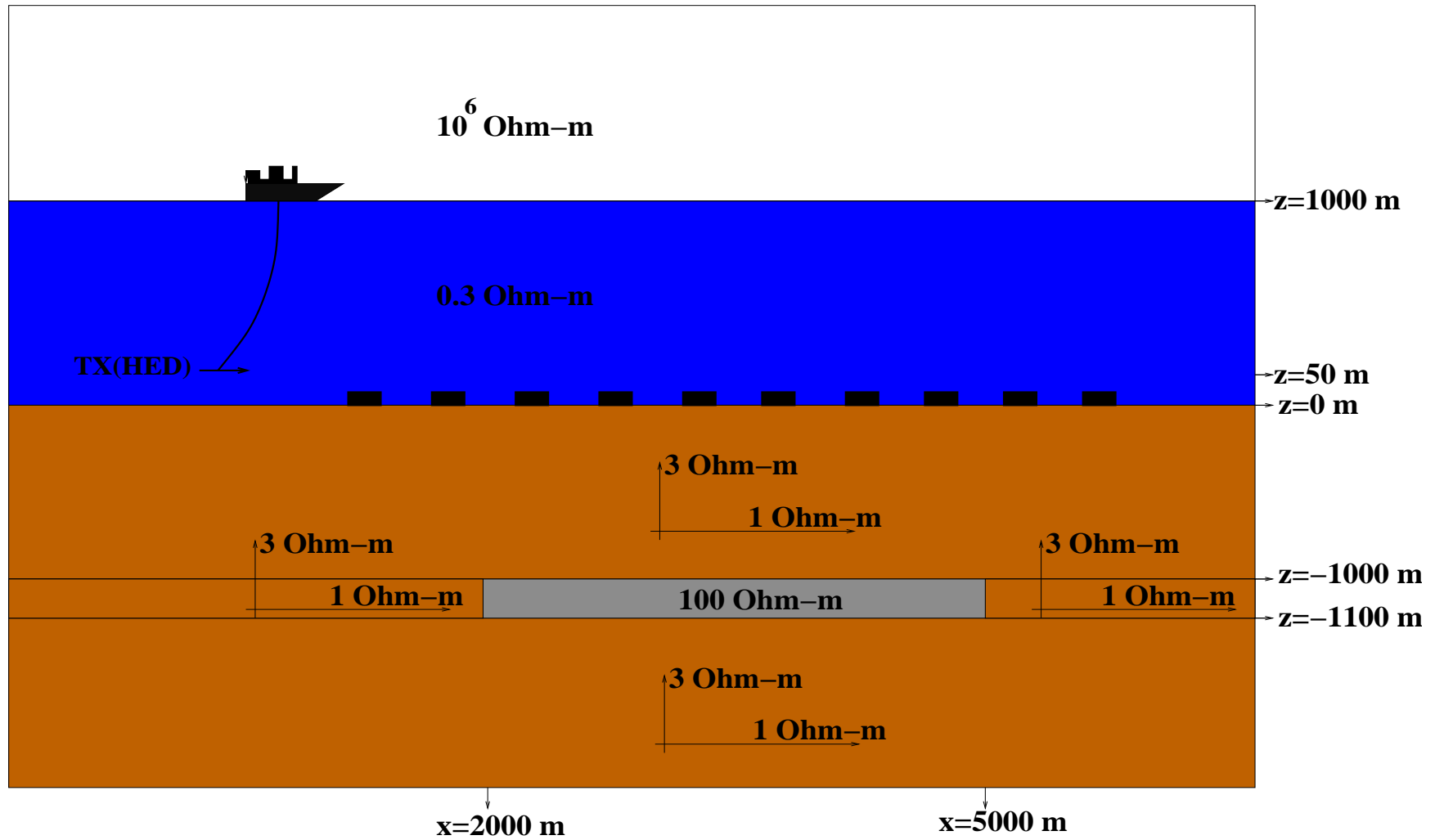
RESULTS: 2D MARINE CSEM

FINITE LAYER OF OIL



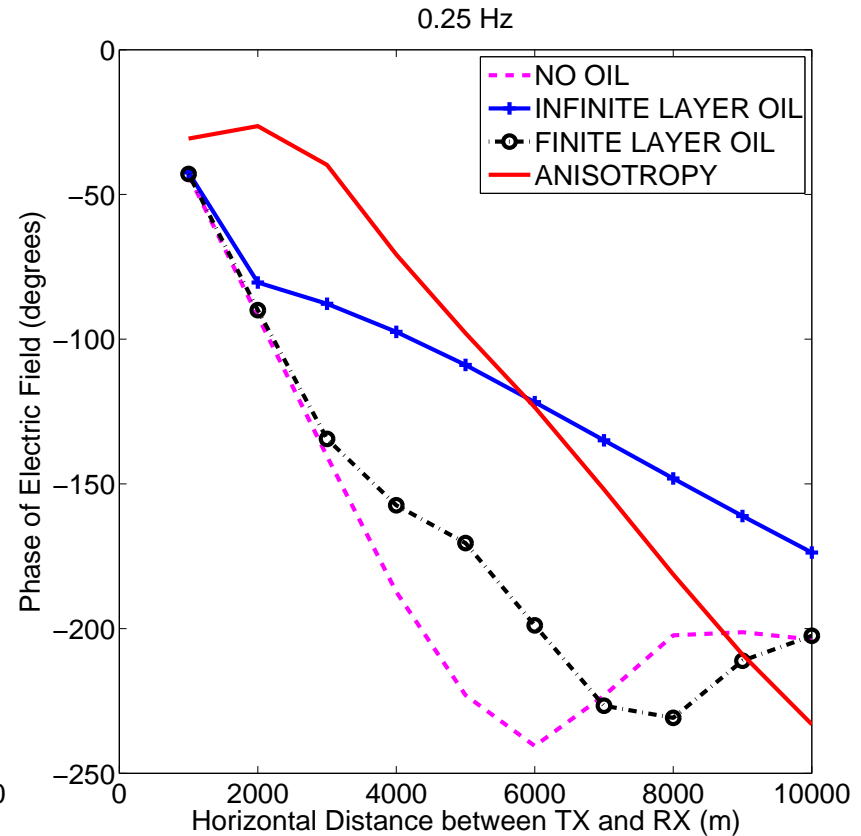
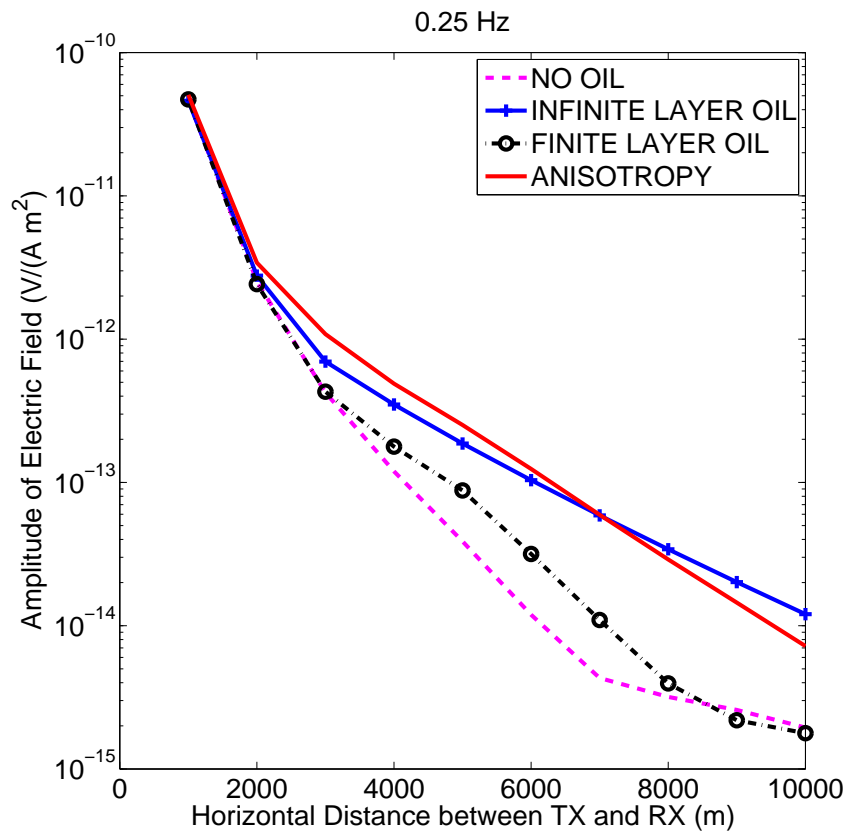
RESULTS: 2D MARINE CSEM

FINITE LAYER OF OIL + ANISOTROPY



RESULTS: 2D MARINE CSEM

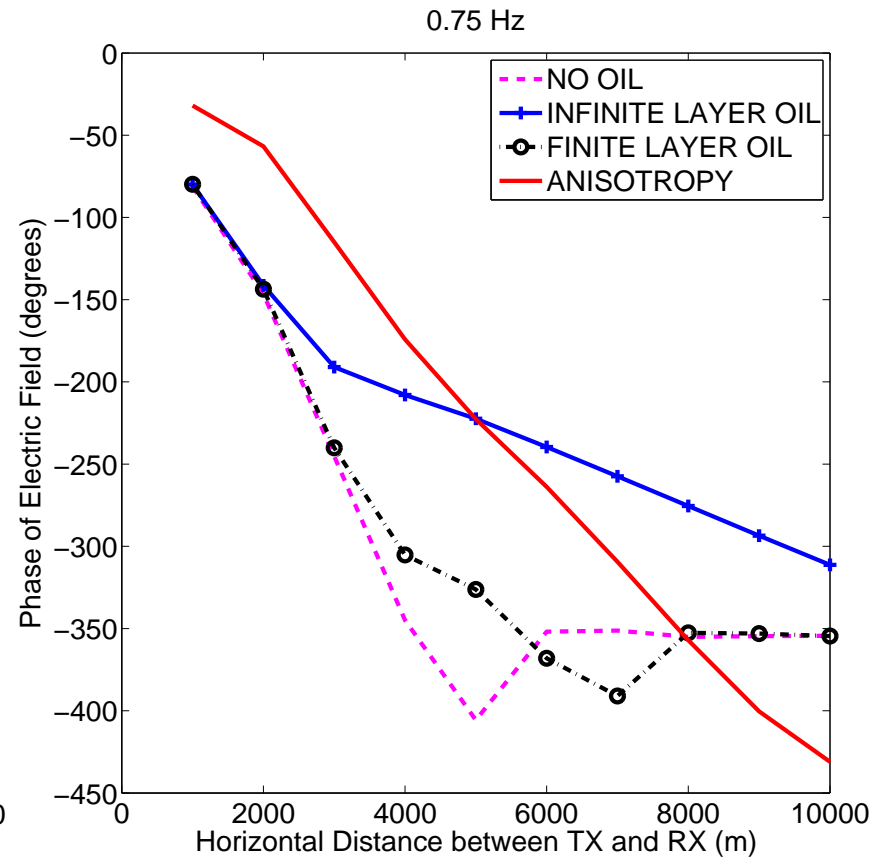
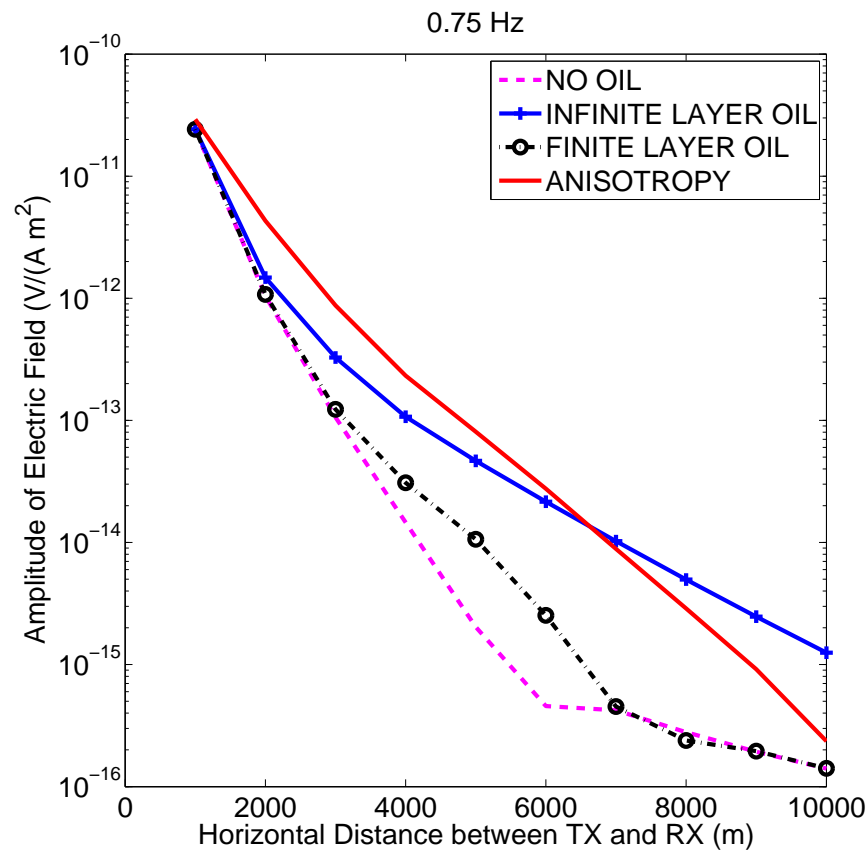
Comparison — 0.25 Hz —



The finite layer of oil is clearly identified, and it is different from the solution for the infinite layer of oil. To consider anisotropy is essential.

RESULTS: 2D MARINE CSEM

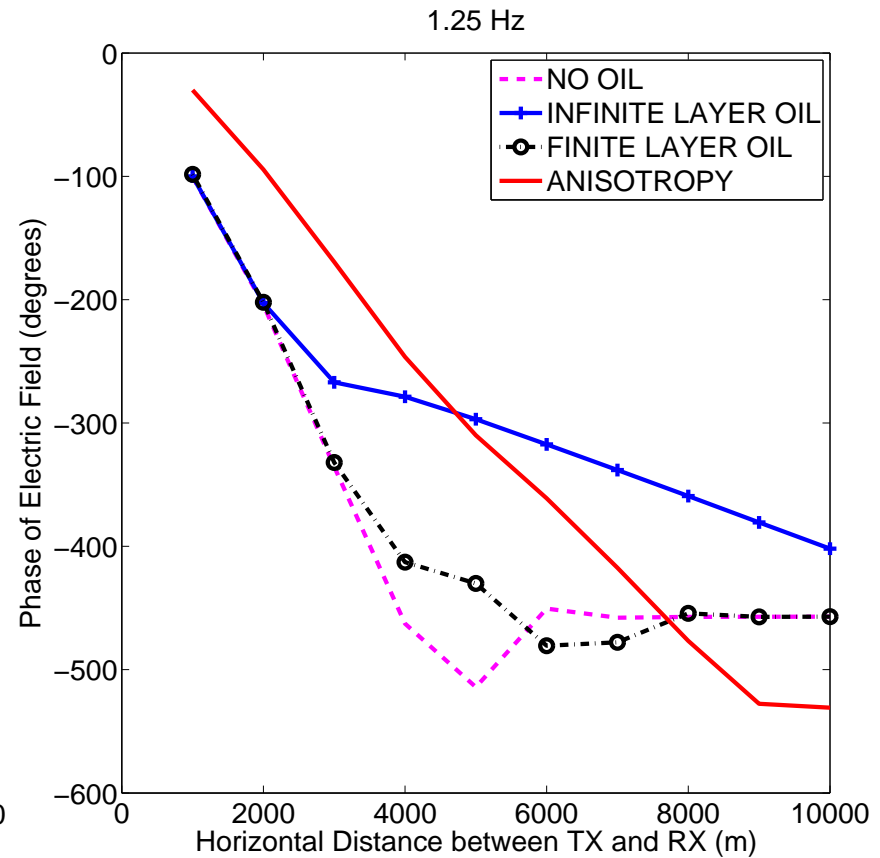
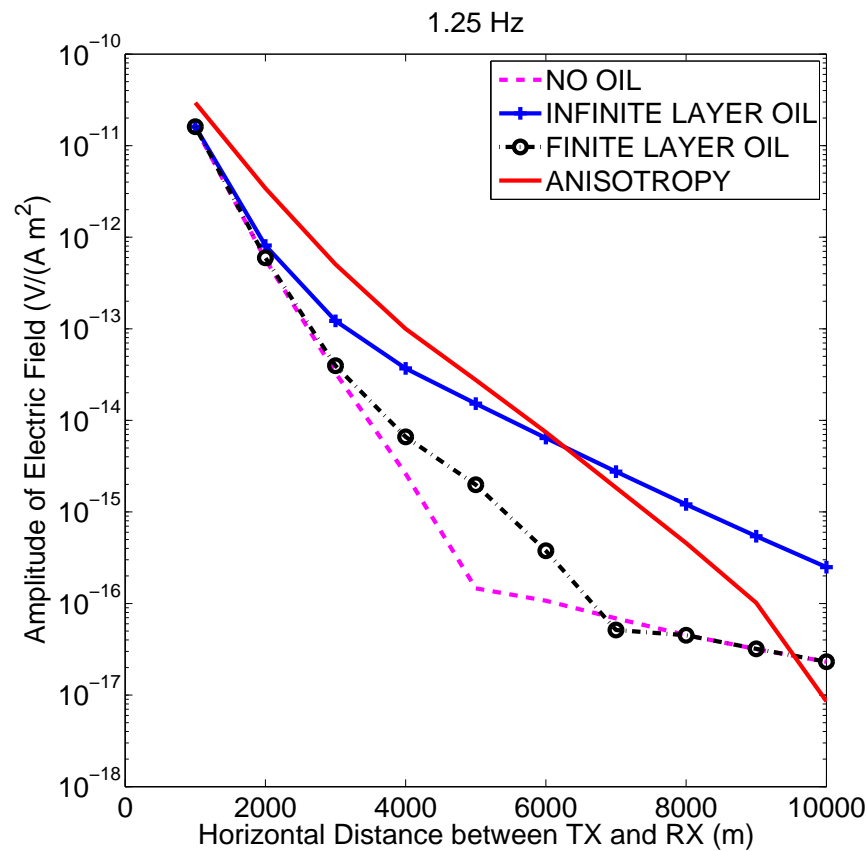
Comparison — 0.75 Hz —



As we increase the frequency, the effect of oil becomes more localized.

RESULTS: 2D MARINE CSEM

Comparison — 1.25 Hz —



As we increase the frequency, the effect of oil becomes more localized.

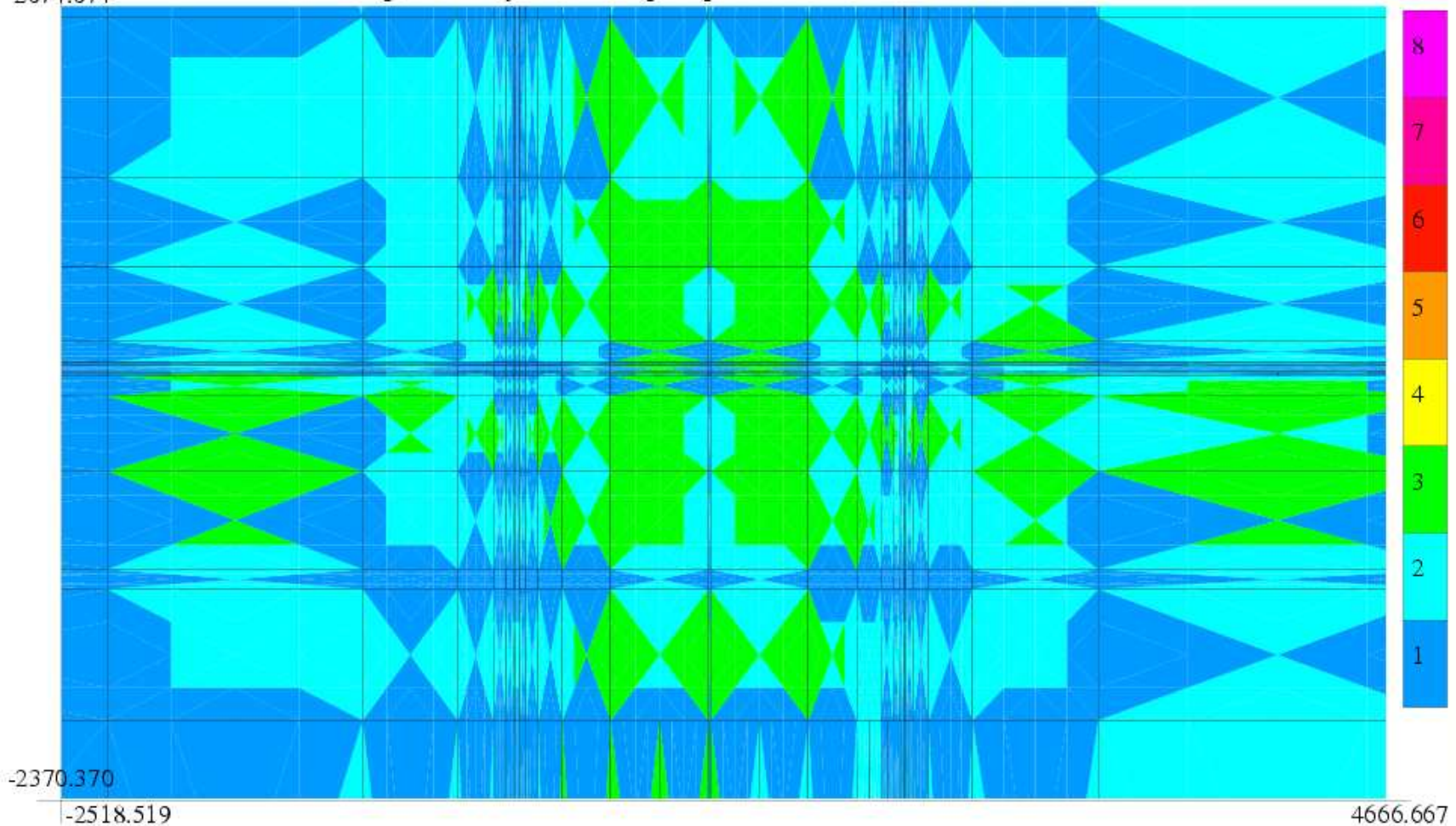
RESULTS: 2D MARINE CSEM

0.75 Hz (FINITE LAYER OF OIL)

TX: x = 0 m ; RX: x = 2000 m.

2Dhp90: A Fully automatic hp-adaptive Finite Element code

2074.074



-2370.370

-2518.519

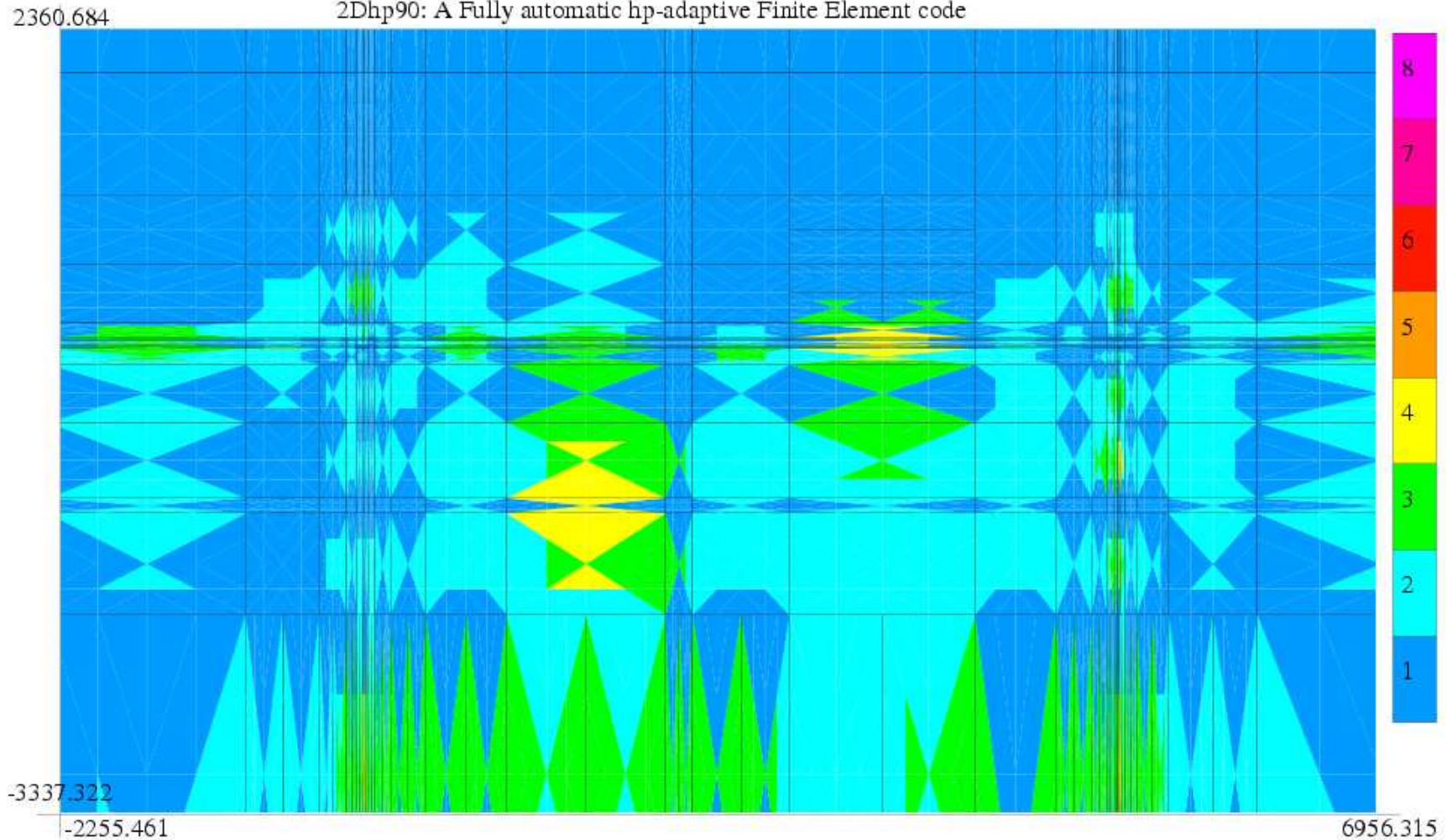
4666.667

RESULTS: 2D MARINE CSEM

0.75 Hz (FINITE LAYER OF OIL)

TX: x = 0 m ; RX: x = 5000 m.

2Dhp90: A Fully automatic hp-adaptive Finite Element code

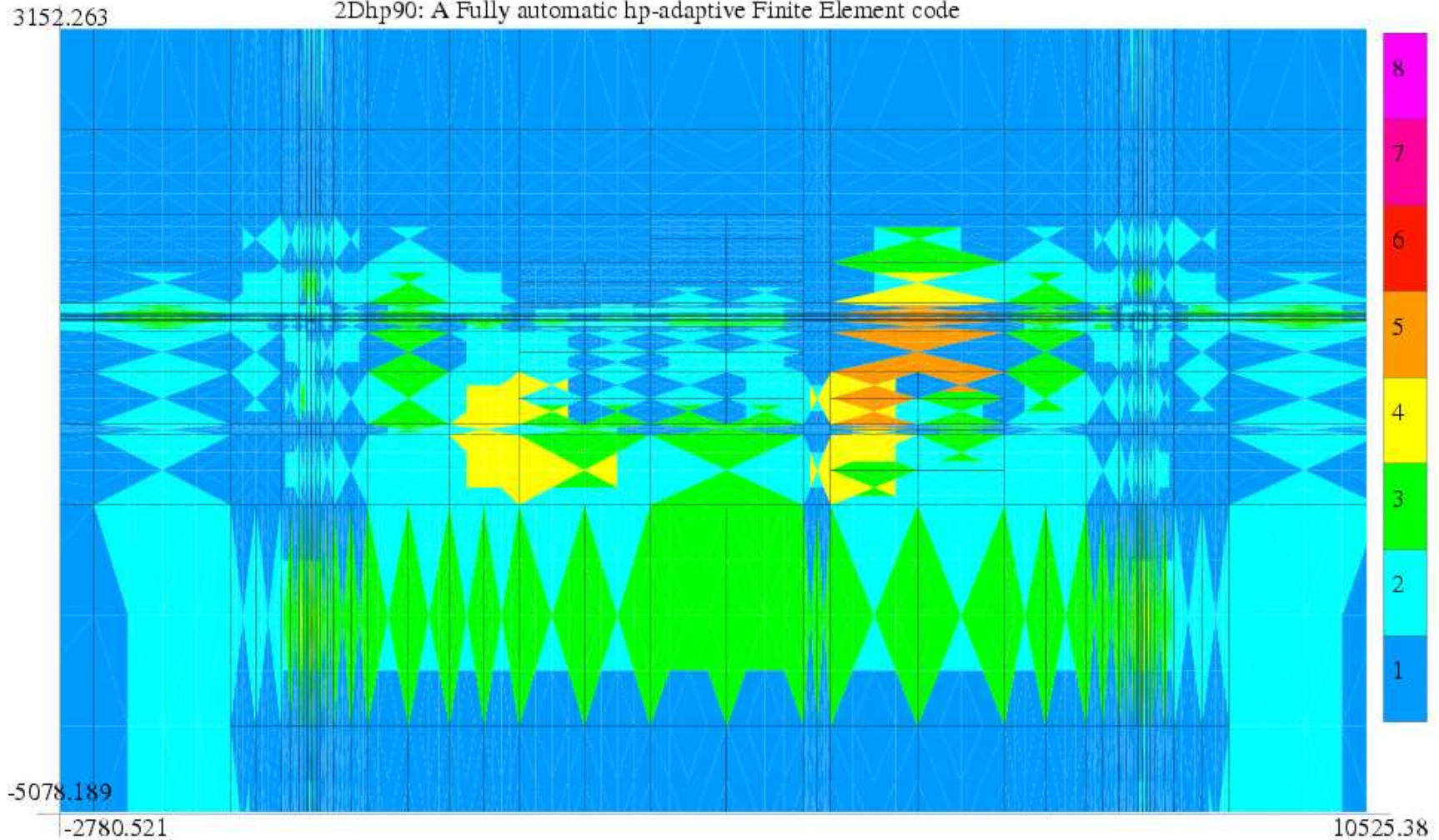


RESULTS: 2D MARINE CSEM

0.75 Hz (FINITE LAYER OF OIL)

TX: $x = 0$ m ; RX: $x = 8000$ m.

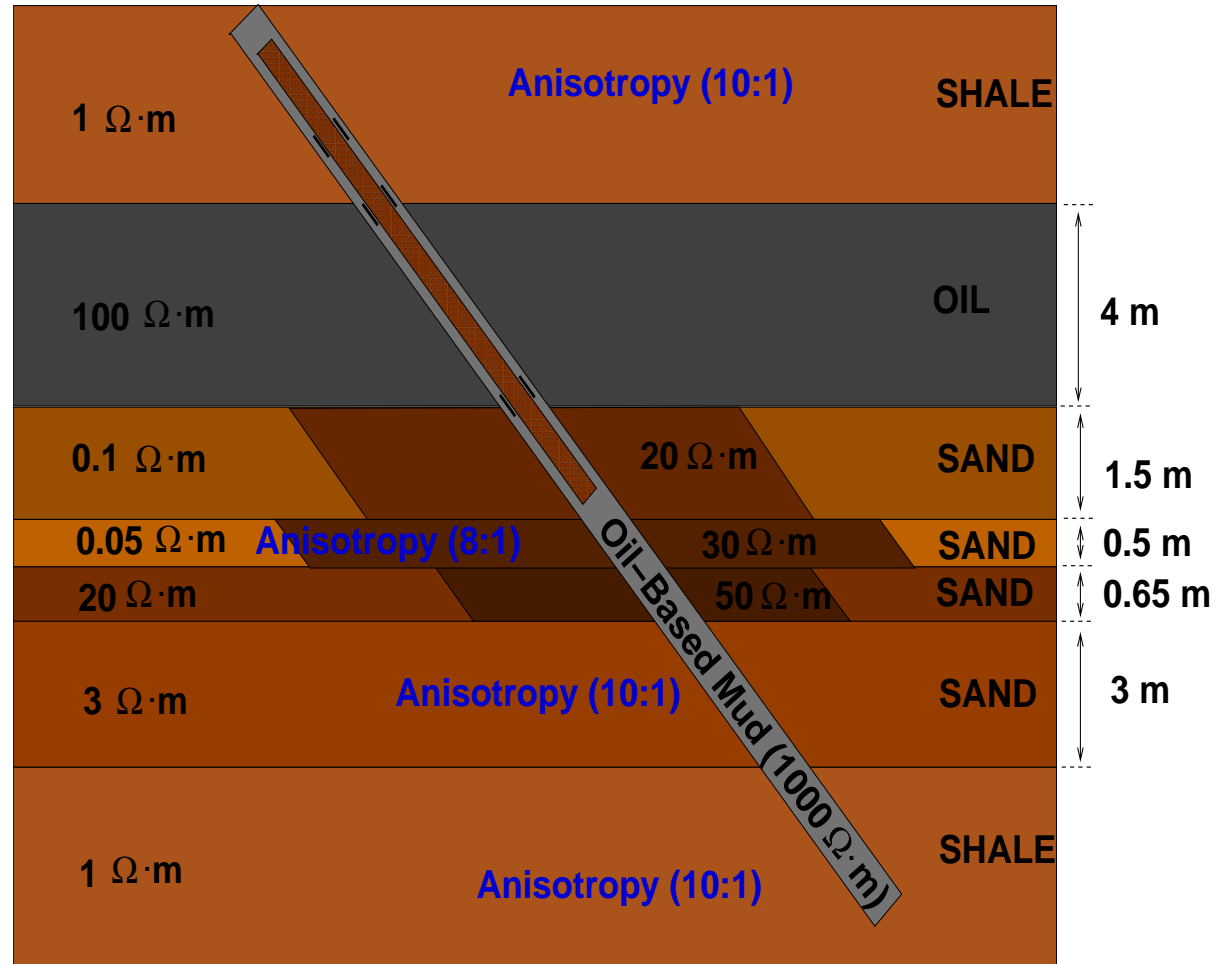
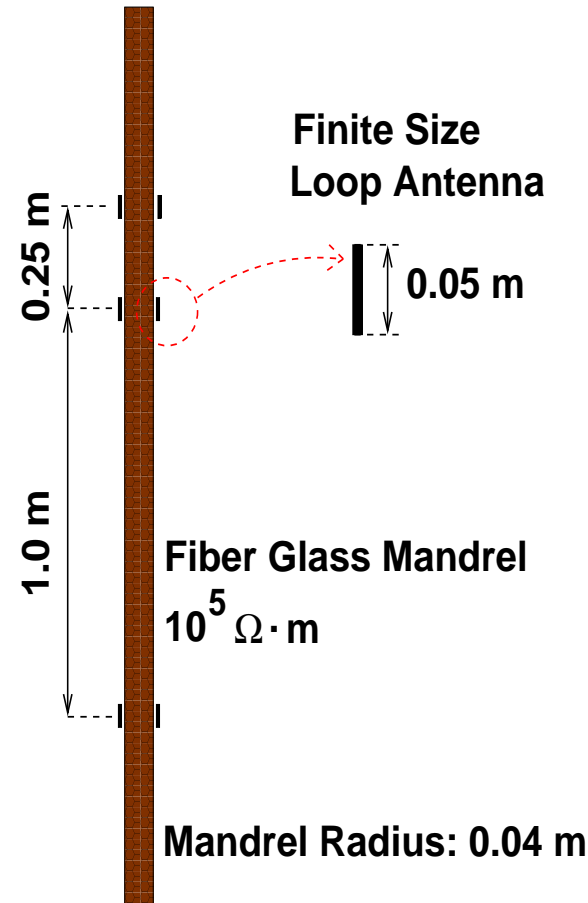
2Dhp90: A Fully automatic hp-adaptive Finite Element code



RESULTS: 3D RESISTIVITY LOGGING

Model Problem

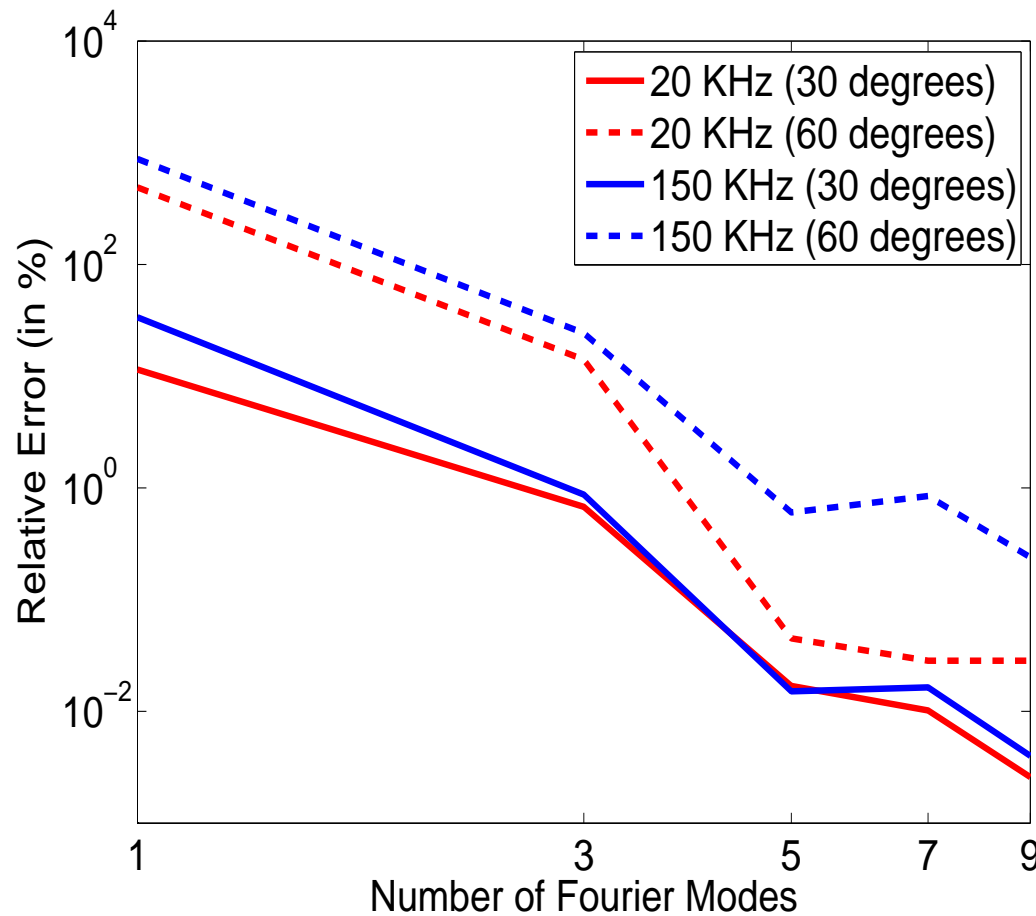
150 kHz (Wireline)



RESULTS: 3D RESISTIVITY LOGGING

Verification

Logging Instrument in a Homogeneous Formation

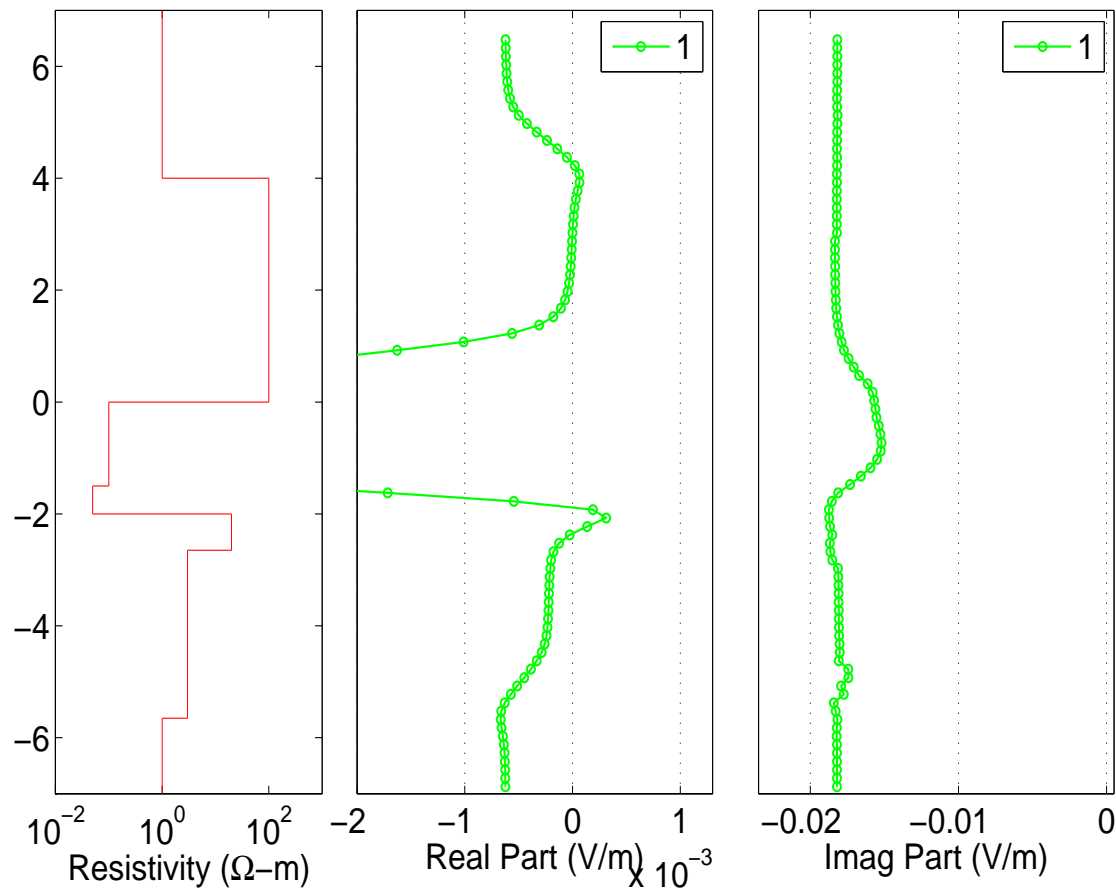


RESULTS: 3D RESISTIVITY LOGGING

Verification

Logging Instrument in a Homogeneous Formation

Wireline, 150 Khz

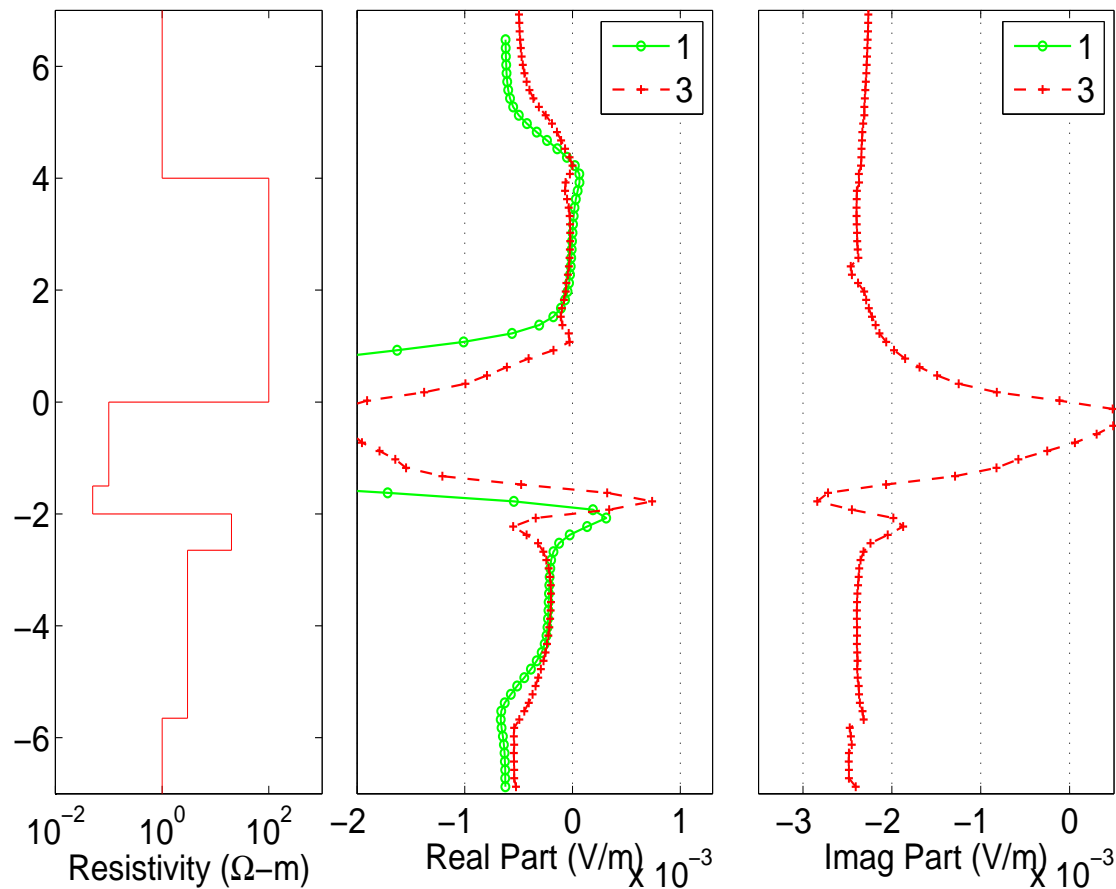


RESULTS: 3D RESISTIVITY LOGGING

Verification

Logging Instrument in a Homogeneous Formation

Wireline, 150 Khz

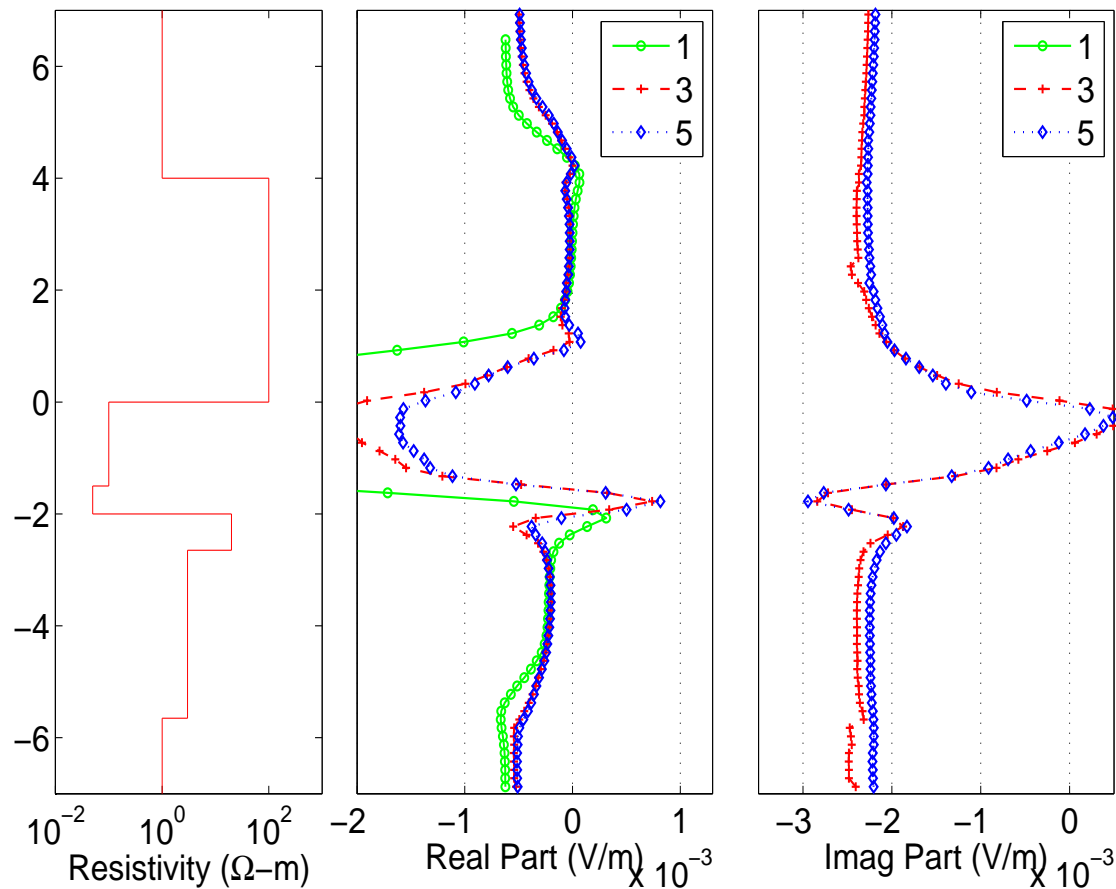


RESULTS: 3D RESISTIVITY LOGGING

Verification

Logging Instrument in a Homogeneous Formation

Wireline, 150 Khz

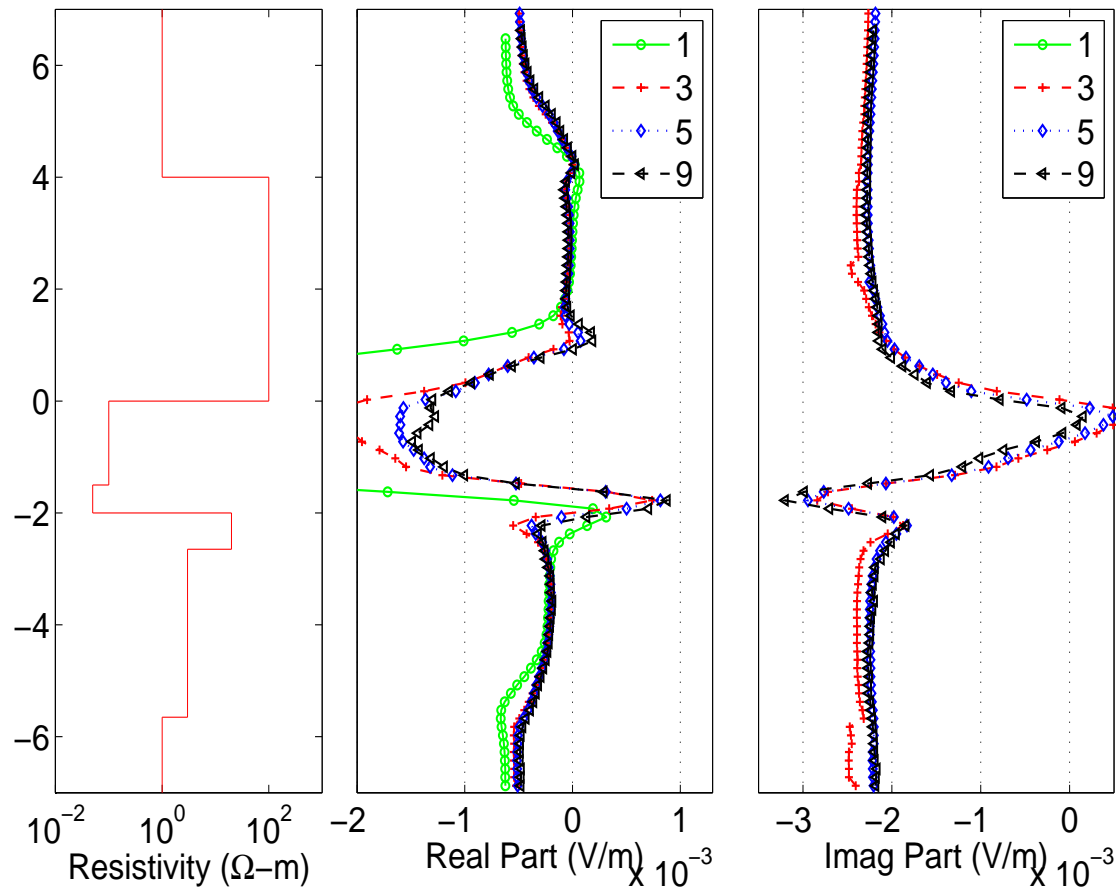


RESULTS: 3D RESISTIVITY LOGGING

Verification

Logging Instrument in a Homogeneous Formation

Wireline, 150 Khz

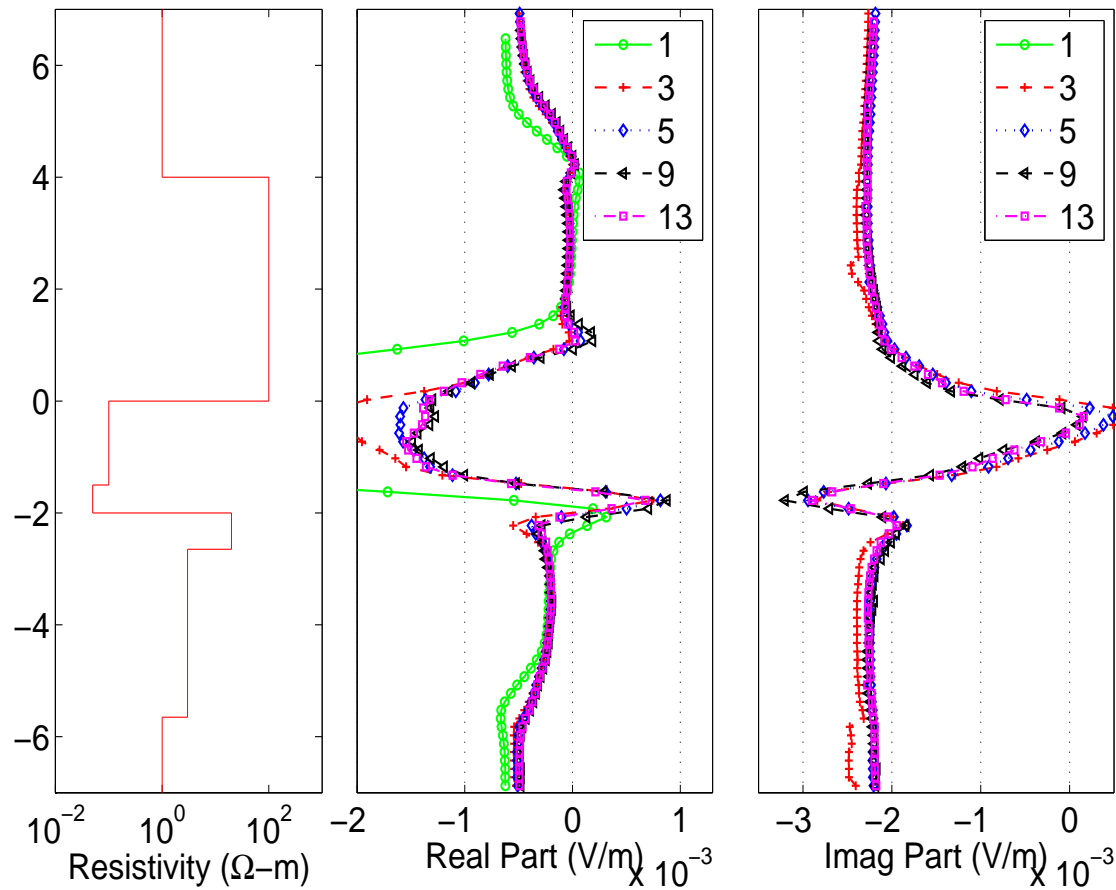


RESULTS: 3D RESISTIVITY LOGGING

Verification

Logging Instrument in a Homogeneous Formation

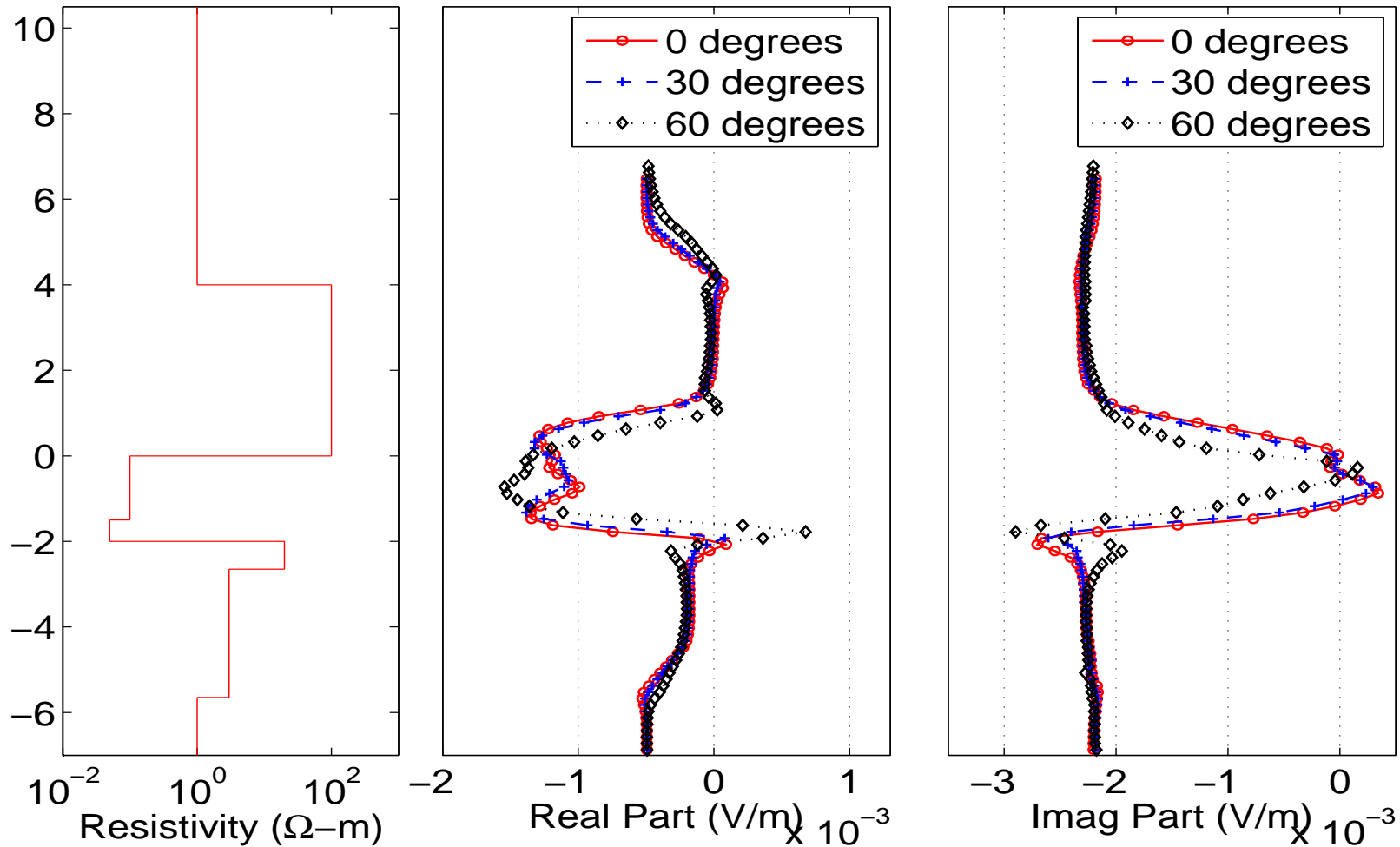
Wireline, 150 Khz



RESULTS: 3D RESISTIVITY LOGGING

Dip Angle

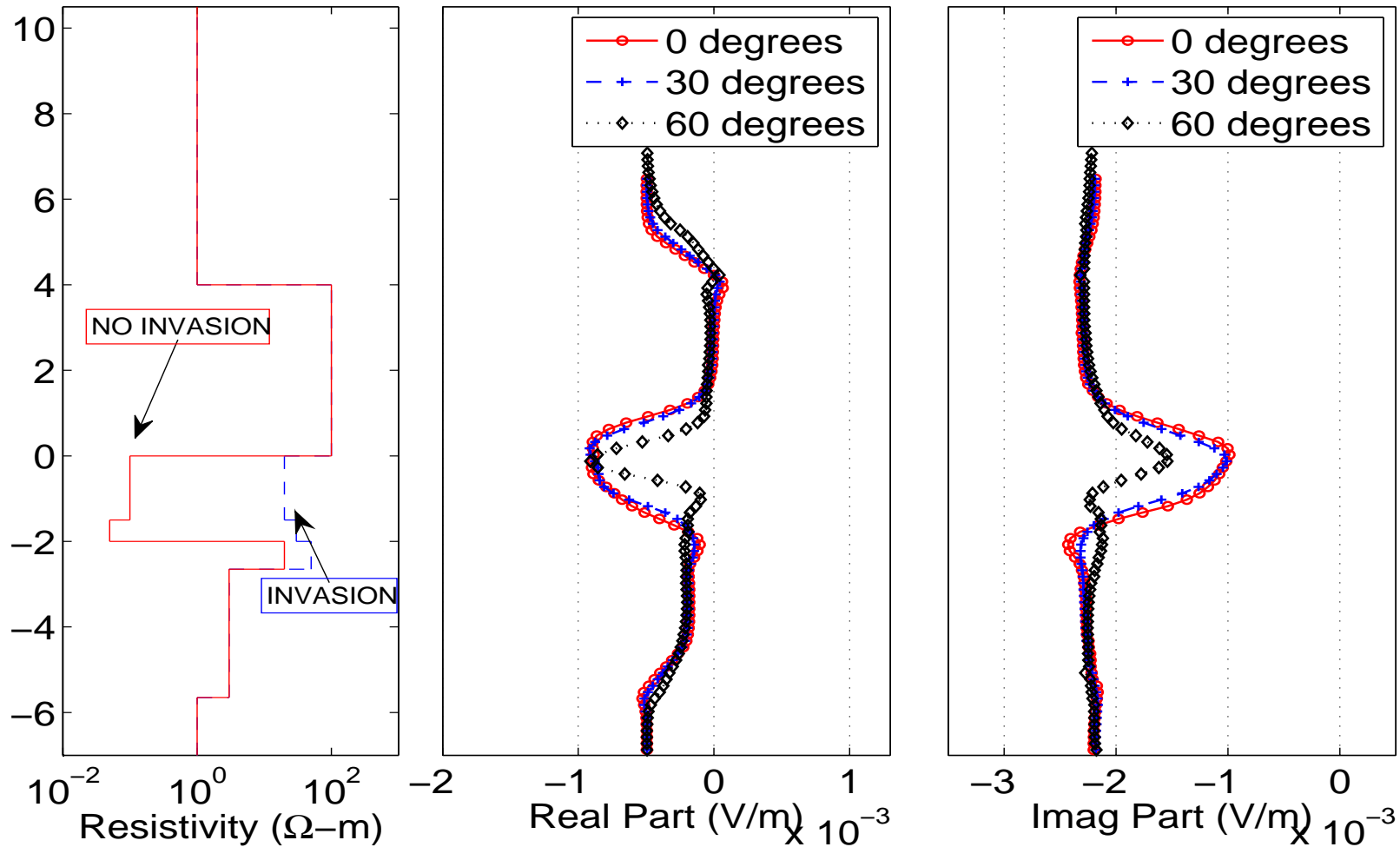
Wireline, 150 Khz



RESULTS: 3D RESISTIVITY LOGGING

Dip Angle + Invasion

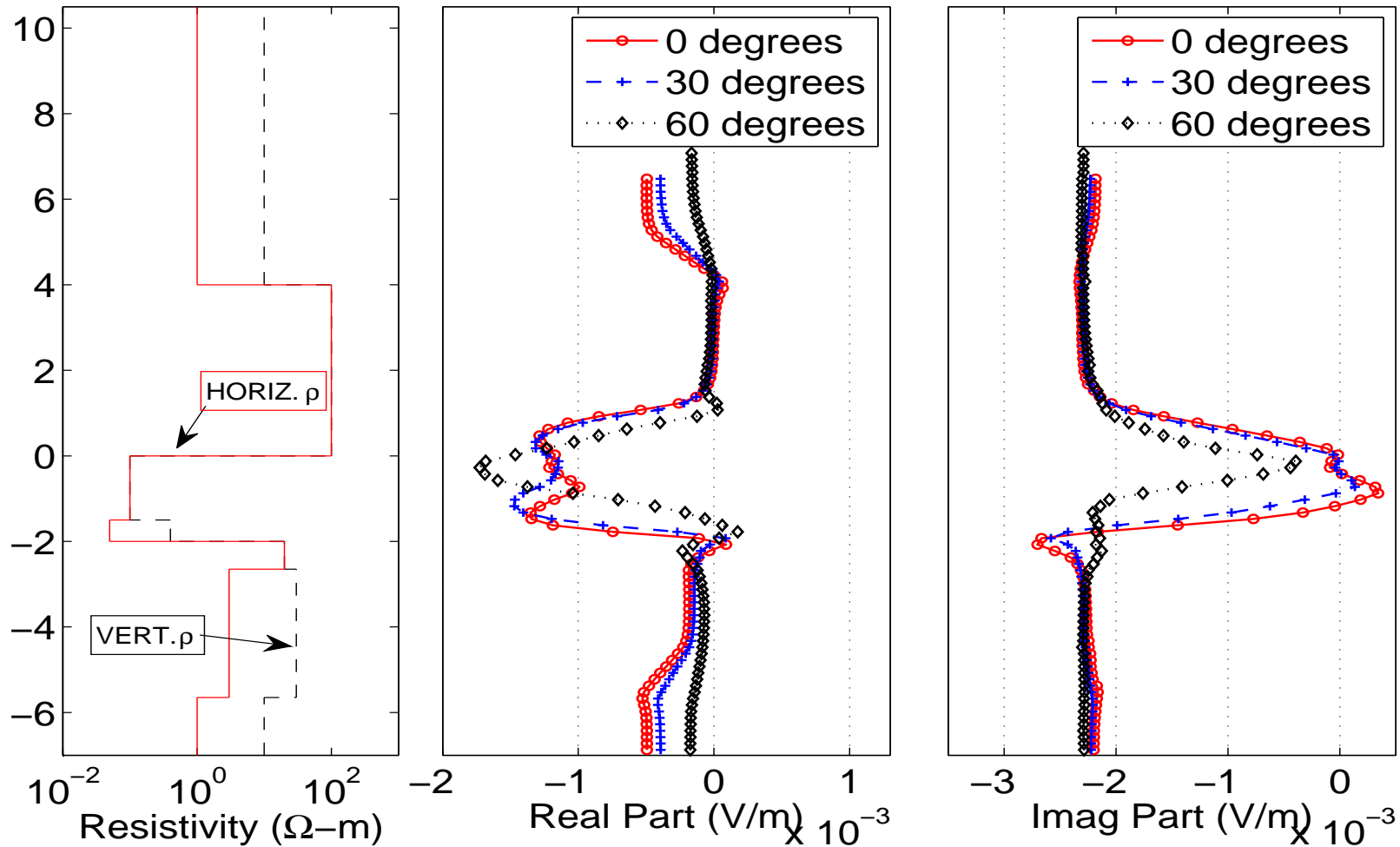
Wireline, 150 Khz



RESULTS: 3D RESISTIVITY LOGGING

Dip Angle + Anisotropy

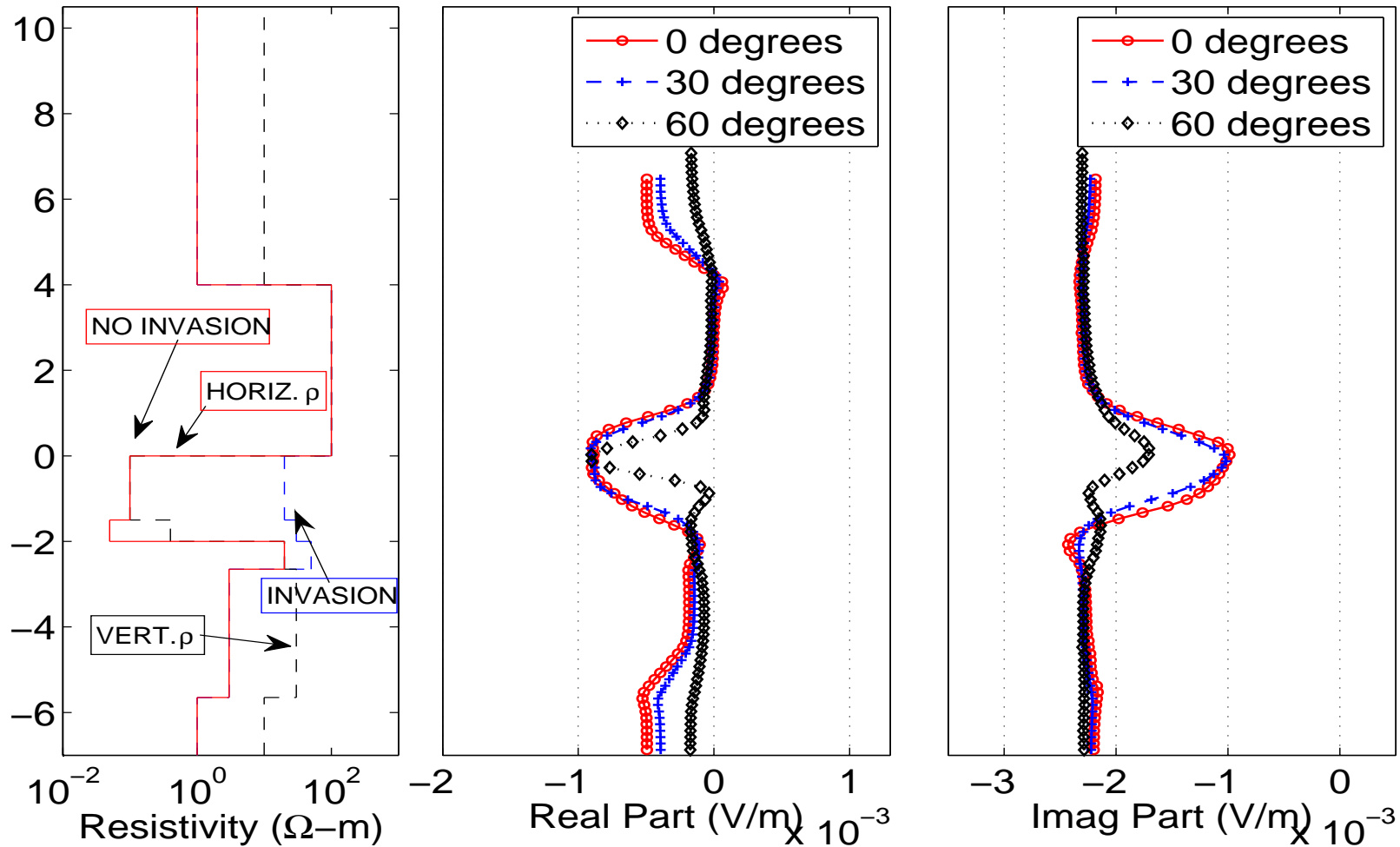
Wireline, 150 Khz



RESULTS: 3D RESISTIVITY LOGGING

Dip Angle + Invasion + Anisotropy

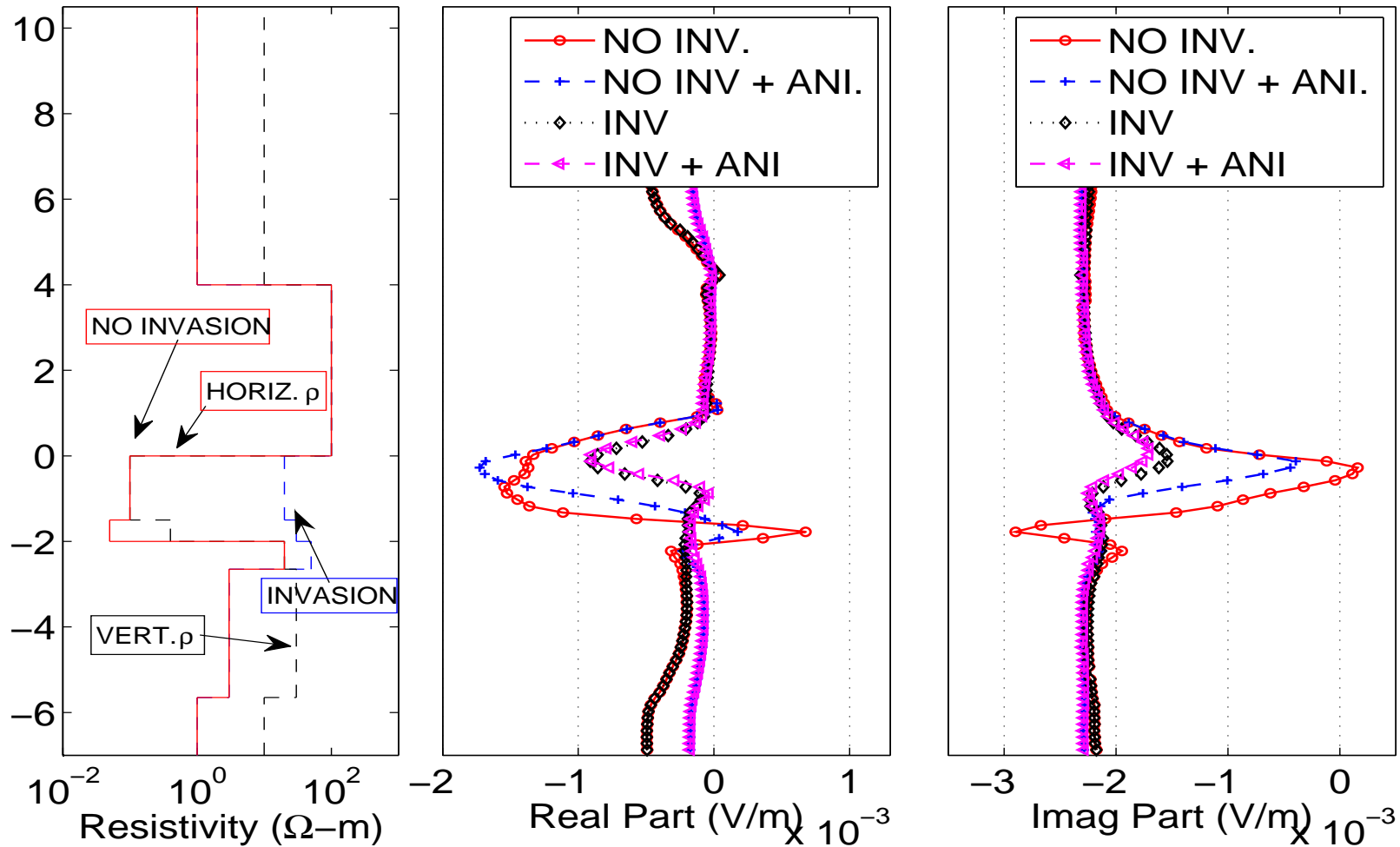
Wireline, 150 Khz



RESULTS: 3D RESISTIVITY LOGGING

60-Degree Deviated Well

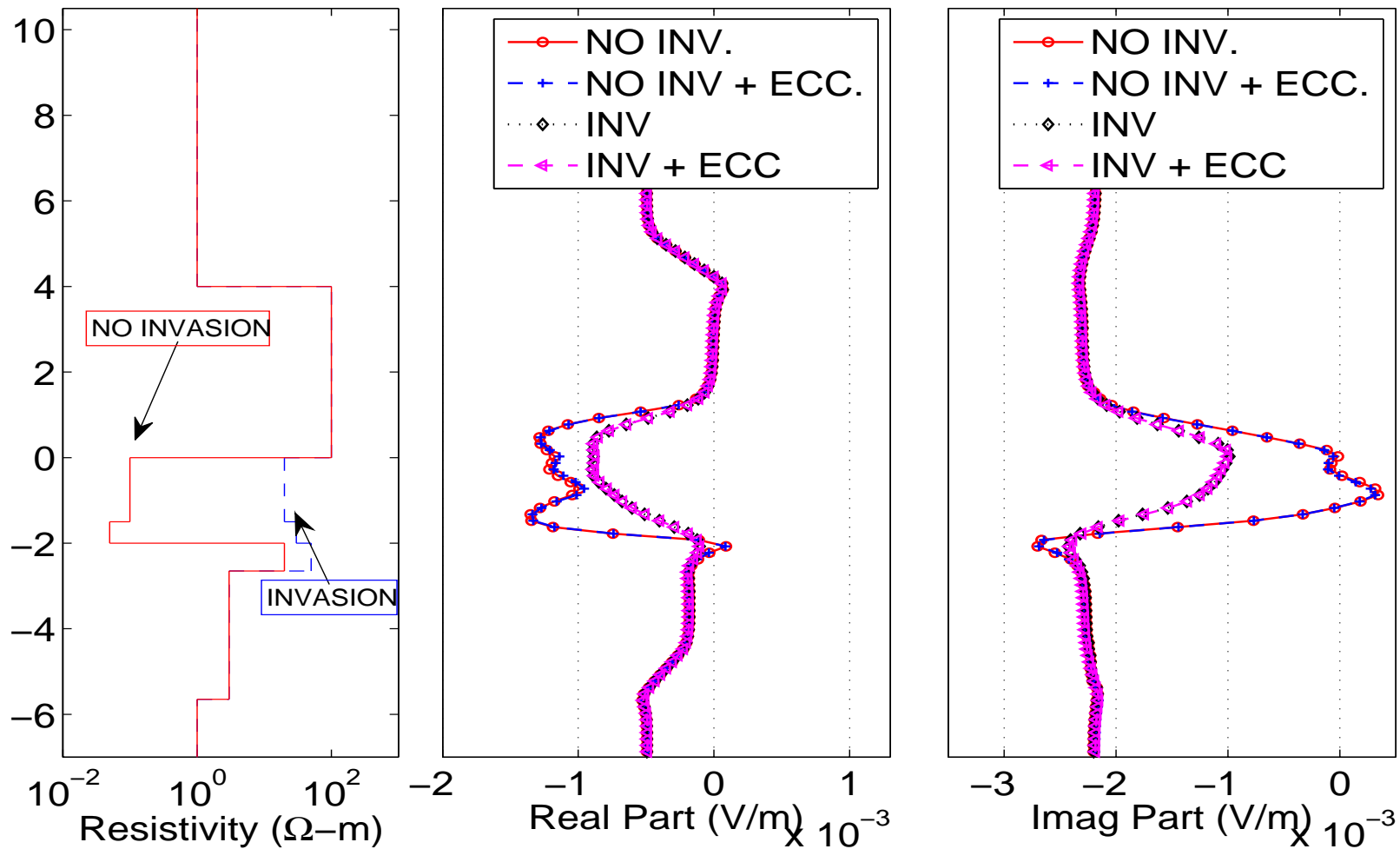
Wireline, 150 Khz



RESULTS: 3D RESISTIVITY LOGGING

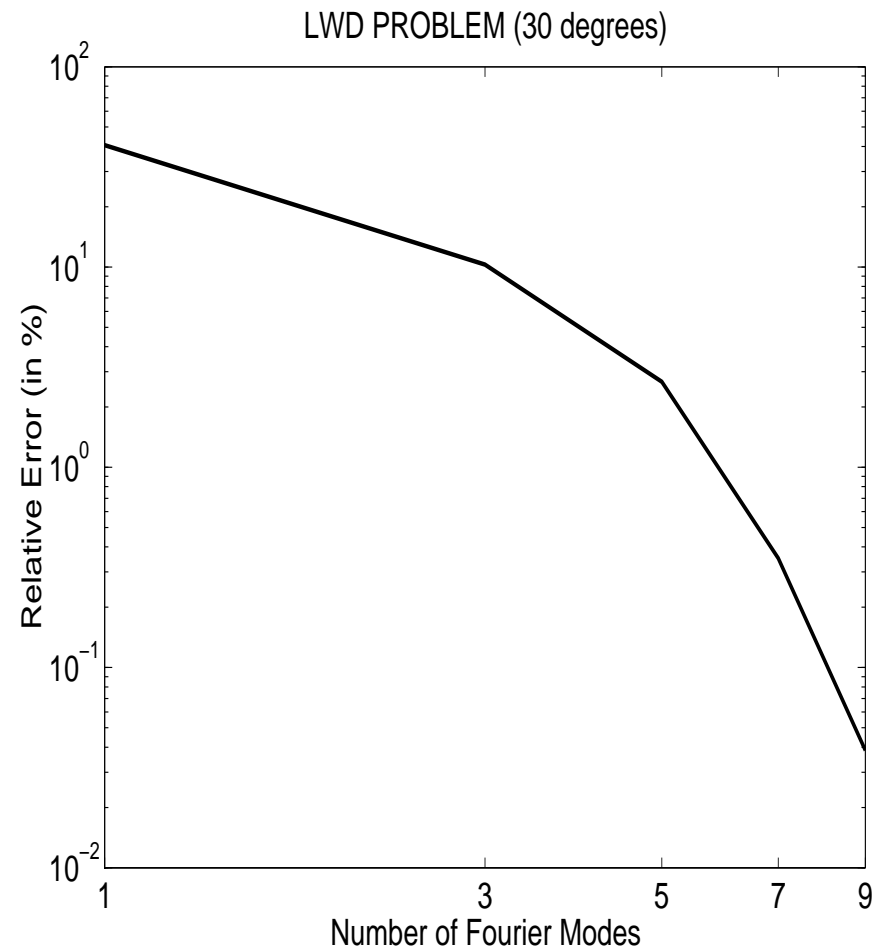
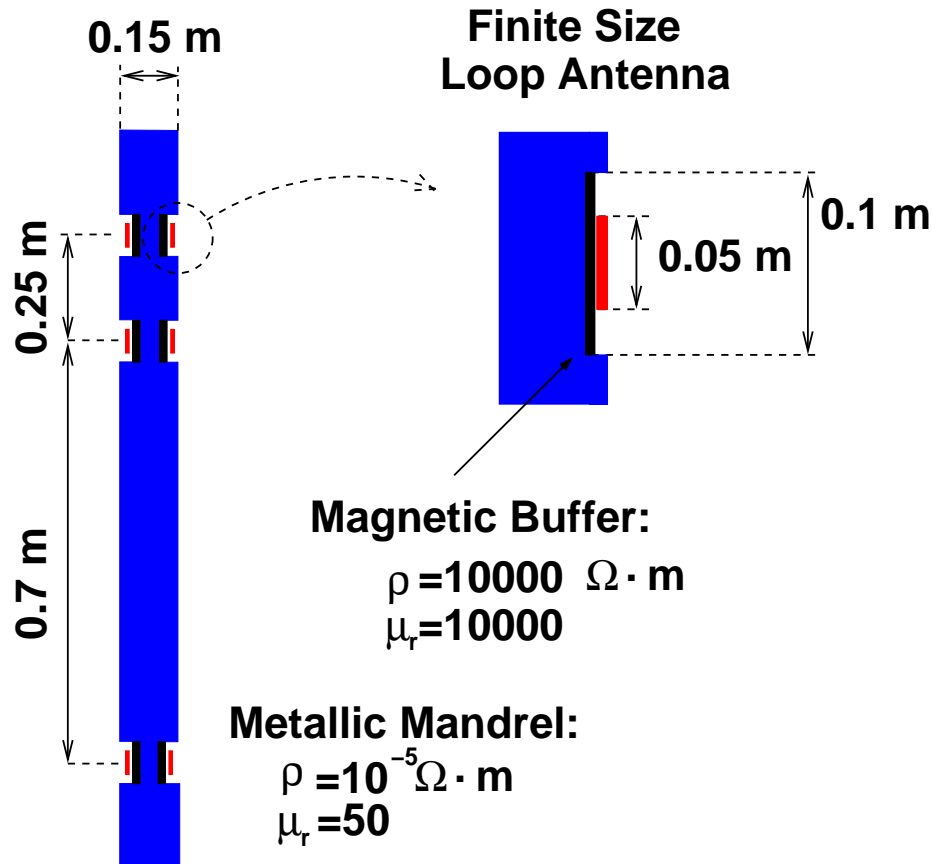
Vertical Well with 0.03 m Eccentricity

Wireline, 150 Khz

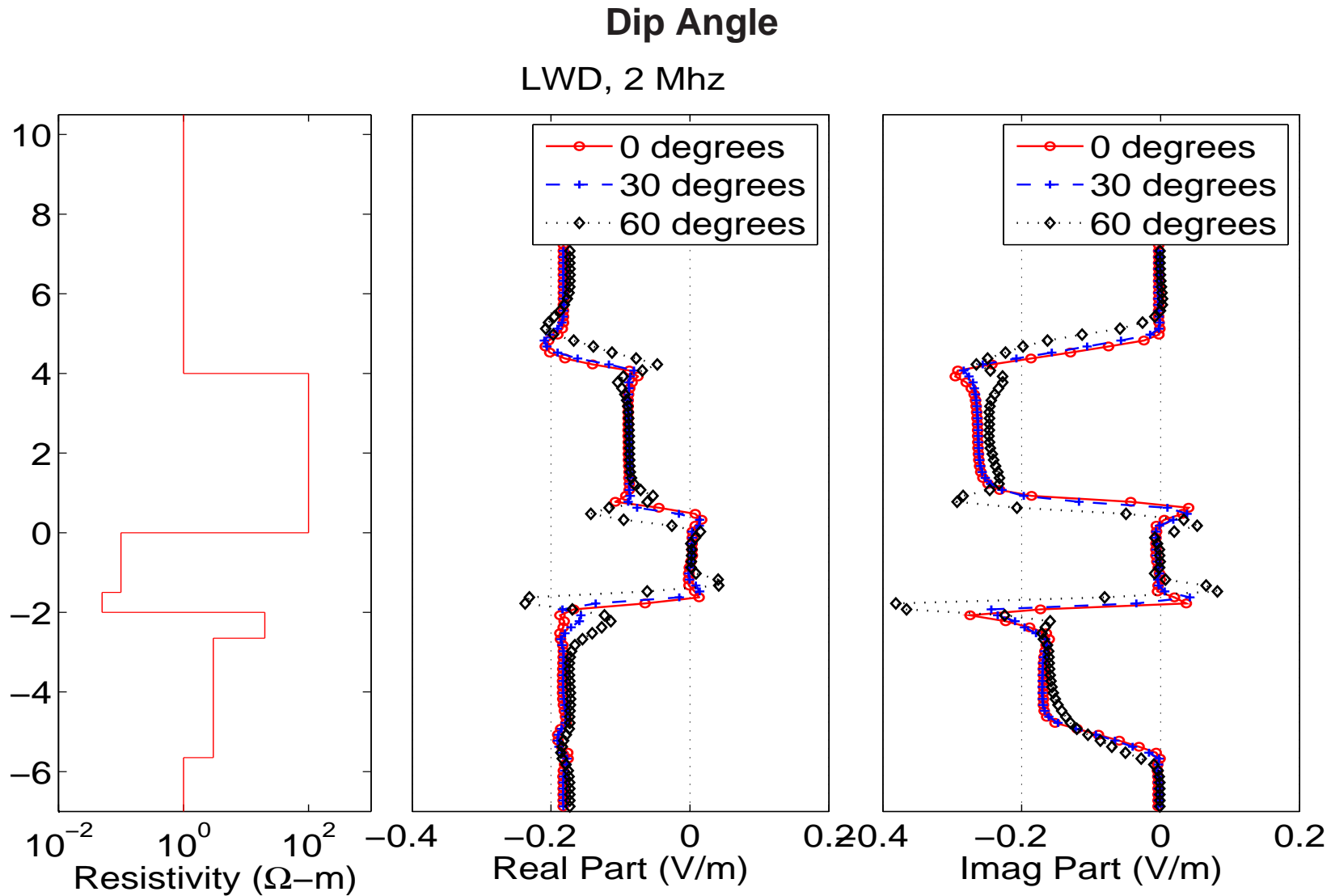


RESULTS: 3D RESISTIVITY LOGGING

Model Problem and Verification



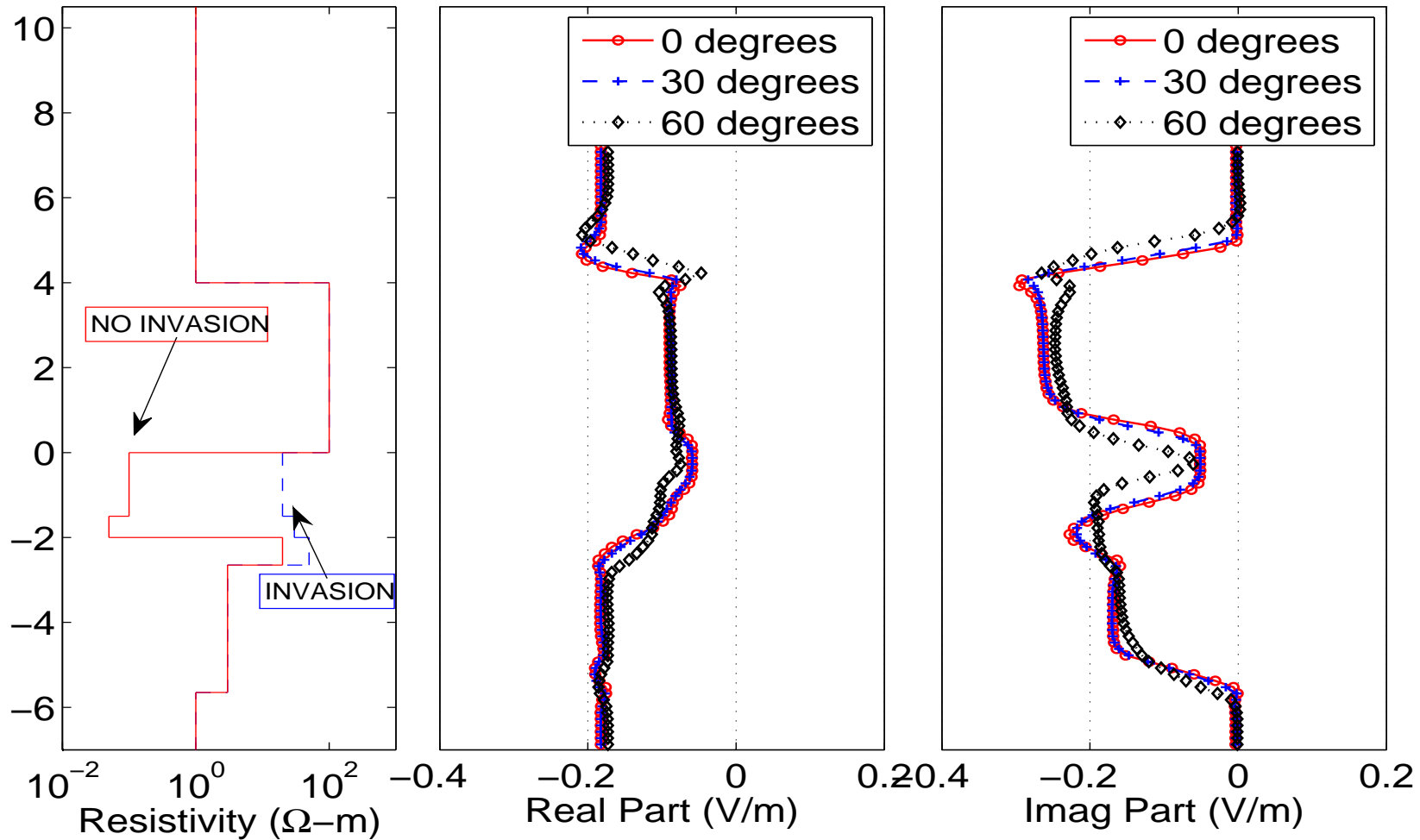
RESULTS: 3D RESISTIVITY LOGGING



RESULTS: 3D RESISTIVITY LOGGING

Dip Angle + Invasion

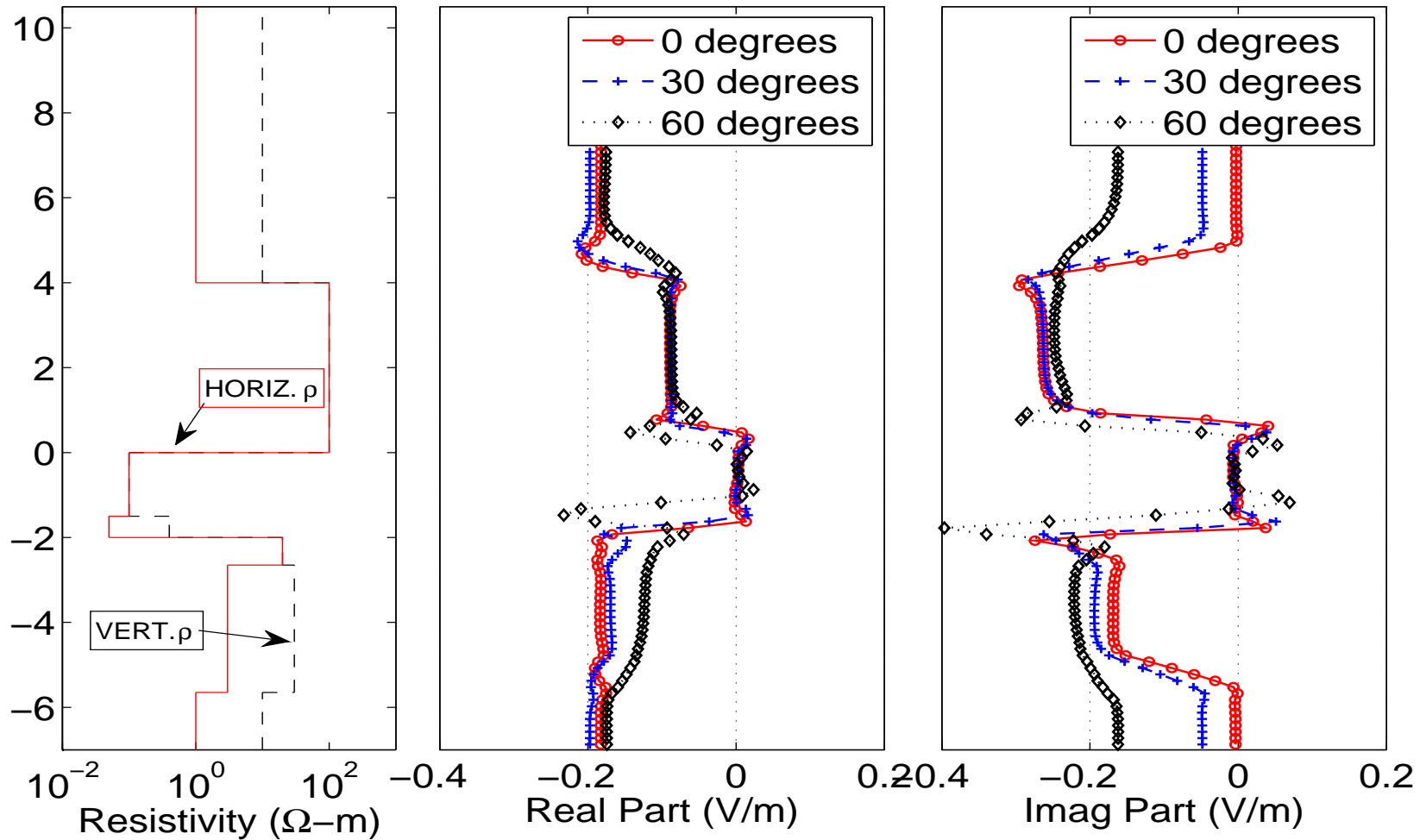
LWD, 2 Mhz



RESULTS: 3D RESISTIVITY LOGGING

Dip Angle + Anisotropy

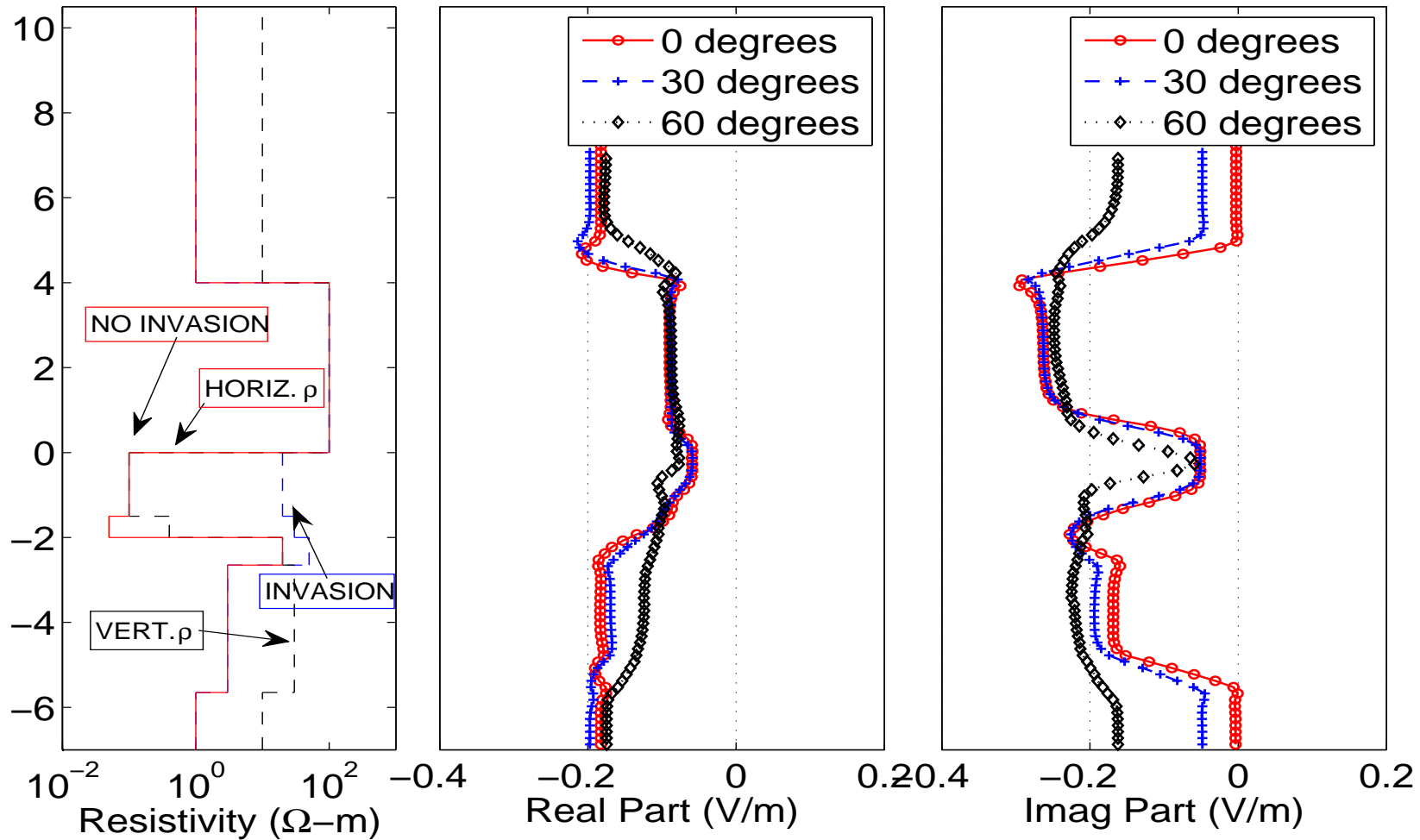
LWD, 2 Mhz



RESULTS: 3D RESISTIVITY LOGGING

Dip Angle + Invasion + Anisotropy

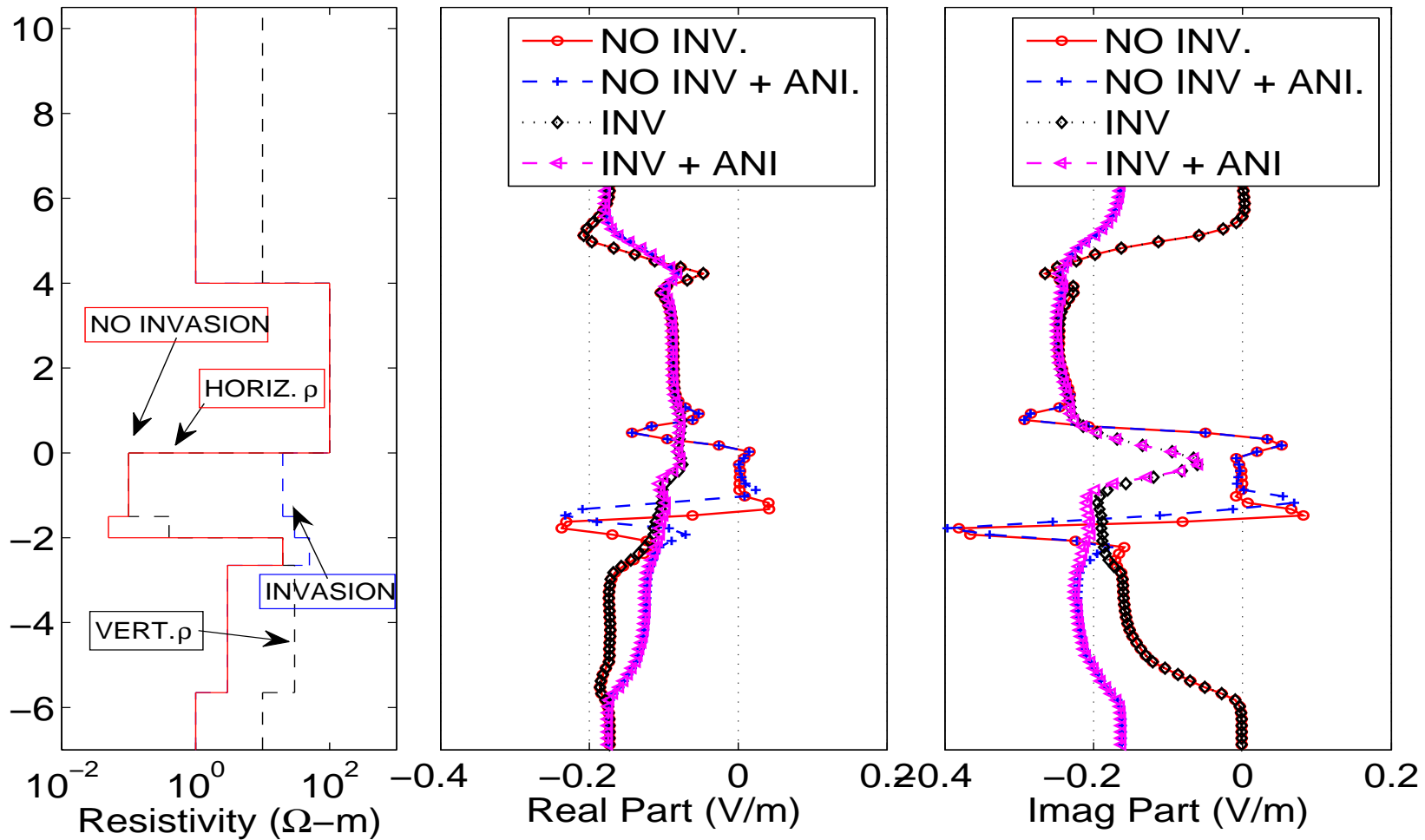
LWD, 2 Mhz



RESULTS: 3D RESISTIVITY LOGGING

60-Degree Deviated Well

LWD, 2 Mhz



CONCLUSIONS AND FUTURE WORK

- **A Fourier-Finite-Element method provides a suitable formulation for simulation of resistivity geophysical applications.**
- **Goal-oriented refinements are essential in marine CSEM geophysical applications due to the dissipative nature of the earth.**
- **A parallel implementation based on a shared domain-decomposition is simple and provides additional performance for a moderate number of processors.**
- **We are developing a multiphysics framework for the joint-inversion of multiphysics measurements.**
- **We are looking for Ph.D. students and postdoctoral fellows to further develop this software and work on the joint-inversion of multiphysics measurements.**

Basque Center for Applied Mathematics (BCAM)